

# Rules for the Classification of Offshore Units Operating in the Caspian Sea and Similar Areas

*Effective from 1 January 2023*

## Part C

Machinery, Systems and Fire Protection



# GENERAL CONDITIONS

## Definitions:

"Administration" means the Government of the State whose flag the Ship is entitled to fly or under whose authority the Ship is authorised to operate in the specific case.

"IACS" means the International Association of Classification Societies.

"Interested Party" means the party, other than the Society, having an interest in or responsibility for the Ship, product, plant or system subject to classification or certification (such as the owner of the Ship and his representatives, the ship builder, the engine builder or the supplier of parts to be tested) who requests the Services or on whose behalf the Services are requested.

"Owner" means the registered owner, the ship owner, the manager or any other party with the responsibility, legally or contractually, to keep the ship seaworthy or in service, having particular regard to the provisions relating to the maintenance of class laid down in Part A, Chapter 2 of the Rules for the Classification of Ships or in the corresponding rules indicated in the specific Rules.

"Rules" in these General Conditions means the documents below issued by the Society:

- (i) Rules for the Classification of Ships or other special units;
- (ii) Complementary Rules containing the requirements for product, plant, system and other certification or containing the requirements for the assignment of additional class notations;
- (iii) Rules for the application of statutory rules, containing the rules to perform the duties delegated by Administrations;
- (iv) Guides to carry out particular activities connected with Services;
- (v) Any other technical document, as for example rule variations or interpretations.

"Services" means the activities described in Article 1 below, rendered by the Society upon request made by or on behalf of the Interested Party.

"Ship" means ships, boats, craft and other special units, as for example offshore structures, floating units and underwater craft.

"Society" or "TASNEEF" means Tasneef and/or all the companies in the Tasneef Group which provide the Services.

"Surveyor" means technical staff acting on behalf of the Society in performing the Services.

## Article 1

1.1. The purpose of the Society is, among others, the classification and certification of ships and the certification of their parts and components. In particular, the Society:

- (i) sets forth and develops Rules;
- (ii) publishes the Register of Ships;
- (iii) issues certificates, statements and reports based on its survey activities.

1.2. The Society also takes part in the implementation of national and international rules and standards as delegated by various Governments.

1.3. The Society carries out technical assistance activities on request and provides special services outside the scope of classification, which are regulated by these general conditions, unless expressly excluded in the particular contract.

## Article 2

2.1. The Rules developed by the Society reflect the level of its technical knowledge at the time they are published. Therefore, the Society, although committed also through its research and development services to continuous updating of the Rules, does not guarantee the Rules meet state-of-the-art science and technology at the time of publication or that they meet the Society's or others' subsequent technical developments.

2.2. The Interested Party is required to know the Rules on the basis of which the Services are provided. With particular reference to Classification Services, special attention is to be given to the Rules concerning class suspension, withdrawal and reinstatement. In case of doubt or inaccuracy, the Interested Party is to promptly contact the Society for clarification.

The Rules for Classification of Ships are published on the Society's website: [www.tasneef.ae](http://www.tasneef.ae).

2.3. The Society exercises due care and skill:

- (i) in the selection of its Surveyors
- (ii) in the performance of its Services, taking into account the level of its technical knowledge at the time the Services are performed.

2.4. Surveys conducted by the Society include, but are not limited to, visual inspection and non-destructive testing. Unless otherwise required, surveys are conducted through sampling techniques and do not consist of comprehensive verification or monitoring of the Ship or of the items subject to certification. The surveys and checks made by the Society on board ship do not necessarily require the constant and continuous presence of the Surveyor. The Society may also commission laboratory testing, underwater inspection and other checks carried out by and under the responsibility of qualified service suppliers. Survey practices and procedures are selected by the Society based on its experience and knowledge and according to generally accepted technical standards in the sector.

## Article 3

3.1. The class assigned to a Ship, like the reports, statements, certificates or any other document or information issued by the Society, reflects the opinion of the Society concerning compliance, at the time the Service is provided, of the Ship or product subject to certification, with the applicable Rules (given the intended use and within the relevant time frame).

The Society is under no obligation to make statements or provide information about elements or facts which are not part of the specific scope of the Service requested by the Interested Party or on its behalf.

3.2. No report, statement, notation on a plan, review, Certificate of Classification, document or information issued or given as part of the Services provided by the Society shall have any legal effect or implication other than a representation that, on the basis of the checks made by the Society, the Ship, structure, materials, equipment, machinery or any other item covered by such document or information meet the Rules. Any such document is issued solely for the use of the Society, its committees and clients or other duly authorised bodies and for no other purpose. Therefore, the Society cannot be held liable for any act made or document issued by other parties on the basis of the statements or information given by the Society. The validity, application, meaning and interpretation of a Certificate of Classification, or any other document or information issued by the Society in connection with its Services, is governed by the Rules of the Society, which is the sole subject entitled to make such interpretation. Any disagreement on technical matters between the Interested Party and the Surveyor in the carrying out of his functions shall be raised in writing as soon as possible with the Society, which will settle any divergence of opinion or dispute.

3.3. The classification of a Ship, or the issuance of a certificate or other document connected with classification or certification and in general with the performance of Services by the Society shall have the validity conferred upon it by the Rules of the Society at the time of the assignment of class or issuance of the certificate; in no case shall it amount to a statement or warranty of seaworthiness,

structural integrity, quality or fitness for a particular purpose or service of any Ship, structure, material, equipment or machinery inspected or tested by the Society.

3.4. Any document issued by the Society in relation to its activities reflects the condition of the Ship or the subject of certification or other activity at the time of the check.

3.5. The Rules, surveys and activities performed by the Society, reports, certificates and other documents issued by the Society are in no way intended to replace the duties and responsibilities of other parties such as Governments, designers, ship builders, manufacturers, repairers, suppliers, contractors or sub-contractors, Owners, operators, charterers, underwriters, sellers or intended buyers of a Ship or other product or system surveyed.

These documents and activities do not relieve such parties from any fulfilment, warranty, responsibility, duty or obligation (also of a contractual nature) expressed or implied or in any case incumbent on them, nor do they confer on such parties any right, claim or cause of action against the Society. With particular regard to the duties of the ship Owner, the Services undertaken by the Society do not relieve the Owner of his duty to ensure proper maintenance of the Ship and ensure seaworthiness at all times. Likewise, the Rules, surveys performed, reports, certificates and other documents issued by the Society are intended neither to guarantee the buyers of the Ship, its components or any other surveyed or certified item, nor to relieve the seller of the duties arising out of the law or the contract, regarding the quality, commercial value or characteristics of the item which is the subject of transaction.

In no case, therefore, shall the Society assume the obligations incumbent upon the above-mentioned parties, even when it is consulted in connection with matters not covered by its Rules or other documents.

In consideration of the above, the Interested Party undertakes to relieve and hold harmless the Society from any third party claim, as well as from any liability in relation to the latter concerning the Services rendered.

Insofar as they are not expressly provided for in these General Conditions, the duties and responsibilities of the Owner and Interested Parties with respect to the services rendered by the Society are described in the Rules applicable to the specific Service rendered.

#### **Article 4**

4.1. Any request for the Society's Services shall be submitted in writing and signed by or on behalf of the Interested Party. Such a request will be considered irrevocable as soon as received by the Society and shall entail acceptance by the applicant of all relevant requirements of the Rules, including these General Conditions. Upon acceptance of the written request by the Society, a contract between the Society and the Interested Party is entered into, which is regulated by the present General Conditions.

4.2. In consideration of the Services rendered by the Society, the Interested Party and the person requesting the service shall be jointly liable for the payment of the relevant fees, even if the service is not concluded for any cause not pertaining to the Society. In the latter case, the Society shall not be held liable for non-fulfilment or partial fulfilment of the Services requested. In the event of late payment, interest at the legal current rate increased by 1.5% may be demanded.

4.3. The contract for the classification of a Ship or for other Services may be terminated and any certificates revoked at the request of one of the parties, subject to at least 30 days' notice to be given in writing. Failure to pay, even in part, the fees due for Services carried out by the Society will entitle the Society to immediately terminate the contract and suspend the Services.

For every termination of the contract, the fees for the activities performed until the time of the termination shall be owed to the Society as well as the expenses incurred in view of activities already programmed; this is without prejudice to the right to compensation due to the Society as a consequence of the termination.

With particular reference to Ship classification and certification, unless decided otherwise by the Society, termination of the contract implies that the assignment of class to a Ship is withheld or, if already assigned, that it is suspended or withdrawn; any statutory certificates issued by the Society will be withdrawn in those cases where provided for by agreements between the Society and the flag State.

#### **Article 5**

5.1. In providing the Services, as well as other correlated information or advice, the Society, its Surveyors, servants or agents operate with due diligence for the proper execution of the activity. However, considering the nature of the activities performed (see art. 2.4), it is not possible to guarantee absolute accuracy, correctness and completeness of any information or advice supplied. Express and implied warranties are specifically disclaimed.

Therefore, except as provided for in paragraph 5.2 below, and also in the case of activities carried out by delegation of Governments, neither the Society nor any of its Surveyors will be liable for any loss, damage or expense of whatever nature sustained by any person, in tort or in contract, derived from carrying out the Services.

5.2. Notwithstanding the provisions in paragraph 5.1 above, should any user of the Society's Services prove that he has suffered a loss or damage due to any negligent act or omission of the Society, its Surveyors, servants or agents, then the Society will pay compensation to such person for his proved loss, up to, but not exceeding, five times the amount of the fees charged for the specific services, information or opinions from which the loss or damage derives or, if no fee has been charged, a maximum of AED5,000 (Arab Emirates Dirhams Five Thousand only). Where the fees charged are related to a number of Services, the amount of the fees will be apportioned for the purpose of the calculation of the maximum compensation, by reference to the estimated time involved in the performance of the Service from which the damage or loss derives. Any liability for indirect or consequential loss, damage or expense is specifically excluded. In any case, irrespective of the amount of the fees charged, the maximum damages payable by the Society will not be more than AED5,000,000 (Arab Emirates Dirhams Five Millions only). Payment of compensation under this paragraph will not entail any admission of responsibility and/or liability by the Society and will be made without prejudice to the disclaimer clause contained in paragraph 5.1 above.

5.3. Any claim for loss or damage of whatever nature by virtue of the provisions set forth herein shall be made to the Society in writing, within the shorter of the following periods: (i) THREE (3) MONTHS from the date on which the Services were performed, or (ii) THREE (3) MONTHS from the date on which the damage was discovered. Failure to comply with the above deadline will constitute an absolute bar to the pursuit of such a claim against the Society.

#### **Article 6**

6.1. These General Conditions shall be governed by and construed in accordance with United Arab Emirates (UAE) law, and any dispute arising from or in connection with the Rules or with the Services of the Society, including any issues concerning responsibility, liability or limitations of liability of the Society, shall be determined in accordance with UAE law. The courts of the Dubai International Financial Centre (DIFC) shall have exclusive jurisdiction in relation to any claim or dispute which may arise out of or in connection with the Rules or with the Services of the Society.

6.2. However,

- (i) In cases where neither the claim nor any counterclaim exceeds the sum of AED300,000 (Arab Emirates Dirhams Three Hundred Thousand) the dispute shall be referred to the jurisdiction of the DIFC Small Claims Tribunal; and
- (ii) for disputes concerning non-payment of the fees and/or expenses due to the Society for services, the Society shall have the

right to submit any claim to the jurisdiction of the Courts of the place where the registered or operating office of the Interested Party or of the applicant who requested the Service is located.

In the case of actions taken against the Society by a third party before a public Court, the Society shall also have the right to summon the Interested Party or the subject who requested the Service before that Court, in order to be relieved and held harmless according to art. 3.5 above.

#### **Article 7**

**7.1.** All plans, specifications, documents and information provided by, issued by, or made known to the Society, in connection with the performance of its Services, will be treated as confidential and will not be made available to any other party other than the Owner without authorisation of the Interested Party, except as provided for or required by any applicable international, European or domestic legislation, Charter or other IACS resolutions, or order from a competent authority. Information about the status and validity of class and statutory certificates, including transfers, changes, suspensions, withdrawals of class, recommendations/conditions of class, operating conditions or restrictions issued against classed ships and other related information, as may be required, may be published on the website or released by other means, without the prior consent of the Interested Party.

Information about the status and validity of other certificates and statements may also be published on the website or released by other means, without the prior consent of the Interested Party.

**7.2.** Notwithstanding the general duty of confidentiality owed by the Society to its clients in clause 7.1 above, the Society's clients hereby accept that the Society may participate in the IACS Early Warning System which requires each Classification Society to provide other involved Classification Societies with relevant technical information on serious hull structural and engineering systems failures, as defined in the IACS Early Warning System (but not including any drawings relating to the ship which may be the specific property of another party), to enable such useful information to be shared and used to facilitate the proper working of the IACS Early Warning System. The Society will provide its clients with written details of such information sent to the involved Classification Societies.

**7.3.** In the event of transfer of class, addition of a second class or withdrawal from a double/dual class, the Interested Party undertakes to provide or to permit the Society to provide the other Classification Society with all building plans and drawings, certificates, documents and information relevant to the classed unit, including its history file, as the other Classification Society may require for the purpose of classification in compliance with the applicable legislation and relative IACS Procedure. It is the Owner's duty to ensure that, whenever required, the consent of the builder is obtained with regard to the provision of plans and drawings to the new Society, either by way of appropriate stipulation in the building contract or by other agreement.

In the event that the ownership of the ship, product or system subject to certification is transferred to a new subject, the latter shall have the right to access all pertinent drawings, specifications, documents or information issued by the Society or which has come to the knowledge of the Society while carrying out its Services, even if related to a period prior to transfer of ownership.

#### **Article 8**

**8.1.** Should any part of these General Conditions be declared invalid, this will not affect the validity of the remaining provisions.



RULES FOR THE CLASSIFICATION OF  
OFFSHORE UNITS OPERATING IN THE CASPIAN SEA  
AND SIMILAR AREAS

Part C  
**Machinery, Systems and Fire Protection**

Chapters 1 **2 3 4**

---

Chapter 1	MACHINERY
<b>Chapter 2</b>	<b>ELECTRICAL INSTALLATIONS</b>
<b>Chapter 3</b>	<b>AUTOMATION</b>
<b>Chapter 4</b>	<b>FIRE PROTECTION AND SAFETY SYSTEMS</b>



# CHAPTER 2

## ELECTRICAL INSTALLATIONS

### Section 1 General

<b>1</b>	<b>Application</b>	<b>21</b>
	1.1 General	
	1.2 References to other regulations and standards	
<b>2</b>	<b>Documentation to be submitted</b>	<b>21</b>
	2.1	
<b>3</b>	<b>Definitions</b>	<b>21</b>
	3.1 General	
	3.2 Essential services	
	3.3 Safety voltage	
	3.4 Low-voltage systems	
	3.5 High-voltage systems	
	3.6 Basic insulation	
	3.7 Supplementary insulation	
	3.8 Double insulation	
	3.9 Reinforced insulation	
	3.10 Earthing	
	3.11 Normal operational and habitable condition	
	3.12 Emergency condition	
	3.13 Main source of electrical power	
	3.14 Dead ship condition	
	3.15 Main generating station	
	3.16 Main switchboard	
	3.17 Emergency switchboard	
	3.18 Emergency source of electrical power	
	3.19 Section boards	
	3.20 Distribution board	
	3.21 Final sub-circuit	
	3.22 Hazardous areas	
	3.23 Certified safe-type equipment	

### Section 2 General Design Requirements

<b>1</b>	<b>Environmental conditions</b>	<b>25</b>
	1.1 General	
	1.2 Ambient air temperatures	
	1.3 Humidity	
	1.4 Cooling water temperatures	
	1.5 Salt mist	
	1.6 Inclinations	
	1.7 Vibrations	
<b>2</b>	<b>Quality of power supply</b>	<b>26</b>
	2.1 Voltage and frequency variation	
	2.2 Harmonic distortions	



<b>3</b>	<b>Electromagnetic susceptibility</b>	<b>27</b>
	3.1	
<b>4</b>	<b>Materials</b>	<b>27</b>
	4.1 General	
	4.2 Insulating materials for windings	
	4.3 Insulating materials for cables	
<b>5</b>	<b>Construction</b>	<b>28</b>
	5.1 General	
	5.2 Degree of protection of enclosures	
<b>6</b>	<b>Protection against explosion hazard</b>	<b>28</b>
	6.1 Protection against explosive gas or vapour atmosphere hazard	
	6.2 Protection against combustible dust hazard	

### **Section 3 System Design**

<b>1</b>	<b>Supply systems and characteristics of the supply</b>	<b>30</b>
	1.1 Supply systems	
	1.2 Maximum voltages	
<b>2</b>	<b>Sources of electrical power</b>	<b>31</b>
	2.1 General	
	2.2 Main source of electrical power	
	2.3 Emergency source of electrical power	
<b>3</b>	<b>Distribution</b>	<b>34</b>
	3.1 Earthed distribution systems	
	3.2 Insulated distribution systems	
	3.3 General requirements for distribution systems	
	3.4 Main distribution of electrical power	
	3.5 Emergency distribution of electrical power	
	3.6 Shore supply	
	3.7 Supply of motors	
	3.8 Specific requirements for special power services	
	3.9 Power supply to heaters	
	3.10 Power supply to lighting installations	
	3.11 Special lighting services	
	3.12 Navigation lights	
	3.13 General emergency alarm system	
	3.14 Public address system	
	3.15 Combined general emergency alarm - public address system	
	3.16 Control and indication circuits	
	3.17 Power supply to the speed control systems of main propulsion engines	
	3.18 Power supply to the speed control systems of generator sets	
<b>4</b>	<b>Degrees of protection of the enclosures</b>	<b>39</b>
	4.1 General	
<b>5</b>	<b>Diversity (demand) factors</b>	<b>40</b>
	5.1 General	

<b>6</b>	<b>Electrical protection</b>	<b>40</b>
	6.1 General requirements for overcurrent protection	
	6.2 Short-circuit currents	
	6.3 Selection of equipment	
	6.4 Protection against short-circuit	
	6.5 Continuity of supply and continuity of service	
	6.6 Protection against overload	
	6.7 Localisation of overcurrent protection	
	6.8 Protection of generators	
	6.9 Protection of circuits	
	6.10 Protection of motors	
	6.11 Protection of storage batteries	
	6.12 Protection of shore power connection	
	6.13 Protection of measuring instruments, pilot lamps and control circuits	
	6.14 Protection of transformers	
<b>7</b>	<b>System components</b>	<b>45</b>
	7.1 General	
<b>8</b>	<b>Electrical cables</b>	<b>45</b>
	8.1 General	
	8.2 Choice of insulation	
	8.3 Choice of protective covering	
	8.4 Cables in refrigerated spaces	
	8.5 Cables in areas with a risk of explosion	
	8.6 Electrical services required to be operable under fire conditions and fire-resistant cables	
	8.7 Cables for submerged bilge pumps	
	8.8 Internal wiring of switchboards and other enclosures for equipment	
	8.9 Current carrying capacity of cables	
	8.10 Minimum nominal cross-sectional area of conductors	
	8.11 Choice of cables	
<b>9</b>	<b>Electrical installations in hazardous areas</b>	<b>50</b>
	9.1 Electrical equipment	
	9.2 Electrical cables	
	9.3 Electrical installations in battery rooms	
	9.4 Electrical equipment allowed in paint stores and in enclosed spaces leading to paint stores	
	9.5 Electrical installations in stores for welding gas (acetylene) bottles	
<b>10</b>	<b>Recording of the Type, Location and Maintenance Cycle of Batteries</b>	<b>52</b>
	10.1 Battery schedule	

## **Section 4 Rotating Machines**

<b>1</b>	<b>Constructional and operational requirements for generators and motors</b>	<b>53</b>
	1.1 Mechanical construction	
	1.2 Sliprings, commutators and brushes	
	1.3 Terminal connectors	
	1.4 Electrical insulation	
<b>2</b>	<b>Special requirements for generators</b>	<b>53</b>
	2.1 Prime movers, speed governors and overspeed protection	
	2.2 A.c. generators	

<b>3</b>	<b>Testing of rotating machines</b>	<b>54</b>
3.1	General	
3.2	Shaft material	
3.3	Tests	
<b>4</b>	<b>Description of the test</b>	<b>55</b>
4.1	Examination of the technical documentation, as appropriate, and visual inspection	
4.2	Insulation resistance measurement	
4.3	Winding resistance measurement	
4.4	Verification of the voltage regulation system	
4.5	Rated load test and temperature rise measurements	
4.6	Overload/overcurrent tests	
4.7	Verification of steady short-circuit conditions	
4.8	Overspeed test	
4.9	Dielectric strength test	
4.10	No load test	
4.11	Verification of degree of protection	
4.12	Verification of bearings	

## **Section 5 Transformers**

<b>1</b>	<b>Constructional and operational requirements</b>	<b>57</b>
1.1	Construction	
1.2	Terminals	
1.3	Short-circuit conditions and parallel operation	
1.4	Electrical insulation and temperature rise	
1.5	Insulation tests	
<b>2</b>	<b>Testing</b>	<b>58</b>
2.1	General	
2.2	Tests on transformers	

## **Section 6 Semiconductor Convertors**

<b>1</b>	<b>Constructional and operational requirements</b>	<b>59</b>
1.1	Construction	
1.2	Protection	
1.3	Parallel operation with other power sources	
1.4	Temperature rise	
1.5	Insulation test	
<b>2</b>	<b>Testing</b>	<b>60</b>
2.1	General	
2.2	Tests on convertors	

## **Section 7 Storage Batteries, Chargers and Uninterruptible Power Systems**

<b>1</b>	<b>Constructional requirements for batteries</b>	<b>61</b>
1.1	General	
1.2	Vented batteries	
1.3	Valve-regulated sealed batteries	
1.4	Tests on batteries	
<b>2</b>	<b>Constructional requirements for chargers</b>	<b>61</b>
2.1	Characteristics	
2.2	Tests on chargers	
<b>3</b>	<b>Uninterruptible power system (UPS) units as alternative and/or transitional power</b>	<b>62</b>
3.1	Application	
3.2	Definitions	
3.3	Design and construction	
3.4	Location	
3.5	Performance	
3.6	Testing and survey	

## **Section 8 Switchgear and Controlgear Assemblies**

<b>1</b>	<b>Constructional requirements for main and emergency switchboards</b>	<b>64</b>
1.1	Construction	
1.2	Busbars and bare conductors	
1.3	Internal wiring	
1.4	Switchgear and controlgear	
1.5	Auxiliary circuits	
1.6	Instruments	
<b>2</b>	<b>Constructional requirements for section boards and distribution boards</b>	<b>66</b>
2.1	Construction	
<b>3</b>	<b>Testing</b>	<b>66</b>
3.1	General	
3.2	Inspection of equipment, check of wiring and electrical operation test	
3.3	High voltage test	
3.4	Measurement of insulation resistance	

## **Section 9 Cables**

<b>1</b>	<b>Constructional requirements</b>	<b>68</b>
1.1	Construction	
1.2	Conductors	
1.3	Insulating materials	
1.4	Inner covering, fillers and binders	
1.5	Protective coverings (armour and sheath)	
1.6	Identification	
<b>2</b>	<b>Testing</b>	<b>69</b>
2.1	Type tests	
2.2	Routine tests	

## Section 10 Miscellaneous Equipment

<b>1</b>	<b>Switchgear and controlgear, protective devices</b>	<b>70</b>
	1.1 General	
	1.2 Circuit-breakers	
	1.3 Protection devices	
<b>2</b>	<b>Lighting fittings</b>	<b>70</b>
	2.1 Applicable requirements	
	2.2 Construction	
<b>3</b>	<b>Accessories</b>	<b>70</b>
	3.1 Applicable requirements	
	3.2 Construction	
<b>4</b>	<b>Plug-and-socket connections</b>	<b>71</b>
	4.1 Applicable requirements	
<b>5</b>	<b>Heating and cooking appliances</b>	<b>71</b>
	5.1 Applicable requirements	
	5.2 General	
	5.3 Space heaters	
	5.4 Cooking appliances	
	5.5 Fuel oil and lube oil heaters	
	5.6 Water heaters	
<b>6</b>	<b>Cable trays/protective casings made of plastics materials</b>	<b>71</b>
	6.1 General requirement	
	6.2 Installation Requirements	

## Section 11 Location

<b>1</b>	<b>General</b>	<b>73</b>
	1.1 Location	
	1.2 Areas with a risk of explosion	
<b>2</b>	<b>Main electrical system</b>	<b>73</b>
	2.1 Location in relation to the emergency system	
	2.2 Main switchboard	
<b>3</b>	<b>Emergency electrical system</b>	<b>73</b>
	3.1 Spaces for the emergency source	
	3.2 Location in relation to the main electrical system	
	3.3 Emergency switchboard	
	3.4 Emergency battery	
<b>4</b>	<b>Distribution boards</b>	<b>74</b>
	4.1 Distribution boards for cargo spaces and similar spaces	
	4.2 Distribution board for navigation lights	

<b>5</b>	<b>Cable runs</b>	<b>74</b>
5.1	General	
5.2	Location of cables in relation to the risk of fire and overheating	
5.3	Location of cables in relation to electromagnetic interference	
5.4	Services with a duplicate feeder	
5.5	Emergency circuits	
<b>6</b>	<b>Storage batteries</b>	<b>75</b>
6.1	General	
6.2	Large vented batteries	
6.3	Moderate vented batteries	
6.4	Small vented batteries	
6.5	Ventilation	

## **Section 12 Installation**

<b>1</b>	<b>General</b>	<b>77</b>
1.1	Protection against injury or damage caused by electrical equipment	
1.2	Protection against damage to electrical equipment	
1.3	Accessibility	
<b>2</b>	<b>Earthing of non-current carrying parts</b>	<b>77</b>
2.1	Parts which are to be earthed	
2.2	Methods of earthing	
2.3	Earthing connections	
2.4	Connection to the ship's structure	
2.5	Earthed distribution systems	
2.6	Aluminium superstructures	
<b>3</b>	<b>Rotating machines</b>	<b>78</b>
3.1		
<b>4</b>	<b>Semiconductor convertors</b>	<b>79</b>
4.1	Semiconductor power convertors	
<b>5</b>	<b>Vented type storage batteries</b>	<b>79</b>
5.1	General	
5.2	Protection against corrosion	
<b>6</b>	<b>Switchgear and controlgear assemblies</b>	<b>79</b>
6.1	Main switchboard	
6.2	Emergency switchboard	
6.3	Section boards and distribution boards	
<b>7</b>	<b>Cables</b>	<b>80</b>
7.1	General	
7.2	Radius of bend	
7.3	Fixing of cables	
7.4	Mechanical protection	
7.5	Penetrations of bulkheads and decks	
7.6	Expansion joints	
7.7	Cables in closed pipes or conduits	
7.8	Cables in casings or trunking and conduits with removable covers	
7.9	Cable ends	
7.10	Joints and tappings (branch circuit)	

- 7.11 Earthing and continuity of metal coverings of cables
- 7.12 Earthing and continuity of metal pipes, conduits and trunking or casings
- 7.13 Precautions for single-core cables for a.c.
- 7.14 Cables in refrigerated spaces
- 7.15 Cables in areas with a risk of explosion
- 7.16 Cables in the vicinity of radio equipment
- 7.17 Cables for submerged bilge pumps

---

**8      Various appliances      85**

---

- 8.1 Lighting fittings
- 8.2 Heating appliances
- 8.3 Heating cables and tapes or other heating elements

**Section 13 High Voltage Installations**

---

**1      General      87**

---

- 1.1 Field of application
- 1.2 Nominal system voltage
- 1.3 High-voltage, low-voltage segregation

---

**2      System Design      87**

---

- 2.1 Distribution
- 2.2 Degrees of protection
- 2.3 Insulation
- 2.4 Protection

---

**3      Rotating machinery      88**

---

- 3.1 Stator windings of generators
- 3.2 Temperature detectors
- 3.3 Tests

---

**4      Power Transformers      88**

---

- 4.1 General

---

**5      Cables      89**

---

- 5.1 General

---

**6      Switchgear and controlgear assemblies      89**

---

- 6.1 General
- 6.2 Construction
- 6.3 Auxiliary systems
- 6.4 High voltage test

---

**7      Installation      89**

---

- 7.1 Electrical equipment
- 7.2 Cables

## Section 14 Electric Propulsion Plant

<b>1</b>	<b>General</b>	<b>91</b>
	1.1 Applicable requirements	
	1.2 Operating conditions	
<b>2</b>	<b>Design of the propulsion plant</b>	<b>91</b>
	2.1 General	
	2.2 Power supply	
	2.3 Auxiliary machinery	
	2.4 Electrical Protection	
	2.5 Excitation of electric propulsion motor	
<b>3</b>	<b>Construction of rotating machines and semiconductor convertors</b>	<b>92</b>
	3.1 Ventilation	
	3.2 Protection against moisture and condensate	
	3.3 Rotating machines	
	3.4 Semiconductor convertors	
<b>4</b>	<b>Control and monitoring</b>	<b>93</b>
	4.1 General	
	4.2 Power plant control systems	
	4.3 Indicating instruments	
	4.4 Alarm system	
	4.5 Reduction of power	
<b>5</b>	<b>Installation</b>	<b>94</b>
	5.1 Ventilation of spaces	
	5.2 Cable runs	
<b>6</b>	<b>Tests</b>	<b>94</b>
	6.1 Test of rotating machines	
<b>7</b>	<b>Specific requirements for PODs</b>	<b>95</b>
	7.1 General	
	7.2 Rotating commutators	
	7.3 Electric motors	
	7.4 Instrumentation and associated devices	
	7.5 Additional tests	



## Section 15 Testing

1	General	96
	1.1 Rule application	
	1.2 Insulation-testing instruments	
2	Type approved components	96
	2.1	
3	Insulation resistance	96
	3.1 Lighting and power circuits	
	3.2 Internal communication circuits	
	3.3 Switchboards	
	3.4 Generators and motors	
4	Earth	96
	4.1 Electrical constructions	
	4.2 Metal-sheathed cables, metal pipes or conduits	
5	Operational tests	97
	5.1 Generating sets and their protective devices	
	5.2 Switchgear	
	5.3 Consuming devices	
	5.4 Communication systems	
	5.5 Installations in areas with a risk of explosion	
	5.6 Voltage drop	

## Appendix 1 Indirect Test Method for Synchronous Machines

1	General	98
	1.1 Test method	

# CHAPTER 3

## AUTOMATION

### Section 1 General Requirements

<b>1</b>	<b>General</b>	<b>103</b>
	1.1 Field of application	
	1.2 Regulations and standards	
	1.3 Definitions	
	1.4 General	
<b>2</b>	<b>Documentation</b>	<b>104</b>
	2.1 General	
	2.2 Documents to be submitted	
	2.3 Documents for programmable electronic system	
<b>3</b>	<b>Environmental and supply conditions</b>	<b>105</b>
	3.1 General	
	3.2 Power supply conditions	
<b>4</b>	<b>Materials and construction</b>	<b>105</b>
	4.1 General	
	4.2 Type approved components	

### Section 2 Design Requirements

<b>1</b>	<b>General</b>	<b>106</b>
	1.1	
<b>2</b>	<b>Power supply of automation systems</b>	<b>106</b>
	2.1 General	
	2.2 Electrical power supply	
<b>3</b>	<b>Control systems</b>	<b>106</b>
	3.1 Local control	
	3.2 Remote control systems	
	3.3 Automatic control systems	
<b>4</b>	<b>Control of propulsion machinery</b>	<b>106</b>
	4.1 Remote control	
	4.2 Remote control from navigating bridge	
	4.3 Automatic control	
	4.4 Automatic control of propulsion and manoeuvring units	
	4.5 Clutches	
	4.6 Brakes	
<b>5</b>	<b>Remote control of valves</b>	<b>108</b>
	5.1	
<b>6</b>	<b>Alarm system</b>	<b>108</b>
	6.1 General requirements	
	6.2 Alarm functions	

<b>7</b>	<b>Safety system</b>	<b>109</b>
	7.1 Design	
	7.2 Function	
	7.3 Shutdown	
	7.4 Standby systems	
	7.5 Testing	

### **Section 3 Programmable Electronic Systems**

<b>1</b>	<b>Scope</b>	<b>110</b>
	1.1 General	
<b>2</b>	<b>Requirements applicable to programmable electronic systems</b>	<b>110</b>
	2.1 General	
	2.2 System categories	
	2.3 Data communication links	
	2.4 Additional requirements for wireless data links	
	2.5 Protection against modification	
<b>3</b>	<b>Documentation</b>	<b>111</b>
	3.1 Documents to be submitted	
<b>4</b>	<b>Tests and Evidence</b>	<b>112</b>
	4.1	
<b>5</b>	<b>Definitions and notes relating to Tab 3, tests and evidence</b>	<b>114</b>
	5.1 Evidence of quality system	
	5.2 Hardware and software description	
	5.3 Evidence of software testing	
	5.4 Hardware tests	
	5.5 Software tests	
	5.6 Performance tests	
	5.7 On board tests	
	5.8 Modifications	

### **Section 4 Constructional Requirements**

<b>1</b>	<b>General</b>	<b>116</b>
	1.1 Construction	
	1.2 Materials	
	1.3 Component design	
	1.4 Environmental and supply conditions	
<b>2</b>	<b>Electrical and/or electronic systems</b>	<b>116</b>
	2.1 General	
	2.2 Electronic system	
	2.3 Electrical system	
<b>3</b>	<b>Pneumatic systems</b>	<b>117</b>
	3.1	
<b>4</b>	<b>Hydraulic systems</b>	<b>117</b>
	4.1	

<b>5</b>	<b>Automation consoles</b>	<b>117</b>
	5.1 General	
	5.2 Indicating instruments	
	5.3 VDU's and keyboards	

## **Section 5 Installation Requirements**

<b>1</b>	<b>General</b>	<b>118</b>
	1.1	
<b>2</b>	<b>Sensors and components</b>	<b>118</b>
	2.1 General	
	2.2 Temperature elements	
	2.3 Pressure elements	
	2.4 Level switches	
<b>3</b>	<b>Cables</b>	<b>118</b>
	3.1 Installation	
	3.2 Cable terminations	
<b>4</b>	<b>Pipes</b>	<b>119</b>
	4.1	
<b>5</b>	<b>Automation consoles</b>	<b>119</b>
	5.1 General	

## **Section 6 Testing**

<b>1</b>	<b>General</b>	<b>120</b>
	1.1 Commissioning	
<b>2</b>	<b>Type approval</b>	<b>120</b>
	2.1 General	
	2.2 Hardware type approval	
	2.3 Software type approval	
	2.4 Navigational and radio equipment	
	2.5 Loading instruments	
<b>3</b>	<b>Acceptance testing</b>	<b>129</b>
	3.1 General	
	3.2 Hardware testing	
	3.3 Software testing	
<b>4</b>	<b>Commissioning</b>	<b>130</b>
	4.1 General	

# CHAPTER 4

## FIRE PROTECTION AND SAFETY SYSTEMS

### Section 1 Fire Protection, Detection and Extinction

<b>1</b>	<b>General</b>	<b>133</b>
	1.1 Purpose and application	
<b>2</b>	<b>Documentation to be submitted</b>	<b>133</b>
	2.1	
<b>3</b>	<b>Definitions</b>	<b>134</b>
	3.1 Accommodation spaces	
	3.2 Cargo area	
	3.3 Cargo spaces	
	3.4 Continuously manned central control stations	
	3.5 Control stations	
	3.6 Crude oil	
	3.7 Deadweight	
	3.8 Flashpoint	
	3.9 Lightweight	
	3.10 Machinery spaces	
	3.11 Machinery spaces of category A	
	3.12 Oil fuel unit	
	3.13 Public spaces	
	3.14 Service spaces	
	3.15 Special category spaces	
	3.16 Tanker	
	3.17 Weather decks	
<b>4</b>	<b>Type approved products</b>	<b>135</b>
	4.1	
<b>5</b>	<b>Probability of ignition</b>	<b>135</b>
	5.1 Arrangements for gaseous fuel for domestic purposes	
	5.2 Cargo area of tankers	
	5.3 Non-sparking fans	
<b>6</b>	<b>Suppression of fire - detection and alarm</b>	<b>137</b>
	6.1 Protection of machinery spaces	
<b>7</b>	<b>Suppression of fire: fire - fighting</b>	<b>138</b>
	7.1 Fire-extinguishing arrangements in machinery spaces	
<b>8</b>	<b>Low pressure carbon dioxide systems</b>	<b>139</b>
	8.1 Vessels and associated devices	
	8.2 Refrigerating plant	
	8.3 Pipes, valves and associated fittings	
	8.4 Control of fire-extinguishing system operation	
	8.5 Release control	
	8.6 Testing	

9	Fire safety systems: General requirements and application for inert gas systems	140
	9.1 General requirements	
	9.2 Application	
	9.3 Requirements for equivalent systems	
10	Fire safety systems: Inert gas systems on oil tankers	141
	10.1 Contents	
	10.2 Engineering specifications	
	10.3 Additional requirements	

## Section 2 Emergency Shutdown Systems

1	General requirements and definitions	146
	1.1	
2	Basic design principles	146
	2.1	
3	Design and functional requirements	147
	3.1	
4	Automatic and manual shutdown	147
	4.1	
5	Electrical equipment for use in an emergency	147
	5.1	

## Section 3 Gas Alarm and Detection Systems

1	General	148
	1.1	
	1.2 H2S alarm system	
	1.3 H2S survival kits	
	1.4 Gas detection and alarm	



Part C

# Machinery, Systems and Fire Protection

Chapter 2

## ELECTRICAL INSTALLATIONS

---

<b>SECTION 1</b>	<b>GENERAL</b>
<b>SECTION 2</b>	<b>GENERAL DESIGN REQUIREMENTS</b>
<b>SECTION 3</b>	<b>SYSTEM DESIGN</b>
<b>SECTION 4</b>	<b>ROTATING MACHINES</b>
<b>SECTION 5</b>	<b>TRANSFORMERS</b>
<b>SECTION 6</b>	<b>SEMICONDUCTOR CONVERTORS</b>
<b>SECTION 7</b>	<b>STORAGE BATTERIES, CHARGERS AND UNINTERRUPTIBLE POWER SYSTEMS</b>
<b>SECTION 8</b>	<b>SWITCHGEAR AND CONTROLGEAR ASSEMBLIES</b>
<b>SECTION 9</b>	<b>CABLES</b>
<b>SECTION 10</b>	<b>MISCELLANEOUS EQUIPMENT</b>
<b>SECTION 11</b>	<b>LOCATION</b>
<b>SECTION 12</b>	<b>INSTALLATION</b>
<b>SECTION 13</b>	<b>HIGH VOLTAGE INSTALLATIONS</b>
<b>SECTION 14</b>	<b>ELECTRIC PROPULSION PLANT</b>
<b>SECTION 15</b>	<b>TESTING</b>
<b>APPENDIX 1</b>	<b>INDIRECT TEST METHOD FOR SYNCHRONOUS MACHINES</b>





# SECTION 1

# GENERAL

## 1 Application

### 1.1 General

**1.1.1** The requirements of this Chapter apply to electrical installations on Offshore Units operating in the Caspian Sea in similar areas. In particular, they apply to the components of electrical installations for:

- essential services including those for special purposes connected with ships specifically intended for such purposes
- services for habitability.

The other parts of the installation are to be so designed as not to introduce any risks or malfunctions to the above services.

**1.1.2** The statutory requirements of the IMO Conventions and/or national safety regulations, as applicable, regarding fire protection, detection and extinction (hereinafter referred to as "fire protection statutory requirements") are no mandatory for the purpose of classification, except where the Society carries out surveys relevant to fire protection statutory requirements on behalf of the flag Administration. In such cases, fire protection statutory requirements are considered a matter of class and therefore compliance with these requirements is also verified by the Society for classification purposes.

**1.1.3** The Society may consider modified requirements for installations not exceeding either 50 V or 50 kW total generator capacity.

### 1.2 References to other regulations and standards

**1.2.1** The Society may refer to other regulations and standards when deemed necessary. These include the IEC standards, notably the IEC 60092 series.

**1.2.2** When referred to by the Society, standards by the International Electrotechnical Commission (IEC) or other internationally recognised standards, are those currently in force at the date of agreement for ship classification.

## 2 Documentation to be submitted

### 2.1

**2.1.1** The documents listed in Tab 1 are to be submitted. The list of documents requested is to be intended as guidance for the complete set of information to be submitted, rather than an actual list of titles.

The Society reserves the right to request the submission of additional documents in the case of non-conventional

design or if it is deemed necessary for the evaluation of the system, equipment or components.

Unless otherwise agreed with the Society, documents for approval are to be sent in triplicate if submitted by the Shipyard and in four copies if submitted by the equipment supplier.

Documents requested for information are to be sent in duplicate.

In any case, the Society reserves the right to require additional copies when deemed necessary.

## 3 Definitions

### 3.1 General

**3.1.1** Unless otherwise stated, the terms used in this Chapter have the definitions laid down by the IEC standards.

The definitions given in the following requirements also apply.

### 3.2 Essential services

**3.2.1** Essential services are those services essential for propulsion and steering, and the safety of the ship, and services to ensure minimum safe and comfortable conditions of habitability and necessary for special purposes connected with ships specifically intended for such purposes.

**3.2.2** Examples of essential services that need to be in continuous operation for maintaining propulsion, steering and safe habitability conditions are the following:

- Steering gear
- Pumps for controllable pitch propellers
- Scavenging air blowers, fuel oil supply pumps, fuel valve cooling pumps, lubricating oil pumps and cooling water pumps for main and auxiliary engines and turbines necessary for the propulsion
- Forced draught fans, feed water pumps, water circulating pumps, condensate pumps, oil burning installations, for steam plants or steam turbines ship, and also for auxiliary boilers on ship where steam is used for equipment supplying primary essential services
- Azimuth thrusters which are the sole means for propulsion/steering with lubricating oil pumps, cooling water pumps
- Electrical equipment for electric propulsion plant with lubricating oil pumps and cooling water pumps
- Electric generators and associated power sources supplying the above equipment
- Hydraulic pumps supplying the above equipment
- Viscosity control equipment for heavy fuel oil

**Pt C, Ch 2, Sec 1**

- Control, monitoring and safety devices/systems for equipment for primary essential services
- Speed regulators dependent on electrical energy for main or auxiliary engines necessary for propulsion.
- hazardous gas detection.

The main lighting system for those parts of the ship normally accessible to and used by personnel and passengers is also considered among these essential service.

**3.2.3** Examples of essential services that need not necessarily be in continuous operation to maintain propulsion, steering and safe habitability conditions, but are necessary for maintaining the ship's safety are the following:

- Windlasses
- Fuel oil transfer pumps and fuel oil treatment equipment
- Lubrication oil transfer pumps and lubrication oil treatment equipment
- Preheaters for heavy fuel oil
- Sea water pumps

- Starting air and control air compressors
- Bilge, ballast and heeling pumps
- Fire pumps and other fire-extinguishing medium pumps
- Ventilation fans for engine and boiler rooms
- Services considered necessary to maintain dangerous cargo in a safe condition
- Navigation lights, aids and signals
- Internal safety communication equipment
- Fire detection and alarm systems
- Electrical equipment for watertight closing appliances
- Electric generators and associated power supplying the above equipment
- Hydraulic pumps supplying the above equipment
- Control, monitoring and safety for cargo containment systems
- Control, monitoring and safety devices/systems for equipment for secondary essential services.

**Table 1 : Documents to be submitted**

No.	I/A (1)	Documents to be submitted
1	A	Single line diagram of main and emergency power and lighting systems.
2	A	Electrical power balance (main and emergency supply).
3	A	Calculation of short-circuit currents for each installation in which the sum of rated power of the energy sources which may be connected contemporaneously to the network is greater than 500 kVA (kW).
4	A	List of circuits including, for each supply and distribution circuit, data concerning the nominal current, the cable type, length and cross-section, nominal and setting values of the protective and control devices.
5	A	Single line diagram and detailed diagram of the main switchboard.
6	A	Single line diagram and detailed diagram of the emergency switchboard.
7	A	Diagram of the most important section boards and motor control centres (above 100 kW).
8	A	Diagram of the general emergency alarm system, of the public address system and other intercommunication systems (see [1.1.2]).
9	A	Detailed diagram of the navigation-light switchboard.
10	I	Schedule for recording of the type, location and maintenance cycle of batteries.
11	A (2)	Selectivity and coordination of the electrical protection.
12	A (3)	Single line diagram.
13	A (3)	Principles of control system and its power supply.
14	A (3)	Alarm and monitoring system including: <ul style="list-style-type: none"> <li>• list of alarms and monitoring points</li> <li>• power supply diagram.</li> </ul>
15	A (3)	Safety system including: <ul style="list-style-type: none"> <li>• list of monitored parameters for safety system</li> <li>• power supply diagram.</li> </ul>
<p>(1) A: to be submitted for approval I: to be submitted for information (2) for high voltage installations (3) for electric propulsion installations.</p>		

**3.2.4** Services of safety and comfort for habitability are those which need to be in operation to maintain the ships minimum conditions for people on board.

Examples of equipment for maintaining conditions of safety and habitability:

- Cooking
- Heating
- Domestic refrigeration
- Mechanical ventilation
- Sanitary and fresh water
- Electric generators and associated power sources supplying the above equipment.

### 3.3 Safety voltage

**3.3.1** A voltage which does not exceed 50 V a.c. r.m.s. between conductors, or between any conductor and earth, in a circuit isolated from the supply by means such as a safety isolating transformer.

**3.3.2** A voltage which does not exceed 50 V d.c. between conductors or between any conductor and earth in a circuit isolated from higher voltage circuits.

### 3.4 Low-voltage systems

**3.4.1** Alternating current systems with rated voltages greater than 50 V r.m.s. up to 1000 V r.m.s. inclusive and direct current systems with a maximum instantaneous value of the voltage under rated operating conditions greater than 50 V up to 1500 V inclusive.

### 3.5 High-voltage systems

**3.5.1** Alternating current systems with rated voltages greater than 1000 V r.m.s. and direct current systems with a maximum instantaneous value of the voltage under rated operating conditions greater than 1500 V.

### 3.6 Basic insulation

**3.6.1** Insulation applied to live parts to provide basic protection against electric shock.

Note 1: Basic insulation does not necessarily include insulation used exclusively for functional purposes.

### 3.7 Supplementary insulation

**3.7.1** Independent insulation applied in addition to basic insulation in order to provide protection against electric shock in the event of a failure of basic insulation.

### 3.8 Double insulation

**3.8.1** Insulation comprising both basic insulation and supplementary insulation.

## 3.9 Reinforced insulation

**3.9.1** A single insulation system applied to live parts, which provides a degree of protection against electric shock equivalent to double insulation.

Note 1: The term "single insulation system" does not imply that the insulation must be one homogeneous piece. It may comprise several layers which cannot be tested singly as supplementary or basic insulation.

## 3.10 Earthing

**3.10.1** The earth connection to the general mass of the hull of the ship in such a manner as will ensure at all times an immediate discharge of electrical energy without danger.

## 3.11 Normal operational and habitable condition

**3.11.1** A condition under which the ship as a whole, the machinery, services, means and aids ensuring propulsion, ability to steer, safe navigation, fire and flooding safety, internal and external communications and signals, means of escape, and emergency boat winches, as well as the designed comfortable conditions of safety and habitability are in working order and functioning normally.

## 3.12 Emergency condition

**3.12.1** A condition under which any services needed for normal operational and habitable conditions are not in working order due to failure of the main source of electrical power.

## 3.13 Main source of electrical power

**3.13.1** A source intended to supply electrical power to the main switchboard for distribution to all services necessary for maintaining the ship in normal operational and habitable condition.

## 3.14 Dead ship condition

**3.14.1** The condition under which the main propulsion plant, boilers and auxiliaries are not in operation due to the absence of power.

Note 1: Dead ship condition is a condition in which the entire machinery installation, including the power supply, is out of operation and the auxiliary services such as compressed air, starting current from batteries etc., for bringing the main propulsion into operation and for the restoration of the main power supply are not available.

## 3.15 Main generating station

**3.15.1** The space in which the main source of electrical power is situated.

## 3.16 Main switchboard

**3.16.1** A switchboard which is directly supplied by the main source of electrical power and is intended to distribute electrical energy to the ship's services.

### 3.17 Emergency switchboard

**3.17.1** A switchboard which in the event of failure of the main electrical power supply system is directly supplied by the emergency source of electrical power or the transitional source of emergency and is intended to distribute electrical energy to the emergency services.

### 3.18 Emergency source of electrical power

**3.18.1** A source of electrical power, intended to supply the emergency switchboard in the event of failure of the supply from the main source of electrical power.

### 3.19 Section boards

**3.19.1** A switchgear and controlgear assembly which is supplied by another assembly and arranged for the distribution of electrical energy to other section boards or distribution boards.

### 3.20 Distribution board

**3.20.1** A switchgear and controlgear assembly arranged for the distribution of electrical energy to final sub-circuits.

### 3.21 Final sub-circuit

**3.21.1** That portion of a wiring system extending beyond the final required overcurrent protective device of a board.

### 3.22 Hazardous areas

**3.22.1** Areas in which an explosive atmosphere is present, or may be expected to be present due to the presence of vapours, gases, flammable dusts or explosives in quantities such as to require special precautions for the construction, installation and use of electrical apparatus.

**3.22.2** Hazardous areas are classified in zones based upon the frequency and the duration of the occurrence of explosive atmosphere.

**3.22.3** Hazardous areas for explosive gas atmosphere are classified in the following zones:

- Zone 0: an area in which an explosive gas atmosphere is present continuously or is present for long periods
- Zone 1: an area in which an explosive gas atmosphere is likely to occur in normal operation
- Zone 2: an area in which an explosive gas atmosphere is not likely to occur in normal operation and if it does occur, is likely to do only infrequently and will exist for a short period only.

### 3.23 Certified safe-type equipment

**3.23.1** Certified safe-type equipment is electrical equipment of a type for which a national or other appropriate authority has carried out the type verifications and tests necessary to certify the safety of the equipment with regard to explosion hazard when used in an explosive gas atmosphere.

## SECTION 2

## GENERAL DESIGN REQUIREMENTS

### 1 Environmental conditions

#### 1.1 General

**1.1.1** The electrical components of installations are to be designed and constructed to operate satisfactorily under the environmental conditions on board.

In particular, the conditions shown in the tables in this Article are to be taken into account.

Note 1: The environmental conditions are characterised by:

- one set of variables including climatic conditions (e.g. ambient air temperature and humidity), biological conditions, conditions dependent upon chemically active substances (e.g. salt mist) or mechanically active substances (e.g. dust or oil), mechanical conditions (e.g. vibrations or inclinations) and conditions dependent upon electromagnetic noise and interference, and
- another set of variables dependent mainly upon location on vessels, operational patterns and transient conditions.

#### 1.2 Ambient air temperatures

**1.2.1** The ambient air temperature ranges shown in Tab 1 apply in relation to the various locations of installation.

**1.2.2** Where electrical equipment is installed within environmentally controlled spaces, the ambient temperature for which the equipment is to be suitable may be reduced from 45° and maintained at a value not less than 35° provided:

- the equipment is not for use for emergency services.
- temperature control is achieved by at least two cooling units so arranged that in the event of loss of one cooling unit, for any reason, the remaining unit(s) is (are) capable of satisfactorily maintaining the design temperature.
- the equipment is able to be initially set to work safely up to a 45° ambient temperature until such time as the lower ambient temperature is achieved; the cooling equipment is to be rated for a 45 ° ambient temperature.
- audible and visual alarms are fitted, at a continually manned control station, to indicate any malfunction of the cooling units.

**1.2.3** In accepting an ambient temperature less than 45° it is to be ensured that electrical cables are adequately rated throughout their length for the maximum ambient temperature to which they are exposed.

**1.2.4** The equipment used for cooling and maintaining the lower ambient temperature is to be classified for essential services not required to be in continuous operation.

**1.2.5** For ships classed for specific services, the Society may accept different ambient air temperature.

**Table 1 : Ambient air temperature**

Location	Temperature range, in °C	
Enclosed spaces	- 15	+ 45
Inside consoles or fitted on combustion engines and similar	- 15	+ 70
Exposed decks	- 35	+ 45

#### 1.3 Humidity

**1.3.1** The humidity ranges shown in Tab 2 apply in relation to the various locations of installation.

**Table 2 : Humidity**

Location	Humidity
General	95% at 55 °C
Air conditioned areas	Different values may be considered on a case by case basis

#### 1.4 Cooling water temperatures

**1.4.1** The temperatures shown in Tab 3 apply.

**1.4.2** For ships classed for specific services, the Society may accept different values for the cooling water temperature.

**Table 3 : Water temperature**

Coolant	Temperature range, in °C	
Sea water	0	+ 32

#### 1.5 Salt mist

**1.5.1** The applicable salt mist content in the air is to be 1 mg/m<sup>3</sup>.

#### 1.6 Inclinations

**1.6.1** The inclinations applicable are those shown in Tab 4.

The Society may consider deviations from these angles of inclination taking into consideration the type, size and service conditions of the ships.

#### 1.7 Vibrations

**1.7.1** In relation to the location of the electrical components, the vibration levels given in Tab 5 are to be assumed. Moreover, the expected shock and vibration levels resulting from icebreaking action are to be withstood.

**1.7.2** The natural frequencies of the equipment, their suspensions and their supports are to be outside the frequency ranges specified.

Where this is not possible using a suitable constructional technique, the equipment vibrations are to be damped so as to avoid unacceptable amplifications.

## 2 Quality of power supply

### 2.1 Voltage and frequency variation

**2.1.1** All electrical appliances supplied from the main or emergency systems are to be so designed and manufactured that they are capable of operating satisfactorily under the normally occurring variations in voltage and frequency.

**2.1.2** Unless otherwise stated in national or international standards, all equipment is to operate satisfactorily with the variations from its rated value shown in Tab 6 to Tab 8 subject to the following conditions.

- a) For alternating current components, the voltage and frequency variations shown in Tab 6 are to be assumed.
- b) For direct current components supplied by d.c. generators or converted by rectifiers, the voltage variations shown in Tab 7 are to be assumed.
- c) For direct current components supplied by electrical batteries, the voltage variations shown in Tab 8 are to be assumed.

**2.1.3** Any special system, e.g. electronic circuits, whose function cannot operate satisfactorily within the limits shown in Tab 6, Tab 7 and Tab 8 is not to be supplied directly from the system but by alternative means, e.g. through stabilised supply.

### 2.2 Harmonic distortions

**2.2.1** For components intended for systems without substantially static converter loads and supplied by synchronous generators, it is assumed that the total voltage harmonic distortion does not exceed 5%, and the single harmonic does not exceed 3% of the nominal voltage.

**2.2.2** For components intended for systems fed by static converters, and/or systems in which the static converter load predominates, it is assumed that:

- the single harmonics do not exceed 5% of the nominal voltage up to the 15th harmonic of the nominal frequency, decreasing to 1% at the 100th harmonic (see Fig 1), and that
- the total harmonic distortion does not exceed 10%.

**Table 4 : Inclination of ship**

Type of machinery, equipment or component	Angles of inclination, in degrees (1)			
	Athwartship		Fore-and-aft	
	static	dynamic (4)	static	dynamic (5)
Machinery and equipment relative to main electrical power installation	15	22,5	5	7,5
Machinery and equipment relative to the emergency power installation and crew and passenger safety systems of the ship (e.g. emergency source of power, emergency fire pumps, etc.)	22,5 (2)	22,5 (2)	10	10
Switchgear and associated electrical and electronic components and remote control systems (3)	22,5	22,5	10	10

(1) Athwartship and fore-and-aft angles may occur simultaneously in their most unfavourable combination.  
 (2) In the case of gas carriers, the emergency power supply must also remain operable with the ship flooded to a final athwartship inclination up to a maximum of 30°.  
 (3) No undesired switching operations or functional changes may occur up to an angle of inclination of 45°.  
 (4) The period of dynamic inclination may be assumed equal to 10 s.  
 (5) The period of dynamic inclination may be assumed equal to 5 s.

Table 5 : Vibration levels

Location	Frequency range Hz	Displacement amplitude mm	Acceleration amplitude g
Machinery spaces, command and control stations, accommodation spaces, exposed decks, cargo spaces	from 2,0 to 13,2 from 13,2 to 100	1,0 -	- 0,7
On air compressors, on diesel engines and similar	from 2,0 to 25,0 from 25,0 to 100	1,6 -	- 4,0
Masts	from 2,0 to 13,2 from 13,2 to 50	3,0 -	- 2,1

Figure 1

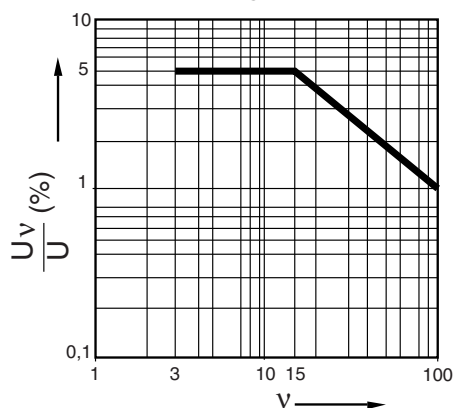


Table 6 : Voltage and frequency variations for a.c. distribution systems

Quantity in operation	Variations	
	Continuous	Transient
Voltage	+ 6% - 10%	± 20% (recovery time: 1,5 s)
Frequency	± 5%	± 10% (recovery time: 5 s)

Table 7 : Voltage variations for d.c. distribution systems

Parameters	Variations
Voltage tolerance (continuous)	± 10%
Voltage cyclic variation deviation	5%
Voltage ripple (a.c. r.m.s. over steady d.c. voltage)	10%

**2.2.3** Higher values for the harmonic content (e.g. in electric propulsion plant systems) may be accepted on the basis of correct operation of all electrical devices.

Table 8 : Voltage variations for battery systems

Systems	Variations
Components connected to the battery during charging (1)	+30%, -25%
Components not connected to the battery during charging	+20%, -25%
(1) Different voltage variations as determined by the charging/discharging characteristics, including ripple voltage from the charging device, may be considered.	

### 3 Electromagnetic susceptibility

#### 3.1

**3.1.1** For electronic type components such as sensors, alarm panels, automatic and remote control equipment, protective devices and speed regulators, the conducted and radiated disturbance levels to be assumed are those given in Chapter 3.

Note 1: See also IEC 60533 - "Electrical and Electronic Installations in Ships - Electromagnetic compatibility".

### 4 Materials

#### 4.1 General

**4.1.1** In general, and unless it is adequately protected, all electrical equipment is to be constructed of durable, flame-retardant, moisture-resistant materials which are not subject to deterioration in the atmosphere and at the temperatures to which they are likely to be exposed. Particular consideration is to be given to sea air and oil vapour contamination.

Note 1: The flame-retardant and moisture-resistant characteristics may be verified by means of the tests cited in IEC 60092-101 or in other recognised standards.

**4.1.2** Where the use of incombustible materials or lining with such materials is required, the incombustibility characteristics may be verified by means of the test cited in IEC 60092-101 or in other recognised standards.



## 4.2 Insulating materials for windings

**4.2.1** Insulated windings are to be resistant to moisture, sea air and oil vapour unless special precautions are taken to protect insulants against such agents.

**4.2.2** The insulation classes given in Tab 9 may be used.

**Table 9 : Insulation Classes**

Class	Maximum continuous operating temperature °C
A	105
E	120
B	130
F	155
H	180

## 4.3 Insulating materials for cables

**4.3.1** See Sec 9, [1.3].

## 5 Construction

### 5.1 General

**5.1.1** All electrical apparatus is to be so constructed as not to cause injury when handled or touched in the normal manner.

**5.1.2** The design of electrical equipment is to allow accessibility to each part that needs inspection or adjustment, also taking into account its arrangement on board.

**5.1.3** Enclosures are to be of adequate mechanical strength and rigidity.

**5.1.4** Enclosures for electrical equipment are generally to be of metal; other materials may be accepted for accessories such as connection boxes, socket-outlets, switches and luminaires. Other exemptions for enclosures or parts of enclosures not made of metal will be specially considered by the Society.

**5.1.5** Cable entrance are not to impair the degree of protection of the relevant enclosure (see Sec 3, Tab 2).

**5.1.6** All nuts and screws used in connection with current-carrying parts and working parts are to be effectively locked.

**5.1.7** All equipment is generally to be provided with suitable, fixed terminal connectors in an accessible position for convenient connection of the external cables.

## 5.2 Degree of protection of enclosures

**5.2.1** Electrical equipment is to be protected against the ingress of foreign bodies and water.

The minimum required degree of protection, in relation to the place of installation, is generally that specified in Sec 3, Tab 2.

**5.2.2** The degrees of protection are to be in accordance with:

- IEC 60529 for equipment in general
- IEC 60034-5 for rotating machines.

## 6 Protection against explosion hazard

### 6.1 Protection against explosive gas or vapour atmosphere hazard

**6.1.1** Electrical equipment intended for use in areas where explosive gas or vapour atmospheres may occur, is to be of a "safe type" suitable for the relevant flammable atmosphere and for shipboard use.

**6.1.2** The following "certified safe type" equipment is considered:

- intrinsically-safe: Ex(ia) - Ex(ib)
- flameproof: Ex(d)
- increased safety: Ex(e)
- pressurised enclosure: Ex(p)
- encapsulated: Ex(m)
- sand filled: Ex(q)
- special protection: Ex(s)
- oil-immersed apparatus (see Note 1): Ex(o)

Note 1: Only when required by the application.

**6.1.3** Other equipment complying with types of protection other than those in [6.1.2] may be considered by the Society, such as:

- simple electrical apparatus and components (e.g. thermocouples, photocells, strain gauges, junction boxes, switching devices), included in intrinsically-safe circuits not capable of storing or generating electrical power or energy in excess of limits stated in the relevant rules
- electrical apparatus specifically designed and certified by the appropriate authority for use in Zone 0 or specially tested for Zone 2 (e.g. type "n" protection)
- equipment the type of which ensures the absence of sparks and arcs and of "hot spots" during its normal operation
- pressurised equipment
- equipment having an enclosure filled with a liquid dielectric, or encapsulated.

## **6.2 Protection against combustible dust hazard**

**6.2.1** Electrical appliances intended for use in areas where a combustible dust hazard may be present are to be arranged with enclosures having a degree of protection and maximum surface temperature suitable for the dust to which they may be exposed.

Note 1: Where the characteristics of the dust are unknown, the appliances are to have a degree of protection IP6X. For most dusts a maximum surface temperature of 200°C is considered adequate.

## SECTION 3

## SYSTEM DESIGN

### 1 Supply systems and characteristics of the supply

#### 1.1 Supply systems

1.1.1 The following distribution systems may be used:

- a) on d.c. installations:
  - two-wire insulated
  - two-wire with one pole earthed
- b) on a.c. installations:
  - three-phase three-wire with neutral insulated
  - three-phase three-wire with neutral directly earthed or earthed through an impedance
  - three-phase four-wire with neutral directly earthed or earthed through an impedance
  - single-phase two-wire insulated
  - single-phase two-wire with one phase earthed.

1.1.2 Distribution systems other than those listed in [1.1.1] (e.g., three-phase four-wire insulated) will be considered by the Society on a case by case basis.

1.1.3 The hull return system of distribution is not to be used for power, heating or lighting.

1.1.4 The requirement of [1.1.3] does not preclude under conditions approved by the Society the use of:

- a) impressed current cathodic protective systems,
- b) limited and locally earthed systems, or
- c) insulation level monitoring devices provided the circulation current does not exceed 30 mA under the most unfavourable conditions.

Note 1: Limited and locally earthed systems such as starting and ignition systems of internal combustion engines are accepted provided that any possible resulting current does not flow directly through any dangerous spaces.

#### 1.2 Maximum voltages

1.2.1 The maximum voltages for both alternating current and direct current low-voltage systems of supply for the ship's services are given in Tab 1.

1.2.2 Voltages exceeding those shown will be specially considered in the case of specific systems.

1.2.3 For high voltage systems reference may be made to IEC 60092-503.

**Table 1 : Maximum voltages for various ship services**

Use		Maximum voltage, in V
For permanently installed and connected to fixed wiring	Power equipment	1000
	Heating equipment (except in accommodation spaces)	500
	Cooking equipment	500
	Lighting	250
	Space heaters in accommodation spaces	250
	Control <b>(1)</b> , communication (including signal lamps) and instrumentation equipment	250
For permanently installed and connected by flexible cable	Power and heating equipment, where such connection is necessary because of the application (e.g. for moveable cranes or other hoisting gear)	1000
For socket-outlets supplying	Portable appliances which are not hand-held during operation by flexible cables	1000
	Portable appliances and other consumers by flexible cables	250
	Equipment requiring extra precaution against electric shock where an isolating transformer is used to supply one appliance <b>(2)</b>	250
	Equipment requiring extra precaution against electric shock with or without a safety transformer <b>(2)</b> .	50
<b>(1)</b> For control equipment which is part of a power and heating installation (e.g. pressure or temperature switches for starting/stopping motors), the same maximum voltage as allowed for the power and heating equipment may be used provided that all components are constructed for such voltage. However, the control voltage to external equipment is not to exceed 500 V. <b>(2)</b> Both conductors in such systems are to be insulated from earth.		

## 2 Sources of electrical power

### 2.1 General

#### 2.1.1 Electrical installations are to be such that:

- a) All electrical auxiliary services necessary for maintaining the ship in normal operational and habitable conditions will be assured without recourse to the emergency source of electrical power.
- b) Electrical services essential for safety will be assured under various emergency conditions.
- c) When a.c. generators are involved, attention is to be given to the starting of squirrel-cage motors connected to the system, particularly with regard to the effect of the magnitude and duration of the transient voltage change produced due to the maximum starting current and the power factor. The voltage drop due to such starting current is not to cause any motor already operating to stall or have any adverse effect on other equipment in use.

### 2.2 Main source of electrical power

**2.2.1** A main source of electrical power is to be provided, of sufficient capability to supply all electrical auxiliary services necessary for maintaining the ship in normal operational and habitable conditions and for the preservation of the cargo without recourse to the emergency source of electrical power.

**2.2.2** For units propelled by electrical power and having two or more constant voltage propulsion generating sets which constitute the source of electrical energy for the ship's auxiliary services, see Sec 14.

**2.2.3** The main source of electrical power is to consist of at least two generating sets.

The capacity of these generating sets is to be such that in the event of any one generating set being stopped it will still be possible to supply those services necessary to provide:

- a) normal operational conditions of propulsion and safety (see [2.2.4])
- b) minimum comfortable safe conditions of habitability (see Sec 1, [3.2.4])
- c) preservation of the cargo.

Such capacity is, in addition, to be sufficient to start the largest motor without causing any other motor to stop or having any adverse effect on other equipment in operation.

**2.2.4** Those services necessary to provide normal operational conditions of propulsion and safety include all essential services.

For the purpose of calculating the capacity necessary for such services, it is essential to consider which of them can be expected to be in use simultaneously.

For a duplicated service, one being supplied electrically and the other non-electrically (e.g. driven by the main

engine), the electrical capacity is not included in the above calculation.

**2.2.5** The services in [2.2.4] do not include:

- thrusters not forming part of the main propulsion
- cargo handling gear
- cargo pumps
- refrigerators for air conditioning.

**2.2.6** Further to the provisions above, the generating sets are to be such as to ensure that with any one generator or its primary source of power out of operation, the remaining generating sets are to be capable of providing the electrical services necessary to start the main propulsion plant from a "dead ship" condition.

**2.2.7** The arrangement of the ship's main source of electrical power is to be such that essential services can be maintained regardless of the speed and direction of rotation of the main propulsion machinery or shafting.

**2.2.8** Generators driven by the propulsion plant (shaft generators) which are intended to operate at constant speed (e.g. a system where vessel speed and direction are controlled by varying propeller pitch) may be accepted as forming part of the main source of electrical power if, in all sailing and manoeuvring conditions including the propeller being stopped, the capacity of these generators is sufficient to provide the electrical power to comply with [2.2.3] and all further requirements, especially those of [2.2.6]. They are to be not less effective and reliable than the independent generating sets.

**2.2.9** Generators and generator systems, having the ship's propulsion machinery as their prime mover but not forming part of the ship's main source of electrical power (see Note 1) may be used whilst the ship is at sea to supply electrical services required for normal operational and habitable conditions, provided that:

- a) there are sufficient and adequately rated additional generators fitted, which constitute the main source of electrical power required by [2.2.1], meeting the provisions of [2.2.7]
- b) arrangements are fitted to automatically start one or more of the generators constituting the main source of electrical power required by [2.2.1], in compliance with [3.3.5] and also in the event of frequency variations exceeding  $\pm 10\%$  of the limits specified below
- c) within the declared operating range of the generators and/or generator systems, the specified limits for the voltage variations in IEC 60092-301 (see Note 3) and the frequency variations in Sec 2, Tab 6 can be met
- d) the short-circuit current of the generator and/or generator system is sufficient to trip the generator/generator system circuit-breaker taking into account the selectivity of the protective devices for the distribution system
- e) where considered appropriate, load shedding arrangements are fitted to meet the requirements of [3.3.6], [3.3.7] and [3.4.8]

- f) on ships having remote control of the propulsion machinery from the navigating bridge, means are provided or procedures are in place so as to ensure that supplies to essential services are maintained during manoeuvring conditions in order to avoid a blackout situation (see Note 4).

Note 1: Such generator systems are those whose operation does not meet the requirements of IEC 60092-201, paragraph 6.2.3.

Note 2: IEC 60092-201 Electrical installations in ships - part 201: System design - General

Note 3: IEC 60092-301 Electrical installations in ships - part 301: Equipment - Generators and motors.

Note 4: A 'blackout situation' means that the main and auxiliary machinery installations, including the main power supply, are out of operation but the services for bringing them into operation (e.g. compressed air, starting current from batteries etc.) are available.

**2.2.10** Where transformers, converters or similar appliances constitute an essential part of the electrical supply system, the system is to be so arranged as to ensure the same continuity of supply as stated in this sub-article [2.2].

This may be achieved by arranging at least two three-phase or three single-phase transformers supplied, protected and installed as indicated in Fig 1, so that with any one transformer not in operation, the remaining transformer(s) is (are) sufficient to ensure the supply to the services stated in [2.2.3].

Each transformer required is to be located as a separate unit with separate enclosure or equivalent, and is to be served by separate circuits on the primary and secondary sides. Each of the primary circuits is to be provided with switchgears and protection devices in each phase. Each of the secondary circuits is to be provided with a multiple isolating switch.

Suitable interlocks or a warning label are to be provided in order to prevent maintenance or repair of one single-phase transformer unless both switchgears are opened on their primary and secondary sides.

**2.2.11** For ships intended for operation with periodically unattended machinery spaces, see Part F, Chapter 2.

**2.2.12** For starting arrangements for main generating sets, see Ch 1, Sec 2, [3.1].

## **2.3 Emergency source of electrical power**

**2.3.1** A self-contained emergency source of electrical power is to be provided.

**2.3.2** Provided that suitable measures are taken for safeguarding independent emergency operation under all circumstances, the emergency generator may be used, exceptionally, and for short periods, to supply non-emergency circuits.

Exceptionally is understood to mean conditions, while the vessel is at sea, such as:

- a) blackout situation
- b) dead ship situation
- c) routine use for testing
- d) short-term parallel operation with the main source of electrical power for the purpose of load transfer.

**2.3.3** The electrical power available is to be sufficient to supply all those services that are essential for safety in an emergency, due regard being paid to such services as may have to be operated simultaneously.

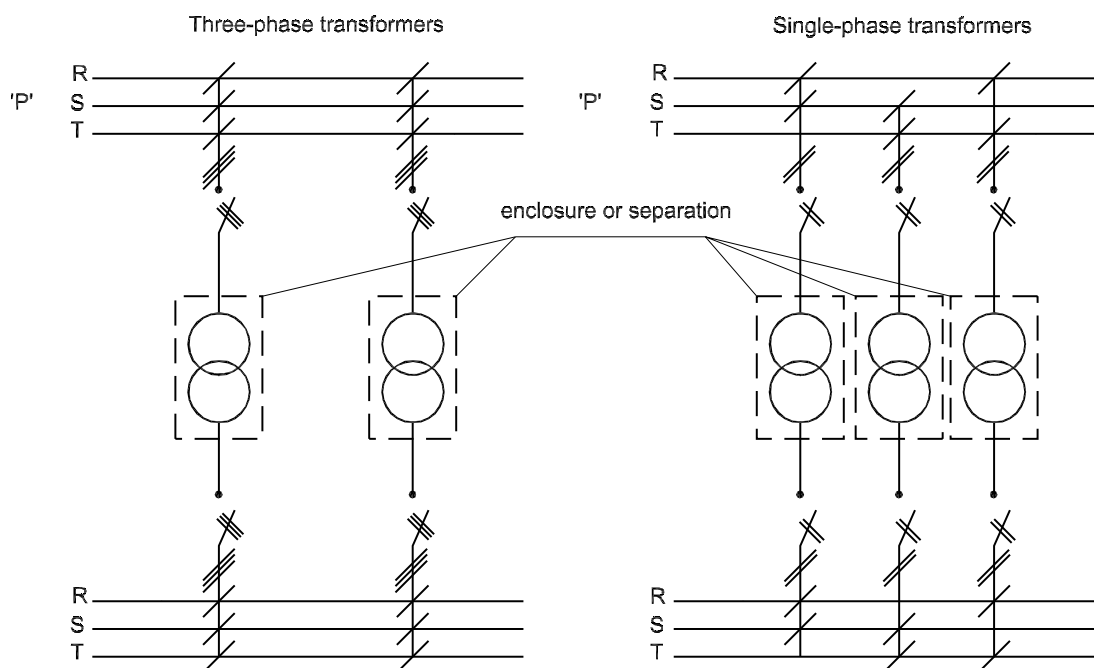
**2.3.4** The emergency source of electrical power is to be capable, having regard to starting currents and the transitory nature of certain loads, of supplying simultaneously at least the services stated in [3.5.3] for the period specified, if they depend upon an electrical source for their operation.

**2.3.5** The transitional source of emergency electrical power, where required, is to be of sufficient capacity to supply at least the services stated in [3.5.6] for half an hour, if they depend upon an electrical source for their operation.

**2.3.6** An indicator is to be mounted in a suitable place on the main switchboard or in the machinery control room to indicate when the batteries constituting either the emergency source of electrical power or the transitional source of emergency electrical power referred to in [2.3.13] and [2.3.14] are being discharged.

**2.3.7** If the services which are to be supplied by the transitional source receive power from an accumulator battery by means of semiconductor converters, means are to be provided for supplying such services also in the event of failure of the converter (e.g. providing a bypass feeder or a duplication of converter).

Figure 1



**2.3.8** Where electrical power is necessary to restore propulsion, the capacity of the emergency source is to be sufficient to restore propulsion to the ship in conjunction to other machinery as appropriate, from a dead ship condition within 30 min. after blackout.

For the purpose of this requirement only, the dead ship condition and blackout are both understood to mean a condition under which the main propulsion plant, boilers and auxiliaries are not in operation and in restoring the propulsion, no stored energy for starting the propulsion plant, the main source of electrical power and other essential auxiliaries is to be assumed available. It is assumed that means are available to start the emergency generator at all times.

The emergency generator and other means needed to restore the propulsion are to have a capacity such that the necessary propulsion starting energy is available within 30 minutes of blackout/dead ship condition as defined above. Emergency generator stored starting energy is not to be directly used for starting the propulsion plant, the main source of electrical power and/or other essential auxiliaries (emergency generator excluded).

**2.3.9** Provision is to be made for the periodic testing of the complete emergency system and shall include the testing of automatic starting arrangements, where provided.

**2.3.10** For starting arrangements for emergency generating sets, see Ch 1, Sec 2, [3.1].

**2.3.11** The emergency source of electrical power may be either a generator or an accumulator battery which is to be complied with the requirements of [2.3.12] or [2.3.13], respectively.

**2.3.12** Where the emergency source of electrical power is a generator, it is to be:

- driven by a suitable prime mover with an independent supply of fuel, having a flashpoint (closed cup test) of not less than 43°C;
- started automatically upon failure of the main source of electrical power supply to the emergency switchboard unless a transitional source of emergency electrical power in accordance with (c) below is provided; where the emergency generator is automatically started, it shall be automatically connected to the emergency switchboard; those services referred to in [3.5.6] shall then be connected automatically to the emergency generator; and
- provided with a transitional source of emergency electrical power as specified in [2.3.14] unless an emergency generator is provided capable both of supplying the services mentioned in that paragraph and of being automatically started and supplying the required load as quickly as is safe and practicable subject to a maximum of 45 s.

**2.3.13** Where the emergency source of electrical power is an accumulator battery it shall be capable of

- carrying the emergency electrical load without recharging while maintaining the voltage of the battery throughout the discharge period within 12% above or below its nominal voltage;
- automatically connecting to the emergency switchboard in the event of failure of the main source of electrical power; and
- immediately supplying at least those services specified in [3.5.6].

**2.3.14** The transitional source of emergency electrical power where required by [2.3.12] (item c) shall consist of an accumulator battery which shall operate without recharging while maintaining the voltage of the battery throughout the discharge period within 12% above or below its nominal voltage and be so arranged as to supply automatically in the event of failure of either the main or the emergency source of electrical power for half an hour at least the services in [3.5.6] if they depend upon an electrical source for their operation.

**2.3.15** The accumulator batteries are to be provided with a means for their protection against low temperature.

### **3 Distribution**

#### **3.1 Earthed distribution systems**

**3.1.1** System earthing is to be effected by means independent of any earthing arrangements of the non-current-carrying parts.

**3.1.2** Means of disconnection are to be fitted in the neutral earthing connection of each generator so that the generator may be disconnected for maintenance or insulation resistance measurements.

**3.1.3** Generator neutrals may be connected in common, provided that the third harmonic content of the voltage wave form of each generator does not exceed 5%.

**3.1.4** Where a switchboard is split into sections operated independently or where there are separate switchboards, neutral earthing is to be provided for each section or for each switchboard. Means are to be provided to ensure that the earth connection is not removed when generators are isolated.

**3.1.5** Where for final sub-circuits it is necessary to locally connect a pole (or phase) of the sub-circuits to earth after the protective devices (e.g. in automation systems or to avoid electromagnetic disturbances), provision (e.g. d.c./d.c. convertors or transformers) is to be made such that current unbalances do not occur in the individual poles or phases.

#### **3.2 Insulated distribution systems**

**3.2.1** Every insulated distribution system, whether primary or secondary (see Note 1), for power, heating or lighting, shall be provided with a device capable of continuously monitoring the insulation level to earth (i.e. the values of electrical insulation to earth) and of giving an audible and visual indication of abnormally low insulation values (see Sec 15).

Note 1: A primary system is one supplied directly by generators. Secondary systems are those supplied by transformers or convertors.

#### **3.3 General requirements for distribution systems**

**3.3.1** The distribution system is to be such that the failure of any single circuit will not endanger or impair essential services that are to be in continuous operation and will not render the other essential services inoperative for longer periods.

**3.3.2** No common switchgear (e.g. contactors for emergency stop) is to be used between the switchboard's busbars and two non duplicated essential services required to be in continuous operation.

**3.3.3** Where the main source of electrical power is necessary for propulsion and steering of the ship, the system shall be so arranged that the electrical supply to equipment necessary for propulsion and steering and to ensure safety of the ship will be maintained or immediately restored in the case of loss of any one of the generators in service.

**3.3.4** Where the electrical power is normally supplied by more than one generator set simultaneously in parallel operation, provision of protection are to be made to ensure that, in case of loss of any of these generating sets, the remaining ones are kept in operation to permit propulsion and steering and to ensure safety. These provisions include automatic disconnection of sufficient non-essential services, those provided for habitability and if necessary those essential services not intended to support propulsion and steering.

**3.3.5** Where the electrical power is normally supplied by one generator, provision are to be made, upon loss of power, for automatic starting and connecting to the main switchboard of stand-by generator(s) of sufficient capacity with automatic restarting of the essential auxiliaries, in sequential operation if required. Starting and connection to the main switchboard of one generator is to be as rapid as possible, preferably within 30 seconds after loss of power.

Where prime movers with longer starting time are used, this starting and connection time may be exceeded upon approval from the Society.

**3.3.6** Load shedding or other equivalent arrangements are to be provided to protect the generators against sustained overload.

**3.3.7** The load shedding is to be automatic.

#### **3.4 Main distribution of electrical power**

**3.4.1** Where the main source of electrical power is necessary for propulsion of the ship, the main busbar is to be divided into at least two parts which are normally to be connected by circuit breakers or other approved means such as circuit breakers without tripping mechanisms or disconnecting links or switches by means of which busbars can be split safely and easily.

The connection of generating sets and associated auxiliaries and other duplicated equipment is to be equally divided between the parts as far as practicable, so that in the event of damage to one section of the switchboard the remaining parts are still supplied.

**3.4.2** Two or more units serving the same consumer (e.g. main and standby lubricating oil pumps) are to be supplied by individual separate circuits without the use of common feeders, protective devices or control circuits.

This requirement is satisfied when such units are supplied by separate cables from the main switchboard or from two independent section boards.

**3.4.3** A main electric lighting system which shall provide illumination throughout those parts of the ship normally accessible to and used by (passengers or) crew shall be supplied from the main source of electrical power.

**3.4.4** Precautions should be taken to minimize risk of supplies to essential and emergency services being interrupted by the inadvertent or accidental opening of switches or circuit breakers due to vibrations or accelerations during ice-breaking operations.

### 3.5 Emergency distribution of electrical power

**3.5.1** The emergency switchboard shall be supplied during normal operation from the main switchboard by an interconnector feeder which shall be adequately protected at the main switchboard against overload and short-circuit and which is to be disconnected automatically at the emergency switchboard upon failure of the main source of electrical power

Where the system is arranged for feedback operation, the interconnector feeder is also to be protected at the emergency switchboard at least against short-circuit.

**3.5.2** In order to ensure ready availability of the emergency source of electrical power, arrangements shall be made where necessary to disconnect automatically non-emergency circuits from the emergency switchboard to ensure that power shall be available to the emergency circuits.

Precautions should be taken to minimize risk of supplies to essential and emergency services being interrupted by the inadvertent or accidental opening of switches or circuit breakers due to vibrations or accelerations during icebreaking operations.

**3.5.3** The emergency source of electrical power shall be capable of supplying simultaneously at least the following services for the periods specified hereafter, if they depend upon an electrical source for their operation:

a) for a period of 3 hours, emergency lighting at every muster and embarkation station and over the sides;

- b) for a period of 18 hours, emergency lighting:
- 1) in all service and accommodation alleyways, stairways and exits, personnel lift cars and personnel lift trunks;
  - 2) in the machinery spaces and main generating stations including their control positions;
  - 3) in all control stations, machinery control rooms, and at each main and emergency switchboard;
  - 4) at all stowage positions for firemen's outfits;
  - 5) at the steering gear;
  - 6) at the fire pump referred to in (e) below, at the sprinkler pump, if any, at the emergency bilge pump, if any, and at the starting positions of their motors; and
  - 7) in all cargo pump-rooms of tanker
- c) for a period of 18 hours:
- 1) the navigation lights and other lights required by the International Regulations for Preventing Collisions at Sea in force;
  - 2) on ships constructed on or after 1 February 1995 the VHF radio installation required by Regulation IV/7.1.1 and IV/7.1.2 of SOLAS Consolidated Edition 1992, and, if applicable:
    - the MF radio installation required by Regulations IV/9.1.1, IV/9.1.2, IV/10.1.2 and IV/10.1.3;
    - the ship earth station required by Regulation IV/10.1.1; and
    - the MF/HF radio installation required by Regulations IV/10.2.1, IV/10.2.2 and IV/11.1;
- d) for a period of 18 hours:
- 1) all internal communication equipment as required in an emergency [3.5.4];
  - 2) the shipborne navigational equipment as required by Regulation V/12; where such provision is unreasonable or impracticable the Society may waive this requirement for ships of less than 5 000 tons gross tonnage;
  - 3) the fire detection and fire alarm systems (see Sec 1, [1.1.2]); and
  - 4) intermittent operation of the daylight signalling lamp, the ship's whistle, the manually operated call points and all internal signals (see [3.5.5]) that are required in an emergency, unless such services have an independent supply for the period of 18 hours from an accumulator battery suitably located for use in an emergency;
- e) for a period of 18 hours: one of the fire pumps, when required, if dependent upon the emergency generator for its source of power (see Sec 1, [1.1.2]);
- f) for the period of time required in Ch 1, Sec 11, [2], the steering gear where it is required to be so supplied.

**3.5.4** Internal communication equipment required in an emergency generally includes:

a) the means of communication between the navigating bridge and the steering gear compartment



- b) the means of communication between the navigating bridge and the position in the machinery space or control room from which the engines are normally controlled
- c) the public address system (see Sec 1, [1.1.2]).

**3.5.5** Internal signals required in an emergency generally include:

- a) general alarm (see Sec 1, [1.1.2])
- b) watertight door indication.

**3.5.6** The transitional source of emergency electrical power, where required, shall supply for half an hour at least the following services if they depend upon an electrical source for their operation:

- a) the lighting required by [3.5.3](item a, b, c1); for this transitional phase, the required emergency electric lighting, in respect of the machinery space and the accommodation and service spaces may be provided by permanently fixed, individual, automatically charged, relay operated accumulator lamps; and
- b) all services required by [3.5.3] (item d1, d3, d4) unless such services have an independent supply for the period specified from an accumulator battery suitably located for use in an emergency.

### **3.6 Shore supply**

**3.6.1** Where arrangements are made for supplying the electrical installation from a source on shore or elsewhere, a suitable connection box is to be installed on the ship in a convenient location to receive the flexible cable from the external source.

**3.6.2** Permanently fixed cables of adequate rating are to be provided for connecting the box to the main switchboard or emergency switchboard.

**3.6.3** Where necessary for systems with earthed neutrals, the box is to be provided with an earthed terminal for connection between the shore's and ship's neutrals or for connection of a protective conductor.

**3.6.4** The connection box is to contain a circuit-breaker or a switch-disconnector and fuses.

The shore connection is to be protected against short-circuit and overload; however, the overload protection may be omitted in the connection box if provided on the main or emergency switchboard.

**3.6.5** Means are to be provided for checking the phase sequence of the incoming supply in relation to the ship's system.

**3.6.6** The cable connection to the box is to be provided with at least one switch-disconnector on the main or emergency switchboard.

**3.6.7** The shore connection is to be provided with an indicator at the main or emergency switchboard in order to show when the cable is energised.

**3.6.8** At the connection box a notice is to be provided giving full information on the nominal voltage and frequency of the installation.

**3.6.9** The switch-disconnector on the main or emergency switchboard is to be interlocked with the generator circuit-breakers in order to prevent its closure when any generator is supplying the main or emergency switchboard unless special provisions to the satisfaction of the Society are taken to permit safe transfer of electrical load.

**3.6.10** Adequate means are to be provided to equalise the potential between the hull and the shore when the electrical installation of the ship is supplied from shore.

### **3.7 Supply of motors**

**3.7.1** A separate final sub-circuit is to be provided for every motor required for an essential service (and for every motor rated at 1 kW or more).

**3.7.2** Each motor is to be provided with controlgear ensuring its satisfactory starting.

Depending on the capacity of the generating plant or the cable network, it may be necessary to limit the starting current to an acceptable value.

Direct on line starters are accepted if the voltage drop does not exceed 15% of the network voltage.

**3.7.3** Efficient means are to be provided for the isolation of the motor and its associated control gear from all live poles of the supply.

Where the control gear is mounted on or adjacent to a switchboard, a disconnecting switch in the switchboard may be used for this purpose.

Otherwise, a disconnecting switch within the control gear enclosure or a separate enclosed disconnecting switch is to be provided.

**3.7.4** Where the starter or any other apparatus for disconnecting the motor is remote from the motor itself, one of the following is to be arranged:

- a) provision for locking the circuit disconnecting switch in the OFF position
- b) an additional disconnecting switch fitted near the motor
- c) provision such that the fuses in each live pole or phase can be readily removed and retained by persons authorised to have access to the motor.

### 3.8 Specific requirements for special power services

**3.8.1** For the supply and characteristics of the distribution of the following services see the requirements listed:

- Steering gear: Ch 1, Sec 11, [2]
- Fire-extinguishing and detecting systems: Ch 4, Sec 1, [6]
- Permanently installed submergible bilge pump: Ch 1, Sec 10, [6.7.7]
- Ventilation fans: Chapter 4
- Fuel pumps: Ch 1, Sec 10
- Pumps discharging overboard above the lightest water line and in way of the area of lifeboat and liferaft launching: Ch 1, Sec 10, [5.2.4].

**3.8.2** Distribution switchboards for de-icing equipment are to be provided with indication of the device in service.

### 3.9 Power supply to heaters

**3.9.1** Each heater rated more than 16A is to be connected to a separate final circuit.

### 3.10 Power supply to lighting installations

**3.10.1** Final sub-circuits for lighting supplying more than one lighting point and for socket-outlets are to be fitted with protective devices having a current rating not exceeding 16 A.

### 3.11 Special lighting services

**3.11.1** In spaces such as:

- main and large machinery spaces
- large galleys
- passageways
- stairways leading to boat-decks
- public spaces

there is to be more than one final sub-circuit for lighting such that failure of any one circuit does not reduce the lighting to an insufficient level.

**3.11.2** Where the emergency installation is required, one of the circuits in [3.11.1] may be supplied from the emergency source of power.

### 3.12 Navigation lights

**3.12.1** Navigation lights are to be connected separately to a distribution board specially reserved for this purpose.

Signalling lights may be connected to the navigation light distribution board, or to a separate distribution board.

**3.12.2** The navigation light distribution board is to be supplied from two alternative circuits, one from the main source of power and one from the emergency source of power; see also [3.5].

The transfer of supply is to be practicable from the bridge, for example by means of a switch.

**3.12.3** Each navigation light is to be controlled and protected in each insulated pole by a double-pole switch and a fuse or, alternatively, by a double-pole circuit-breaker, fitted on the distribution board referred to in [3.12.1].

**3.12.4** Where there are double navigation lights, i.e. lights with two lamps or where for every navigation light a spare is also fitted, the connections to such lights may run in a single cable provided that means are foreseen in the distribution board to ensure that only one lamp or light may be supplied at any one time.

**3.12.5** Each navigation light is to be provided with an automatic indicator giving audible and/or visual warning in the event of failure of the light. If an audible device alone is fitted, it is to be connected to a separate source of supply from that of the navigation lights, for example an accumulator (storage) battery.

If a visual signal is used connected in series with the navigation light, means are to be provided to prevent the extinction of the navigation light due to the failure of the visual signal.

A minimum level of visibility is to be assured in the case of use of dimmer devices.

### 3.13 General emergency alarm system

**3.13.1** For the application of this item [3.13], see Sec 1, [1.1.2].

**3.13.2** An electrically operated bell or klaxon or other equivalent warning system installed in addition to the ship's whistle or siren, for sounding the general emergency alarm signal, is to comply with the requirements of this sub-article.

**3.13.3** The general emergency alarm system is to be supplemented by either a public address system complying with the requirements in [3.14] or other suitable means of communication.

**3.13.4** Entertainment sound system is to be automatically turned off when the general alarm system is activated.

**3.13.5** The system is to be continuously powered from the ship's main supply and from the emergency source of electrical power required by [2.3] and [3.6].

**3.13.6** The system is to be capable of operation from the navigation bridge and, except for the ship's whistle, also from other strategic points.

Note 1: Other strategic points are taken to mean those locations, other than the navigation bridge, from where emergency situations are intended to be controlled and the general alarm system can be activated.

**3.13.7** The alarm is to continue to function after it has been triggered until it is manually turned off or is temporarily interrupted by a message on the public address system.

**3.13.8** The alarm system is to be audible throughout all the accommodation and normal crew working spaces.

**3.13.9** In cabins without a loudspeaker installation, an electronic alarm transducer, e.g. a buzzer or similar, is to be installed.

**3.13.10** For cables used for the general emergency alarm system, see [8.6].

### **3.14 Public address system**

**3.14.1** For the application of this item [3.14], see Sec 1, [1.1.2].

**3.14.2** The public address system is to be a loudspeaker installation enabling the broadcast of messages into all spaces where people on board are normally present.

In spaces such as under deck passageways, bosun's locker, hospital and pump rooms, the public address system is/may not be required.

**3.14.3** Where the public address system is used to supplement the general emergency alarm system as per [3.13.3], it is to be continuously powered from the emergency source of electrical power required by [3.5].

**3.14.4** The system is to allow for the broadcast of messages from the navigation bridge and from other places on board the ship as deemed necessary.

**3.14.5** The system is to be protected against unauthorised use.

**3.14.6** The system is to be installed with regard to acoustically marginal conditions and not require any action from the addressee.

**3.14.7** Where an individual loudspeaker has a device for local silencing, an override arrangement from the control station(s), including the navigating bridge, is to be in place.

### **3.15 Combined general emergency alarm - public address system**

**3.15.1** For the application of this item [3.15], see Sec 1, [1.1.2].

**3.15.2** Where the public address system is the only means for sounding the general emergency alarm signal and the fire alarm, in addition to the requirements of [3.13] and [3.14], the following are to be satisfied:

- the system automatically overrides any other input system when an emergency alarm is required
- the system automatically overrides any volume control provided to give the required output for the emergency mode when an emergency alarm is required
- the system is arranged to prevent feedback or other interference
- the system is arranged to minimise the effect of a single failure so that the alarm signal is still audible (above

ambient noise levels) also in the case of failure of any one circuit or component, by means of the use of:

- multiple amplifiers
- segregated cable routes to public rooms, alleyways, stairways and control stations
- more than one device for generating electronic sound signal
- electrical protection for individual loudspeakers against short-circuits.

### **3.16 Control and indication circuits**

**3.16.1** For the supply of automation systems, comprising control, alarm and safety system, see the requirements of Chapter 3.

**3.16.2** Control and indicating circuits relative to essential services are to be branched off from the main circuit in which the relevant equipment is installed. Equivalent arrangements may be accepted by the Society.

### **3.17 Power supply to the speed control systems of main propulsion engines**

**3.17.1** Electrically operated speed control systems of main engines are to be fed from the main source of electrical power.

**3.17.2** Where more than one main propulsion engine is foreseen, each speed control system is to be provided with an individual supply by means of separate wiring from the main switchboard or from two independent section boards.

Where the main busbars are divided into two sections, the governors are, as far as practicable, to be supplied equally from the two sections.

**3.17.3** In the case of propulsion engines which do not depend for their operation on electrical power, i.e. pumps driven from the main engine, the speed control systems are to be fed both from the main source of electrical power and from an accumulator battery for at least 15 minutes or from a similar supply source.

Such battery may also be used for other services such as automation systems, where foreseen.

### **3.18 Power supply to the speed control systems of generator sets**

**3.18.1** Each electrically operated control and/or speed control system of generator sets is to be provided with a separate supply from the main source of electric power and from an accumulator battery for at least 15 minutes or from a similar supply source.

**3.18.2** The wiring supplying the main source of electrical power is to be from the main switchboard or from independent section boards.

Where the main busbars are divided into two sections, the governors are, as far as practicable, to be supplied from the sections to which the relevant generators are connected.

## 4 Degrees of protection of the enclosures

### 4.1 General

**4.1.1** The minimum required degree of protection for electrical equipment, in relation to the place of installation, is generally that specified in Tab 2.

**4.1.2** Equipment supplied at nominal voltages in excess of 500 V and accessible to non-authorized personnel (e.g. equipment not located in machinery spaces or in locked compartments under the responsibility of the ship's officers) is to have a degree of protection against touching live parts of at least IP4X.

**4.1.3** In addition to the requirements of this sub-article, equipment installed in spaces with an explosion hazard is also subject to the provisions of Sec 2, [6].

**4.1.4** The enclosures of electrical equipment for the monitoring and control of watertight doors which are situated below the bulkhead deck are to provide suitable protection against the ingress of water.

In particular, the minimum required degree of protection is to be:

- IPX7 for electric motors, associated circuits and control components
- IPX8 for door position indicators and associated circuit components
- IPX6 for door movement warning signals.

Note 1: The water pressure testing of the enclosures protected to IPX8 is to be based on the pressure that may occur at the location of the component during flooding for a period of 36 hours.

**Table 2 : Minimum required degrees of protection**

Condition in location	Example of location	Switchboard Control gear Motor start- ers	Gener- ators	Motors	Trans- formers	Lumi- naires	Heating appli- ances	Cook- ing appli- ances	Socket outlets	Accessories (e.g. switches, connection boxes)
Danger of touch- ing live parts only	Dry accommoda- tion spaces Dry control rooms	IP 20	X (1)	IP 20	IP 20	IP 20	IP20	IP 20	IP 20	IP 20
Danger of drip- ping liquid and/or moderate mechanical damage	Control rooms, wheel-house, radio room	IP 22	X	IP 22	IP 22	IP 22	IP22	IP 22	IP 22	IP 22
	Engine and boiler rooms above floor	IP 22	IP 22	IP 22	IP 22	IP 22	IP22	IP 22	IP 44	IP 44
	Steering gear rooms	IP 22	IP 22	IP 22	IP 22	IP 22	IP22	X	IP 44	IP 44
	Emergency machinery rooms	IP 22	IP 22	IP 22	IP 22	IP 22	IP22	X	IP 44	IP 44
	General store- rooms	IP 22	X	IP 22	IP 22	IP 22	IP22	X	IP 22	IP 44
	Pantries	IP 22	X	IP 22	IP 22	IP 22	IP22	IP 22	IP 44	IP 44
	Provision rooms	IP 22	X	IP 22	IP 22	IP 22	IP22	X	IP 44	IP 44
	Ventilation ducts	X	X	IP 22	X	X	X	X	X	X
Increased dan- ger of liquid and/or mechani- cal damage	Bathrooms and/or showers	X	X	X	X	IP 34	IP44	X	IP 55	IP 55
	Engine and boiler rooms below floor	X	X	IP 44	X	IP 34	IP44	X	X	IP 55
	Closed fuel oil separator rooms	IP 44	X	IP 44	IP 44	IP 34	IP44	X	X	IP 55
	Closed lubricat- ing oil separator rooms	IP 44	X	IP 44	IP 44	IP 34	IP44	X	X	IP 55

Condition in location	Example of location	Switchboard Control gear Motor starters	Generators	Motors	Transformers	Luminaires	Heating appliances	Cooking appliances	Socket outlets	Accessories (e.g. switches, connection boxes)
Increased danger of liquid and mechanical damage	Ballast pump rooms	IP 44	X	IP 44 (2)	IP 44 (2)	IP 34	IP 44	X	IP 55	IP 55
	Refrigerated rooms	X	X	IP 44	X	IP 34	IP 44	X	IP 55	IP 55
	Galleys and laundries	IP 44	X	IP 44	IP 44	IP 34	IP 44	IP 44	IP 44	IP 44
	Public bathrooms and shower	X	X	IP 44	IP 44	IP 34	IP 44	X	IP 44	IP 44
Danger of liquid spraying. Presence of cargo dust. Serious mechanical damage. Aggressive fumes	Shaft or pipe tunnels in double bottom	IP 55	X	IP 55	IP 55	IP 55	IP 55	X	IP 56	IP 56
	Holds for general cargo	X	X	IP 55	X	IP 55	IP 55	X	IP 56	IP 56
	Ventilation trunks	X	X	IP 55	X	X	X	X	X	X
Danger of liquid in massive quantities	Open decks	IP 56	X	IP 56	X	IP 55	IP 56	X	IP 56	IP 56
<p>(1) The symbol "X" denotes equipment which it is not advised to install.</p> <p>(2) Electric motors and starting transformers for lateral thrust propellers located in spaces similar to ballast pump rooms may have degree of protection IP22.</p>										

4.1.5 For electrical and electronic equipment installed in engine rooms protected by fixed water-based local application fire-fighting systems, see Ch 4, Sec 1, [7] .

## 5 Diversity (demand) factors

### 5.1 General

5.1.1 The cables and protective devices of final sub-circuits are to be rated in accordance with their connected load.

5.1.2 Circuits supplying two or more final sub-circuits are to be rated in accordance with the total connected load subject, where justifiable, to the application of a diversity (demand) factor.

5.1.3 A diversity (demand) factor may be applied provided that the known or anticipated operating conditions in a particular part of an installation are suitable for the application of diversity.

5.1.4 In the evaluation of the electric load analysis, the power required by the heating arrangements is to be considered as follows:

- 100% of electric power needed for anti-icing and anti-freezing purposes
- 50% of electric power needed for de-icing purposes.

These consumers are to be regarded as essential services.

## 6 Electrical protection

### 6.1 General requirements for overcurrent protection

6.1.1 Electrical installations are to be protected against accidental overcurrents including short-circuit.

The choice, arrangement and performance of the various protective devices are to provide complete and coordinated automatic protection in order to ensure as far as possible:

- continuity of service in the event of a fault, through coordinated and discriminative action of the protective devices
- elimination of the effects of faults to reduce damage to the system and the hazard of fire as far as possible.

Note 1: An overcurrent is a current exceeding the nominal current.

Note 2: A short-circuit is the accidental connection by a relatively low resistance or impedance of two or more points in a circuit which are normally at different voltages.

6.1.2 Devices provided for overcurrent protection are to be chosen according to the requirements, especially with regard to overload and short-circuit.

Note 1: Overload is an operating condition in an electrically undamaged circuit which causes an overcurrent.

6.1.3 Systems are to be such as to withstand the thermal and electrodynamic stresses caused by the possible overcurrent, including short-circuit, for the admissible duration.

## 6.2 Short-circuit currents

**6.2.1** In calculating the maximum prospective short-circuit current, the source of current is to include the maximum number of generators which can be simultaneously connected (as far as permitted by any interlocking arrangements), and the maximum number of motors which are normally simultaneously connected in the system.

The maximum number of generators or transformers is to be evaluated without taking into consideration short-term parallel operation (e.g. for load transfer) provided that suitable interlock is foreseen.

**6.2.2** Short-circuit current calculations are to be performed in accordance with a method recognised by the Society, such as that given in IEC 60363.

**6.2.3** In the absence of precise data concerning the characteristics of generators, accumulator batteries and motors, the maximum short-circuit currents on the main busbars may be calculated as follows:

- for alternating current systems:

$$I_{ac} = 10 I_{TG} + 3,5 I_{TM}$$

$$I_{pk} = 2,4 I_{ac}$$

- for direct current systems supplied by batteries:

$$I_p = K C_{10} + 6 I_{TM}$$

where:

$I_p$	: Maximum short-circuit current
$I_{ac}$	: r.m.s. value of the symmetrical component (at the instant T/2)
$I_{pk}$	: Maximum peak value
$I_{TG}$	: Rated current of all generators which can be connected simultaneously
$C_{10}$	: Battery capacity in Ah for a discharge duration of 10 hours
$K$	: Ratio of the short-circuit current of the batteries to $C_{10}$ ; (see Note 1)
$I_{TM}$	: Rated current of all motors which are normally simultaneously connected in the system.

Note 1: For stationary batteries the following values may be assumed for guidance:

- vented lead-acid batteries:  $K = 8$
- vented alkaline type batteries intended for discharge at low rates corresponding to a battery duration exceeding three hours:  $K = 15$
- sealed lead-acid batteries having a capacity of 100 Ah or more or alkaline type batteries intended for discharge at high rates corresponding to a battery duration not exceeding three hours:  $K = 30$ .

## 6.3 Selection of equipment

**6.3.1** Circuit-breakers of withdrawable type are required where they are not suitable for isolation.

**6.3.2** Equipment is to be chosen on the basis of its rated current and its making/breaking capacity.

**6.3.3** In the selection of circuit-breakers with intentional short-time delay for short-circuit release, those of utilisation category B are to be used and they are to be selected also taking into account their rated short-time withstand current capacity ( $I_{cw}$ ).

For circuit-breakers without intentional short-time delay for short-circuit release, circuit breakers of utilisation category A may be used and they are to be selected according to their rated service short-circuit breaking capacity ( $I_{cs}$ ).

Note 1: For the purpose of these Rules, utilisation categories A and B are defined as follows:

- Utilisation category A: circuit-breakers not specifically intended for selectivity under short-circuit conditions with respect to other short-circuit protective devices in series on the load side, i.e. without an intentional short-time delay provided for selectivity under short-circuit conditions
- Utilisation category B: circuit-breakers specifically intended for selectivity under short-circuit conditions with respect to other short-circuit protective devices in series on the load side, i.e. with an intentional short-time delay (which may be adjustable) provided for selectivity under short-circuit conditions.

**6.3.4** For duplicated essential services and non-essential services, circuit-breakers may be selected according to their ultimate short-circuit breaking capacity ( $I_{cu}$ ).

**6.3.5** For switches, the making/breaking capacity is to be in accordance with utilisation category AC-22 A or DC-22 A (in compliance with IEC 60947-3).

**6.3.6** For fuse-switch disconnectors or switch-disconnector fuse units, the making/breaking capacity is to be in accordance with utilisation categories AC-23 A or DC-23 A (in compliance with IEC 60947-3).

## 6.4 Protection against short-circuit

**6.4.1** Protection against short-circuit currents is to be provided by circuit-breakers or fuses.

**6.4.2** The rated short-circuit breaking capacity of every protective device is to be not less than the maximum prospective value of the short-circuit current at the point of installation at the instant of contact separation.

**6.4.3** The rated short-circuit making capacity of every mechanical switching device intended to be capable of being closed on short-circuit is to be not less than the maximum value of the short-circuit current at the point of installation. On alternating current this maximum value corresponds to the peak value allowing for maximum asymmetry.

**6.4.4** Every protective device or contactor not intended for short-circuit interruption is to be adequate for the maximum short-circuit current liable to occur at the point of installation having regard to the time required for the short-circuit to be removed.

**6.4.5** The use of a protective device not having a short-circuit breaking or making capacity at least equal to the maximum prospective short-circuit current at the point where it is installed is permitted, provided that it is backed up on the generator side by a fuse or by a circuit-breaker having at least the necessary short-circuit rating and not being the generator circuit-breaker.

**6.4.6** The same fuse or circuit-breaker may back up more than one circuit-breaker where the circuits concerned do not involve essential services.

**6.4.7** The short-circuit performance of the back-up arrangement is to be equal to the requirements of IEC 60947-2 for a single circuit-breaker having the same short-circuit performance category as the backed-up circuit-breaker and rated for the maximum prospective short-circuit level at the supply terminals of the arrangement.

**6.4.8** Circuit-breakers with fuses connected to the load side may be used, provided the back-up fuses and the circuit-breakers are of coordinated design, in order to ensure that the operation of the fuses takes place in due time so as to prevent arcing between poles or against metal parts of the circuit-breakers when they are submitted to overcurrents involving the operation of the fuse.

**6.4.9** When determining the performance requirements for the above-mentioned back-up protection arrangement, it is permissible to take into account the impedance of the various circuit elements of the arrangement, such as the impedance of a cable connection when the backed-up circuit-breaker is located away from the back-up breaker or fuse.

## **6.5 Continuity of supply and continuity of service**

**6.5.1** The protection of circuits is to be such that a fault in one service does not cause the loss of any essential services.

**6.5.2** The protection of the emergency circuit is to be such that a failure in one circuit does not cause a loss of other emergency services.

Note 1:

The continuity of supply is the condition for which during and after a fault in a circuit, the supply to the healthy circuits (see circuit 3 in Fig 2) is permanently ensured.

The continuity of service is the condition for which after a fault in a circuit has been cleared, the supply to the healthy circuits (see circuit 3 in Fig 2) is re-established.

## **6.6 Protection against overload**

**6.6.1** Devices provided for overload protection are to have a tripping characteristic (overcurrent-trip time) adequate for the overload ability of the elements of the system to be protected and for any discrimination requirements.

**6.6.2** The use of fuses up to 320 A for overload protection is permitted.

## **6.7 Localisation of overcurrent protection**

**6.7.1** Short-circuit protection is to be provided for every non-earthed conductor.

**6.7.2** Overload protection is to be provided for every non-earthed conductor; nevertheless, in insulated single-phase circuits or insulated three-phase circuits having substantially balanced loads, the overload protection may be omitted on one conductor.

**6.7.3** Short-circuit and overload protective devices are not to interrupt earthed conductors, except in the case of multiple disconnection devices which simultaneously interrupt all the conductors, whether earthed or not.

**6.7.4** Electrical protection is to be located as close as possible to the origin of the protected circuit.

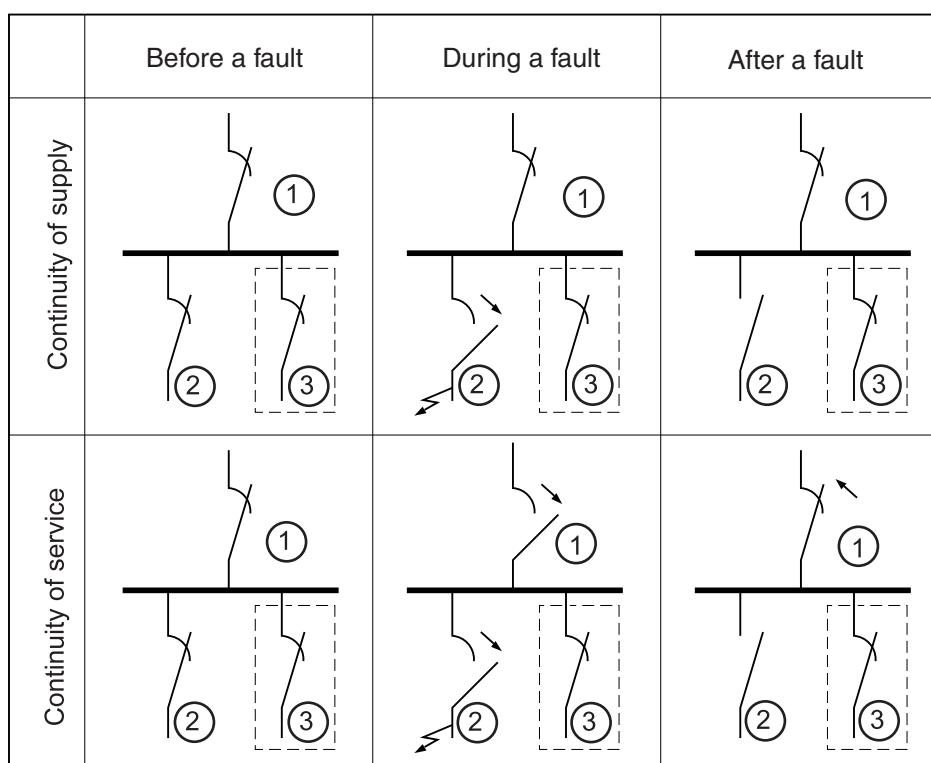
## **6.8 Protection of generators**

**6.8.1** Generators are to be protected against short-circuits and overloads by multipole circuit-breakers.

For generators not arranged to operate in parallel with a rated output equal to or less than 50 kVA, a multipole switch with a fuse in each insulated phase on the generator side may be accepted.

**6.8.2** When multipole switch and fuses are used, the fuse rating is to be maximum 110% of the generator rated current.

Figure 2



### 6.8.3 Where a circuit-breaker is used:

- the overload protection is to trip the generator circuit-breaker at an overload between 10% and 50%; for an overload of 50% of the rated current of the generator the time delay is not to exceed 2 minutes; however, the figure of 50% or the time delay of 2 minutes may be exceeded if the construction of the generator permits this
- the setting of the short-circuit protection is to instantaneously trip the generator circuit-breaker at an overcurrent less than the steady short-circuit current of the generator. Short time delays (e.g. from 0,5 s to 1 s) may be introduced for discrimination requirements in "instantaneous" tripping devices.

**6.8.4** For emergency generators the overload protection may, instead of disconnecting the generator automatically, give a visual and audible alarm in a permanently attended space.

**6.8.5** After disconnection of a generator due to overload, the circuit-breaker is to be ready for immediate reclosure.

**6.8.6** Generator circuit-breakers are to be provided with a reclosing inhibitor which prevents their automatic reclosure after tripping due to a short-circuit.

**6.8.7** Generators having a capacity of 1500 kVA or above are to be equipped with a suitable protective device or system which, in the event of a short-circuit in the generator or in the supply cable between the generator and its circuit-breaker, will de-excite the generator and open the circuit-breaker (e.g. by means of differential protection).

**6.8.8** Where the main source of electrical power is necessary for the propulsion of the ship, load shedding or other equivalent arrangements are to be provided to protect the generators against sustained overload.

**6.8.9** Arrangements are to be made to disconnect or reduce automatically the excess load when the generators are overloaded in such a way as to prevent a sustained loss of speed and/or voltage (see Sec 2, Tab 6). The operation of such device is to activate a visual and audible alarm. A time delay of 5-20 s is considered acceptable.

**6.8.10** When an overload is detected the load shedding system is to disconnect automatically, after an appropriate time delay, the circuits supplying the non-essential services and, if necessary in a second stage, the essential services not required to be in continuous operation to maintain propulsion and steering.

**6.8.11** The load shedding system is to be designed to prevent the generator overloading during icebreaking operations.

**6.8.12** Alternating current generators arranged to operate in parallel are to be provided with reverse-power protection.

The protection is to be selected in accordance with the characteristics of the prime mover.

The following values are recommended:

- 2-6% of the rated power for turbogenerators
- 8-15% of the rated power for diesel generators.

The reverse-power protection may be replaced by other devices ensuring adequate protection of the prime movers.



**6.8.13** Generators are to be provided with an undervoltage protection which trips the breaker if the voltage falls to 70% - 35% of the rated voltage.

For generators arranged for parallel operation, measures are to be taken to prevent the generator breaker from closing if the generator is not generating and to prevent the generator remaining connected to the busbars if voltage collapses.

The operation of the undervoltage release is to be instantaneous when preventing closure of the breaker, but it is to be delayed for selectivity purposes when tripping the breaker.

## 6.9 Protection of circuits

**6.9.1** Each separate circuit shall be protected against short-circuit and against overload, unless otherwise specified in these Rules or where the Society may exceptionally otherwise permit.

**6.9.2** Each circuit is to be protected by a multipole circuit-breaker or switch and fuses against overloads and short-circuits.

**6.9.3** Circuits for lighting are to be disconnected on both non-earthed conductors; single-pole disconnection of final sub-circuits with both poles insulated is permitted only in accommodation spaces.

**6.9.4** The protective devices of the circuits supplying motors are to allow excess current to pass during transient starting of motors.

**6.9.5** Final sub-circuits which supply one consumer with its own overload protection (for example motors), or consumers which cannot be overloaded (for example permanently wired heating circuits and lighting circuits), may be provided with short-circuit protection only.

**6.9.6** Steering gear circuits are to be provided with short-circuit protection only (see Ch 1, Sec 11, [2]).

## 6.10 Protection of motors

**6.10.1** Motors of rating exceeding 1 kW and all motors for essential services are to be protected individually against overload and short-circuit. The short-circuit protection may be provided by the same protective device for the motor and its supply cable (see [6.9.5]).

**6.10.2** For motors intended for essential services, the overload protection may be replaced by an overload alarm (for steering gear motors see Ch 1, Sec 11, [2]).

**6.10.3** The protective devices are to be designed so as to allow excess current to pass during the normal accelerating period of motors according to the conditions corresponding to normal use.

If the current/time characteristic of the overload protection device does not correspond to the starting conditions of a motor (e.g. for motors with extra-long starting period), provision may be made to suppress operation of the device during the acceleration period on condition that the short-circuit protection remains operative and the suppression of overload protection is only temporary.

**6.10.4** For continuous duty motors the protective gear is to have a time delay characteristic which ensures reliable thermal protection against overload.

**6.10.5** The protective devices are to be adjusted so as to limit the maximum continuous current to a value within the range 105% - 120% of the motor's rated full load current.

**6.10.6** For intermittent duty motors the current setting and the delay (as a function of time) of the protective devices are to be chosen in relation to the actual service conditions of the motor.

**6.10.7** Where fuses are used to protect polyphase motor circuits, means are to be provided to protect the motor against unacceptable overload in the case of single phasing.

**6.10.8** Motors rated above 1 kW are to be provided with:

- undervoltage protection, operative on the reduction or failure of voltage, to cause and maintain the interruption of power in the circuit until the motor is deliberately restarted or
- undervoltage release, operative on the reduction or failure of voltage, so arranged that the motor restarts automatically when power is restored after a power failure.

**6.10.9** The automatic restart of a motor is not to produce a starting current such as to cause excessive voltage drop.

In the case of several motors required to restart automatically, the total starting current is not to cause an excessive voltage drop or sudden surge current; to this end, it may be necessary to achieve a sequence start.

**6.10.10** The undervoltage protective devices are to allow the motor to be started when the voltage exceeds 85% of the rated voltage and are to intervene without fail when the voltage drops to less than approximately 20% of the rated voltage, at the rated frequency and with a time delay as necessary.

## 6.11 Protection of storage batteries

**6.11.1** Batteries are to be protected against overload and short-circuit by means of fuses or multipole circuit-breakers at a position adjacent to the battery compartment.

Overcurrent protection may be omitted for the circuit to the starter motors when the current drawn is so large that is impracticable to obtain short-circuit protection.

Where the batteries could adversely be affected by low temperatures, they are to be heated to maintain the minimum workable temperature.

**6.11.2** Emergency batteries supplying essential services are to have short-circuit protection only.

## 6.12 Protection of shore power connection

**6.12.1** Permanently fixed cables connecting the shore connection box to the main switchboard are to be protected by fuses or circuit-breakers (see [3.6.4]).

### 6.13 Protection of measuring instruments, pilot lamps and control circuits

**6.13.1** Measuring circuits and devices (voltage transformers, voltmeters, voltage coils of measuring instruments, insulation monitoring devices etc.) and pilot lamps are to be protected against short-circuit by means of multipole circuit-breakers or fuses.

The protective devices are to be placed as near as possible to the tapping from the supply.

The secondary side of current transformers is not to be protected.

**6.13.2** Control circuits and control transformers are to be protected against overload and short-circuit by means of multipole circuit-breakers or fuses on each pole not connected to earth.

Overload protection may be omitted for transformers with a rated current of less than 2 A on the secondary side.

The short-circuit protection on the secondary side may be omitted if the transformer is designed to sustain permanent short-circuit current.

**6.13.3** Where a fault in a pilot lamp would impair the operation of essential services, such lamps are to be protected separately from other circuits such as control circuits.

Note 1: Pilot lamps connected via short-circuit-proof transformers may be protected in common with control circuits.

**6.13.4** Circuits whose failure could endanger operation, such as steering gear control feeder circuits, are to be protected only against short-circuit.

**6.13.5** The protection is to be adequate for the minimum cross-section of the protected circuits.

### 6.14 Protection of transformers

**6.14.1** The primary winding side of power transformers is to be protected against short-circuit and overload by means of multipole circuit-breakers or switches and fuses.

Overload protection on the primary side may be dispensed with where it is provided on the secondary side or when the total possible load cannot reach the rated power of the transformer.

**6.14.2** The protection against short-circuit is to be such as to ensure the selectivity between the circuits supplied by the secondary side of the transformer and the feeder circuit of the transformer.

**6.14.3** When transformers are arranged to operate in parallel, means are to be provided so as to trip the switch on the secondary winding side when the corresponding switch on the primary side is open.

## 7 System components

### 7.1 General

**7.1.1** The components of the electrical system are to be dimensioned such as to withstand the currents that can pass

through them during normal service without their rating being exceeded.

**7.1.2** The components of the electrical system are to be designed and constructed so as to withstand for the admissible duration the thermal and electrodynamic stresses caused by possible overcurrents, including short-circuit.

## 8 Electrical cables

### 8.1 General

**8.1.1** All electrical cables and wiring external to equipment shall be at least of a flame-retardant type, in accordance with IEC 60332-1.

**8.1.2** In addition to the provisions of [8.1.1], when cables are laid in bundles, cable types are to be chosen in compliance with IEC 60332-3 Category A, or other means (see Sec 12) are to be provided such as not to impair their original flame-retarding properties.

**8.1.3** Where necessary for specific applications such as radio frequency or digital communication systems, which require the use of particular types of cables, the Society may permit the use of cables which do not comply with the provisions of [8.1.1] and [8.1.2].

**8.1.4** Cables which are required to have fire-resisting characteristics are to comply with the requirements stipulated in [8.6].

### 8.2 Choice of insulation

**8.2.1** The maximum rated operating temperature of the insulating material is to be at least 10°C higher than the maximum ambient temperature liable to occur or to be produced in the space where the cable is installed.

**8.2.2** The maximum rated conductor temperature for normal and short-circuit operation, for the type of insulating compounds normally used for shipboard cables, is not to exceed the values stated in Tab 3. Special consideration will be given to other insulating materials.

**8.2.3** PVC insulated cables are not to be used either in refrigerated spaces, or on decks exposed to the weather.

**8.2.4** Mineral insulated cables will be considered on a case by case basis.

### 8.3 Choice of protective covering

**8.3.1** The conductor insulating materials are to be enclosed in an impervious sheath of material appropriate to the expected ambient conditions where cables are installed in the following locations:

- on decks exposed to the weather,
- in damp or wet spaces (e.g. in bathrooms),
- in refrigerated spaces,
- in machinery spaces and, in general,
- where condensation water or harmful vapour may be present.

**8.3.2** Where cables are provided with armour or metallic braid (e.g. for cables installed in hazardous areas), an overall impervious sheath or other means to protect the metallic elements against corrosion is to be provided; see Sec 9, [1.5].

**8.3.3** An impervious sheath is not required for single-core cables installed in tubes or ducts inside accommodation spaces, in circuits with maximum system voltage 250 V.

**8.3.4** In choosing different types of protective coverings, due consideration is to be given to the mechanical action to which each cable may be subjected during installation and in service.

If the mechanical strength of the protective covering is considered insufficient, the cables are to be mechanically protected (e.g. by an armour or by installation inside pipes or conduits).

**8.3.5** Single-core cables for a.c. circuits with rated current exceeding 20 A are to be either non-armoured or armoured with non-magnetic material.

## **8.4 Cables in refrigerated spaces**

**8.4.1** Cables installed in refrigerated spaces are to have a watertight or impervious sheath and are to be protected against mechanical damage. If an armour is applied on the sheath, the armour is to be protected against corrosion by a further moisture-resisting covering.

## **8.5 Cables in areas with a risk of explosion**

**8.5.1** For cables in areas with a risk of explosion, see [9].

## **8.6 Electrical services required to be operable under fire conditions and fire-resistant cables**

**8.6.1** Electrical services required to be operable under fire conditions are as follows:

- Control and power systems to power-operated fire doors and status indication for all fire doors
- Control and power systems to power-operated watertight doors and their status indication
- Emergency fire pump
- Emergency lighting
- Fire and general alarms
- Fire detection systems
- Fire-extinguishing systems and fire-extinguishing media release alarms
- Low location lighting
- Public address systems
- Remote emergency stop/shutdown arrangements for systems which may support the propagation of fire and/or explosion.

**8.6.2** Where cables for services specified in [8.6.2] including their power supplies pass through high fire risk areas

(see Note 1), and in addition for passenger ships, main vertical fire zones, other than those which they serve, they are to be so arranged that a fire in any of these areas or zones does not affect the operation of the service in any other area or zone. This may be achieved by either of the following measures:

- a) Cables being of a fire-resistant type complying with IEC 60331-31 for cables of greater than 20 mm overall diameter, otherwise 60331-21, are installed and run continuous to keep the fire integrity within the high fire risk area (see Fig 3).
- b) At least two loops/radial distributions run as widely apart as is practicable and so arranged that in the event of damage by fire at least one of the loops/radial distributions remains operational.

Systems that are self monitoring, fail safe or duplicated with cable runs as widely separated as is practicable may be exempted.

Note 1:

a) For the purpose of application of this item [8.6], the definition of "high fire risk areas" is the following:

- (1) Machinery spaces as defined Chapter 4
- (2) Spaces containing fuel treatment equipment and other highly flammable substances
- (3) Galley and Pantries containing cooking appliances
- (4) Laundry containing drying equipment
- (5) Spaces as defined by paragraphs (8), (12), and (14) of Chap. II-2 / Reg. 9.2.2.3.2.2 of SOLAS for ships carrying more than 36 passengers;

b) Fire-resistant type cables are to be easily distinguishable.

c) For special cables, requirements in the following standards may be used:

- (1) IEC60331-23: Procedures and requirements - Electric data cables
- (2) IEC60331-25: Procedures and requirements - Optical fibre cables.

**8.6.3** Cables connecting fire pumps to the emergency switchboard are to be of a fire-resistant type where they pass through high fire risk areas.

## **8.7 Cables for submerged bilge pumps**

**8.7.1** Cables and their connections to such pumps are to be capable of operating under a head of water equal to their distance below the bulkhead deck. The cable is to be impervious-sheathed and armoured, is to be installed in continuous lengths from above the bulkhead to the motor terminals and is to enter the air bell from the bottom.

## **8.8 Internal wiring of switchboards and other enclosures for equipment**

**8.8.1** For installation in switchboards and other enclosures for equipment, single-core cables may be used without further protection (sheath).

Other types of flame-retardant switchboard wiring may be accepted at the discretion of the Society.

**8.9 Current carrying capacity of cables**

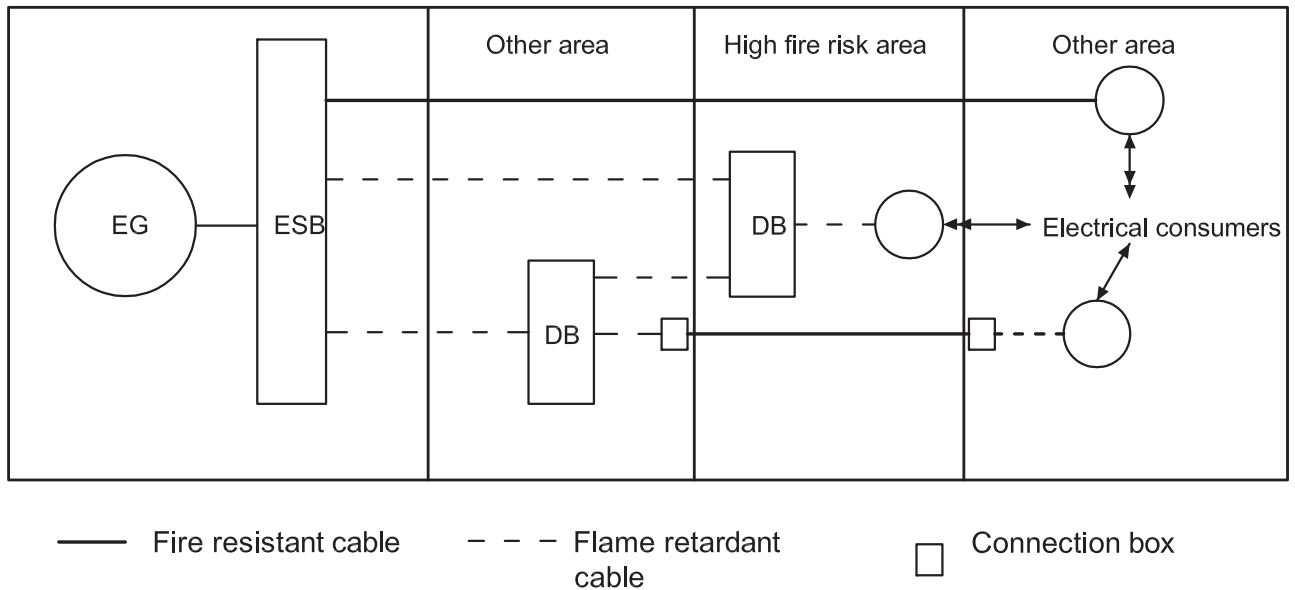
**8.9.1** The current carrying capacity for continuous service of cables given in Tab 4 to Tab 8 is based on the maximum permissible service temperature of the conductor also indicated therein and on an ambient temperature of 45°C.

**8.9.2** The current carrying capacity cited in [8.9.1] is applicable, with rough approximation, to all types of protective covering (e.g. both armoured and non-armoured cables).

**8.9.3** Values other than those shown in Tab 4 to Tab 8 may be accepted provided they are determined on the basis of calculation methods or experimental values approved by the Society.

**8.9.4** When the actual ambient temperature obviously differs from 45°C, the correction factors shown in Tab 9 may be applied to the current carrying capacity in Tab 4 to Tab 8.

**Figure 3**



**8.9.5** Where more than six cables are bunched together in such a way that there is an absence of free air circulating around them, and the cables can be expected to be under

full load simultaneously, a correction factor of 0,85 is to be applied.

**Table 3 : Maximum rated conductor temperature**

Type of insulating compound	Abbreviated designation	Maximum rated conductor temperature, in °C	
		Normal operation	Short-circuit
a) Thermoplastic: - based upon polyvinyl chloride or copolymer of vinyl chloride and vinyl acetate	PVC/A	60	150
b) Elastomeric or thermosetting: - based upon ethylene-propylene rubber or similar (EPM or EPDM)	EPR	85	250
- based upon high modulus or hardgrade ethylene propylene rubber	HEPR	85	250
- based upon cross-linked polyethylene	XLPE	85	250
- based upon rubber silicon	S 95	95	350
- based upon ethylene-propylene rubber or similar (EPM or EPDM) halogen free	HF EPR	85	250
- based upon high modulus or hardgrade halogen free ethylene propylene rubber	HF HEPR	85	250
- based upon cross-linked polyethylene halogen free	HF XLPE	85	250
- based upon rubber silicon halogen free	HF S 95	95	350
- based upon cross-linked polyolefin material for halogen free cable <b>(1)</b>	HF 85	85	250
<b>(1)</b> Used on sheathed cable only			

**Table 4 : Current carrying capacity, in A in continuous service for cables based on maximum conductor operating temperature of 60°C (ambient temperature 45°C)**

Nominal section mm <sup>2</sup>	Number of conductors		
	1	2	3 or 4
1	8	7	6
1,5	12	10	8
2,5	17	14	12
4	22	19	15
6	29	25	20
10	40	34	28
16	54	46	38
25	71	60	50
35	87	74	61
50	105	89	74
70	135	115	95
95	165	140	116
120	190	162	133
150	220	187	154
185	250	213	175
240	290	247	203
300	335	285	235

**Table 6 : Current carrying capacity, in A in continuous service for cables based on maximum conductor operating temperature of 80°C (ambient temperature 45°C)**

Nominal section mm <sup>2</sup>	Number of conductors		
	1	2	3 or 4
1	15	13	11
1,5	19	16	13
2,5	26	22	18
4	35	30	25
6	45	38	32
10	63	54	44
16	84	71	59
25	110	94	77
35	140	119	98
50	165	140	116
70	215	183	151
95	260	221	182
120	300	255	210
150	340	289	238
185	390	332	273
240	460	391	322
300	530	450	371

**Table 5 : Current carrying capacity, in A in continuous service for cables based on maximum conductor operating temperature of 75°C (ambient temperature 45°C)**

Nominal section mm <sup>2</sup>	Number of conductors		
	1	2	3 or 4
1	13	11	9
1,5	17	14	12
2,5	24	20	17
4	32	27	22
6	41	35	29
10	57	48	40
16	76	65	53
25	100	85	70
35	125	106	88
50	150	128	105
70	190	162	133
95	230	196	161
120	270	230	189
150	310	264	217
185	350	298	245
240	415	353	291
300	475	404	333

**Table 7 : Current carrying capacity, in A in continuous service for cables based on maximum conductor operating temperature of 85°C (ambient temperature 45°C)**

Nominal section mm <sup>2</sup>	Number of conductors		
	1	2	3 or 4
1	16	14	11
1,5	20	17	14
2,5	28	24	20
4	38	32	27
6	48	41	34
10	67	57	47
16	90	77	63
25	120	102	84
35	145	123	102
50	180	153	126
70	225	191	158
95	275	234	193
120	320	272	224
150	365	310	256
185	415	353	291
240	490	417	343
300	560	476	392

**Table 8 : Current carrying capacity, in A in continuous service for cables based on maximum conductor operating temperature of 95°C (ambient temperature 45°C)**

Nominal section mm <sup>2</sup>	Number of conductors		
	1	2	3 or 4
1	20	17	14
1,5	24	20	17
2,5	32	27	22
4	42	36	29
6	55	47	39
10	75	64	53
16	100	85	70
25	135	115	95
35	165	140	116
50	200	170	140
70	255	217	179
95	310	264	217
120	360	306	252
150	410	349	287
185	470	400	329
240	570	485	399
300	660	560	462

**8.9.6** Where a cable is intended to supply a short-time load for 1/2-hour or 1-hour service (e.g. mooring winches or bow thruster propellers), the current carrying capacity obtained from Tab 4 to Tab 8 may be increased by applying the corresponding correction factors given in Tab 10.

In no case is a period shorter than 1/2-hour to be used, whatever the effective period of operation.

**8.9.7** For supply cables to single services for intermittent loads (e.g. cargo winches or machinery space cranes), the current carrying capacity obtained from Tab 4 to Tab 8 may be increased by applying the correction factors given in Tab 11.

The correction factors are calculated with rough approximation for periods of 10 minutes, of which 4 minutes with a constant load and 6 minutes without load.

## 8.10 Minimum nominal cross-sectional area of conductors

**8.10.1** In general the minimum allowable conductor cross-sectional areas are those given in Tab 12.

**8.10.2** The nominal cross-sectional area of the neutral conductor in three-phase distribution systems is to be equal to at least 50% of the cross-sectional area of the phases, unless the latter is less than or equal to 16 mm<sup>2</sup>. In such case the cross-sectional area of the neutral conductor is to be equal to that of the phase.

**8.10.3** For the nominal cross-sectional area of:

- earthing conductors, see Sec 12, [2.3]
- earthing connections for distribution systems, see Sec 12, [2.5].

## 8.11 Choice of cables

**8.11.1** The rated voltage of any cable is to be not lower than the nominal voltage of the circuit for which it is used.

**8.11.2** The nominal cross-sectional area of each cable is to be sufficient to satisfy the following conditions with reference to the maximum anticipated ambient temperature:

- the current carrying capacity is to be not less than the highest continuous load carried by the cable
- the voltage drop in the circuit, by full load on this circuit, is not to exceed the specified limits
- the cross-sectional area calculated on the basis of the above is to be such that the temperature increases which may be caused by overcurrents or starting transients do not damage the insulation.

**8.11.3** The highest continuous load carried by a cable is to be calculated on the basis of the power requirements and of the diversity factor of the loads and machines supplied through that cable.

**8.11.4** When the conductors are carrying the maximum nominal service current, the voltage drop from the main or emergency switchboard busbars to any point in the installation is not to exceed 6% of the nominal voltage.

For battery circuits with supply voltage less than 55 V, this value may be increased to 10%.

For the circuits of navigation lights, the voltage drop is not to exceed 5% of the rated voltage under normal conditions.

**Table 9 : Correction factors for various ambient air temperatures**

Maximum conductor temperature, in °C	Correction factors for ambient air temperature of :										
	35°C	40°C	45°C	50°C	55°C	60°C	65°C	70°C	75°C	80°C	85°C
60	1,29	1,15	1,00	0,82	-	-	-	-	-	-	-
75	1,15	1,08	1,00	0,91	0,82	0,71	0,58	-	-	-	-
80	1,13	1,07	1,00	0,93	0,85	0,76	0,65	0,53	-	-	-
85	1,12	1,06	1,00	0,94	0,87	0,79	0,71	0,61	0,50	-	-
95	1,10	1,05	1,00	0,95	0,89	0,84	0,77	0,71	0,63	0,55	0,45

**Table 10 : Correction factors for short-time loads**

$\frac{1}{2}$ -hour service		1-hour service		Correlation factor
Sum of nominal cross-sectional areas of all conductors in the cable, in mm <sup>2</sup>		Sum of nominal cross-sectional areas of all conductors in the cable, in mm <sup>2</sup>		
Cables with metallic sheath and armoured cables	Cables with non-metallic sheath and non-armoured cables	Cables with metallic sheath and armoured cables	Cables with non-metallic sheath and non-armoured cables	
up to 20	up to 75	up to 80	up to 230	1,06
21-41	76-125	81-170	231-400	1,10
41-65	126-180	171-250	401-600	1,15
66-95	181-250	251-430	601-800	1,20
96-135	251-320	431-600	-	1,25
136-180	321-400	601-800	-	1,30
181-235	401-500	-	-	1,35
236-285	501-600	-	-	1,40
286-350	-	-	-	1,45

**Table 11 : Correction factors for intermittent service**

Sum of nominal cross sectional areas of all conductors in the cable, in mm <sup>2</sup>		Correction factor
Cables with metallic sheath and armoured cables	Cables without metallic sheath and non-armoured cables	
	$S \leq 5$	1,10
	$5 < S \leq 8$	1,15
	$8 < S \leq 16$	1,20
$S \leq 4$	$16 < S \leq 825$	1,25
$4 < S \leq 7$	$25 < S \leq 42$	1,30
$7 < S \leq 17$	$42 < S \leq 72$	1,35
$17 < S \leq 42$	$72 < S \leq 140$	1,40
$42 < S \leq 110$	$140 < S$	1,45
$110 < S$	-	1,50

## 9 Electrical installations in hazardous areas

### 9.1 Electrical equipment

**9.1.1** No electrical equipment is to be installed in hazardous areas unless the Society is satisfied that such equipment is:

- essential for operational purposes,
- of a type which will not ignite the mixture concerned,
- appropriate to the space concerned, and
- appropriately certified for safe usage in the dusts, vapours or gases likely to be encountered.

**9.1.2** Where electrical equipment of a safe type is permitted in hazardous areas it is to be selected with due consideration to the following:

- a) risk of explosive dust concentration; see Sec 2, [6.2]:
  - degree of protection of the enclosure
  - maximum surface temperature
- b) risk of explosive gas atmosphere; see Sec 2, [6.1]:
  - explosion group
  - temperature class.

**9.1.3** Where electrical equipment is permitted in hazardous areas, all switches and protective devices are to interrupt all poles or phases and, where practicable, to be located in a non-hazardous area unless specifically permitted otherwise.

Such switches and equipment located in hazardous areas are to be suitably labelled for identification purposes.

**9.1.4** For electrical equipment installed in Zone 0 hazardous areas, only the following types are permitted:

- certified intrinsically-safe apparatus Ex(ia)
- simple electrical apparatus and components (e.g. thermocouples, photocells, strain gauges, junction boxes, switching devices), included in intrinsically-safe circuits of category "ia" not capable of storing or generating electrical power or energy in excess of limits stated in the relevant rules, and accepted by the appropriate authority
- equipment specifically designed and certified by the appropriate authority for use in Zone 0.

Table 12 : Minimum nominal cross-sectional areas

Service	Nominal cross-sectional area	
	external wiring mm <sup>2</sup>	internal wiring mm <sup>2</sup>
Power, heating and lighting systems	1,0	1,0
Control circuits for power plant	1,0	1,0
Control circuits other than those for power plant	0,75	0,5
Control circuits for telecommunications, measurement, alarms	0,5	0,2
Telephone and bell equipment, not required for the safety of the ship or crew calls	0,2	0,1
Bus and data cables	0,2	0,1

**9.1.5** For electrical equipment installed in Zone 1 hazardous areas, only the following types are permitted:

- any type that may be considered for Zone 0
- certified intrinsically-safe apparatus Ex(ib)
- simple electrical apparatus and components (e.g. thermocouples, photocells, strain gauges, junction boxes, switching devices), included in intrinsically-safe circuits of category "ib" not capable of storing or generating electrical power or energy in excess of limits stated in the relevant rules, and accepted by the appropriate authority
- certified flameproof Ex(d)
- certified pressurised Ex(p)
- certified increased safety Ex(e)
- certified encapsulated Ex(m)
- certified sand filled Ex(q)
- certified specially Ex(s)
- through runs of cable.

**9.1.6** For electrical equipment installed in Zone 2 hazardous areas, only the following types are permitted:

- any type that may be considered for Zone 1
- tested specially for Zone 2 (e.g. type "n" protection)
- pressurised, and accepted by the appropriate authority
- encapsulated, and accepted by the appropriate authority
- the type which ensures the absence of sparks and arcs and of "hot spots" during its normal operation (minimum class of protection IP55).

**9.1.7** When apparatus incorporates a number of types of protection, it is to be ensured that all are suitable for use in the zone in which it is located.

## 9.2 Electrical cables

**9.2.1** Electrical cables are not to be installed in hazardous areas except as specifically permitted or when associated with intrinsically safe circuits.

**9.2.2** All cables installed in Zone 0, Zone 1 and weather exposed areas classified Zone 2 are to be sheathed with at least one of the following:

- a non-metallic impervious sheath in combination with braiding or other metallic covering
- a copper or stainless steel sheath (for mineral insulated cables only).

**9.2.3** All cables installed in non-weather exposed Zone 2 areas are to be provided with at least a non-metallic external impervious sheath.

**9.2.4** Cables of intrinsically safe circuits are to have a metallic shielding with at least a non-metallic external impervious sheath.

**9.2.5** The circuits of a category "ib" intrinsically safe system are not to be contained in a cable associated with a category "ia" intrinsically safe system required for a hazardous area in which only category "ia" systems are permitted.

## 9.3 Electrical installations in battery rooms

**9.3.1** Only intrinsically safe apparatus and certified safe type lighting fittings may be installed in compartments assigned solely to large vented storage batteries; see Sec 11, [6.2.1].

The associated switches are to be installed outside such spaces.

Electric ventilator motors are to be outside ventilation ducts and, if within 3 m of the exhaust end of the duct, they are to be of an explosion-proof safe type. The impeller of the fan is to be of the non-sparking type.

Overcurrent protective devices are to be installed as close as possible to, but outside of, battery rooms.

Electrical cables other than those pertaining to the equipment arranged in battery rooms are not permitted.

Electrical equipment for use in battery rooms is to have minimum explosion group IIC and temperature class T1.

**9.3.2** Standard marine electrical equipment may be installed in compartments assigned solely to valve-regulated sealed storage batteries.

**9.3.3** Where vented (see Note 1) type batteries replace valve-regulated sealed (see Note 2) types, the requirements of Sec 11 are to be complied with.

Note 1: A vented battery is one in which the cells have a cover provided with an opening through which products of electrolysis and



evaporation are allowed to escape freely from the cells to atmosphere.

Note 2: A valve-regulated battery is one in which cells are closed but have an arrangement (valve) which allows the escape of gas if the internal pressure exceeds a predetermined value.

#### 9.4 Electrical equipment allowed in paint stores and in enclosed spaces leading to paint stores

9.4.1 Electrical equipment is to be installed in paint stores and in ventilation ducts serving such spaces only when it is essential for operational services

Certified safe type equipment of the following type is acceptable:

- a) intrinsically safe Exi
- b) flameproof Exd
- c) pressurised Exp
- d) increased safety Exe
- e) special protection Exs

Cables (through-runs or terminating cables) of armoured type or installed in metallic conduits are to be used.

9.4.2 The minimum requirements for certified safe type equipment are as follows:

- explosion group II B
- temperature class T3.

9.4.3 Switches, protective devices and motor control gear of electrical equipment installed in a paint store are to interrupt all poles or phases and are preferably to be located in a non-hazardous space.

9.4.4 In areas on open deck within 1m of inlet and exhaust ventilation openings or within 3 m of exhaust mechanical ventilation outlets, the following electrical equipment may be installed:

- electrical equipment with the type of protection as permitted in paint stores or
- equipment of protection class Exn or
- appliances which do not generate arcs in service and whose surface does not reach unacceptably high temperature or
- appliances with simplified pressurised enclosures or vapour-proof enclosures (minimum class of protection IP55) whose surface does not reach unacceptably high temperature
- cables as specified in [9.4.1].

9.4.5 The enclosed spaces giving access to the paint store may be considered as non-hazardous, provided that :

- the door to the paint store is a gas-tight door with self-closing devices without holding back arrangements

- the paint store is provided with an acceptable, independent, natural ventilation system ventilated from a safe area

- warning notices are fitted adjacent to the paint store entrance stating that the store contains flammable liquids.

Note 1: The paint stores and inlet and exhaust ventilation ducts under 10.4.4 are classified as Zone 1 and areas on open deck under 10.4.4 as Zone 2, as defined in IEC standard 60092-502, Electrical Installation in ships-part 502: Tankers-special features.

Note 2: A watertight door may be considered as being gas-tight.

#### 9.5 Electrical installations in stores for welding gas (acetylene) bottles

9.5.1 The following equipment may be installed in stores for welding gas bottles provided that it is of a safe type appropriate for Zone 1 area installation:

- lighting fittings
- ventilator motors where provided.

9.5.2 Electrical cables other than those pertaining to the equipment arranged in stores for welding gas bottles are not permitted.

9.5.3 Electrical equipment for use in stores for welding gas bottles is to have minimum explosion group IIC and temperature class T2.

### 10 Recording of the Type, Location and Maintenance Cycle of Batteries

#### 10.1 Battery schedule

10.1.1 Where batteries are fitted for use for essential and emergency services, a schedule of such batteries is to be compiled and maintained. The schedule, required in Sec 1, Tab 1, is to include at least the following information regarding the battery(ies):

- type and Manufacturer's type designation
- voltage and ampere-hour rating
- location
- equipment and/or system(s) served
- maintenance/replacement cycle dates
- date(s) of last maintenance and/or replacement
- for replacement batteries in storage, the date of manufacture and shelf life.

Note 1: Shelf life is the duration of storage under specified conditions at the end of which a battery retains the ability to give a specified performance.

## SECTION 4

## ROTATING MACHINES

### 1 Constructional and operational requirements for generators and motors

#### 1.1 Mechanical construction

**1.1.1** Insulating materials, insulated windings and construction of electrical machines are to conform to the relevant requirements of Sec 2, [4] and Sec 2, [5].

**1.1.2** Shafts are to be made of material complying with the provisions of Pt D, Ch 2, Sec 3 or, where rolled products are allowed in place of forgings, with those of Pt D, Ch 2, Sec 1.

**1.1.3** Where welded parts are foreseen on shafts and rotors, the provisions of Part D, Chapter 5 are to apply.

**1.1.4** Sleeve bearings are to be efficiently and automatically lubricated at all running speeds.

Provision is to be made for preventing the lubricant from gaining access to windings or other insulated or bare current carrying parts.

**1.1.5** Means are to be provided to prevent bearings from being damaged by the flow of currents circulating between them and the shaft. According to the Manufacturer's requirements, electrical insulation of at least one bearing is to be considered.

**1.1.6** For surface-cooled machines with an external fan installed on the open deck, adequate protection of the fan against icing is to be provided.

**1.1.7** When liquid cooling is used, the coolers are to be so arranged as to avoid entry of water into the machine, whether by leakage or condensation in the heat exchanger, and provision is to be made for the detection of leakage.

**1.1.8** Rotating machines whose ventilation or lubrication system efficiency depends on the direction of rotation are to be provided with a warning plate.

#### 1.2 Sliprings, commutators and brushes

**1.2.1** Sliprings and commutators with their brushgear are to be so constructed that undue arcing is avoided under all normal load conditions.

**1.2.2** The working position of brushgear is to be clearly and permanently marked.

**1.2.3** Sliprings, commutators and brushgear are to be readily accessible for inspection, repairs and maintenance.

#### 1.3 Terminal connectors

**1.3.1** Suitable, fixed terminal connectors are to be provided in an accessible position for connection of the external cables.

**1.3.2** All terminal connectors are to be clearly identified with reference to a diagram.

**1.3.3** The degree of protection of terminal boxes is to be adequate to that of the machine.

#### 1.4 Electrical insulation

**1.4.1** Insulating materials for windings and other current carrying parts are to comply with the requirements of Sec 2, [4.2] and Sec 2, [4.3].

## 2 Special requirements for generators

### 2.1 Prime movers, speed governors and overspeed protection

**2.1.1** Prime movers for generators are to comply with the relevant requirements of Ch 1, Sec 2, [2.7].

**2.1.2** When generators are to operate in parallel, the characteristics of speed governors are to comply with the provisions of [2.2].

### 2.2 A.c. generators

**2.2.1** Alternators are to be so constructed that, when started up, they take up the voltage without the aid of an external electrical power source.

Where these provisions are not complied with, the external electrical power source is to be constituted by a battery installation in accordance with the requirements for electrical starting systems of auxiliary machinery (see Ch 1, Sec 2).

**2.2.2** The voltage wave form is to be approximately sinusoidal, with a maximum deviation from the sinusoidal fundamental curve of 5% of the peak value.

**2.2.3** Each alternator is to be provided with automatic means of voltage regulation.

**2.2.4** For a.c. generating sets operating in parallel, the governing characteristics of the prime movers are to be such that, within the limits of 20% and 100% total load, the load on any generating set will not normally differ from its proportionate share of the total load by more than 15% of the rated power in kW of the largest machine or 25% of the rated power in kW of the individual machine in question, whichever is the lesser.

**2.2.5** For a.c. generating sets intended to operate in parallel, means are to be provided to regulate the governor so as to permit an adjustment of load not exceeding 5% of the rated load at normal frequency.

**2.2.6** When a.c. generators are operated in parallel, the reactive loads of the individual generating sets are not to differ from their proportionate share of the total reactive load by more than 10% of the rated reactive power of the largest machine, or 25% of that of the smallest machine, whichever is the lesser.

### 3 Testing of rotating machines

#### 3.1 General

**3.1.1** All machines are to be tested by the Manufacturer

**3.1.2** Manufacturer’s test records are to be provided for machines for essential services, for other machines they are to be available upon request.

**3.1.3** All tests are to be carried out according to IEC Publication 60092-301.

**3.1.4** All a.c. generators having rated power of 100 kVA and above, all d.c. generators having rated power of 100

kW and above, and all a.c./d.c. motors having rated power of 100 kW and above, intended for essential services are to be surveyed by the Society during testing and, if appropriate, during manufacturing.

Note 1: An alternative inspection scheme may be agreed by the Society with the Manufacturer whereby the attendance of the Surveyor will not be required as indicated above.

#### 3.2 Shaft material

**3.2.1** Shaft material for electric propulsion motors and for main engine driven generators where the shaft is part of the propulsion shafting is to be certified by the Society.

**3.2.2** Shaft material for other machines is to be in accordance with recognised international or national standards (See [1.1.2]).

#### 3.3 Tests

**3.3.1** Type tests are to be carried out on a prototype machine or on the first of a batch of machines, and routine tests carried out on subsequent machines in accordance with Tab 1.

Note 1: Test requirements may differ for shaft generators, special purpose machines and machines of novel construction.

**Table 1 : Tests to be carried out on electrical rotating machines**

No.	Tests	a.c. Generators		Motors	
		Type test (1)	Routine test (2)	Type test (1)	Routine test (2)
1	Examination of the technical documentation, as appropriate, and visual inspection	X	X	X	X
2	Insulation resistance measurement	X	X	X	X
3	Winding resistance measurement	X	X	X	X
4	Verification of the voltage regulation system	X	X (3)		
5	Rated load test and temperature rise measurement	X		X	
6	Overload/overcurrent test	X	X (4)	X	X (4)
7	Verification of steady short-circuit conditions (5)	X			
8	Overspeed test	X	X	X (6)	X (6)
9	Dielectric strength test	X	X	X	X
10	No load test	X	X	X	X
11	Verification of degree of protection	X		X	
12	Verification of bearings	X	X	X	X

(1) Type tests on prototype machine or tests on at least the first of a batch of machines.  
 (2) The report on routinely tested machines is to contain the Manufacturer’s serial number of the machine which has been type tested and the test result.  
 (3) Only functional test of voltage regulator system.  
 (4) Only applicable for machine of essential services rated above 100kW/kVA.  
 (5) Verification of steady short circuit condition applies to synchronous generators only.  
 (6) Not applicable for squirrel cage motors.

Table 2 : Minimum insulation resistance

Rated voltage $U_n$ , in V	Minimum test voltage, in V	Minimum insulation resistance, in $M\Omega$
$U_n = 250$	$2 U_n$	1
$250 < U_n \leq 1000$	500	1
$1000 < U_n \leq 7200$	1000	$U_n/1000 + 1$
$7200 < U_n \leq 15000$	5000	$U_n/1000 + 1$

## 4 Description of the test

### 4.1 Examination of the technical documentation, as appropriate, and visual inspection

#### 4.1.1 Examination of the technical documentation

Technical documentation of machines rated at 100kW (kVA) and over is to be available for examination by the Surveyor.

#### 4.1.2 Visual inspection

A visual examination of the machine is to be made to ensure, as far as is practicable, that it complies with the technical documentation.

### 4.2 Insulation resistance measurement

4.2.1 Immediately after the high voltage tests the insulation resistances are to be measured using a direct current insulation tester between:

- all current carrying parts connected together and earth,
- all current carrying parts of different polarity or phase, where both ends of each polarity or phase are individually accessible.

The minimum values of test voltages and corresponding insulation resistances are given in Tab 2. The insulation resistance is to be measured close to the operating temperature, or an appropriate method of calculation is to be used.

### 4.3 Winding resistance measurement

4.3.1 The resistances of the machine windings are to be measured and recorded using an appropriate bridge method or voltage and current method.

### 4.4 Verification of the voltage regulation system

4.4.1 The alternating current generator, together with its voltage regulation system, is to be verified in such a way that, at all loads from no load running to full load, the rated voltage at the rated power factor is maintained under steady conditions within  $\pm 2.5\%$ . These limits may be increased to  $\pm 3.5\%$  for emergency sets.

4.4.2 When the generator is driven at rated speed, giving its rated voltage, and is subjected to a sudden change of symmetrical load within the limits of specified current and

power factor, the voltage is not to fall below 85% nor exceed 120% of the rated voltage

4.4.3 The voltage of the generator is then to be restored to within plus or minus 3% of the rated voltage for the main generator sets in not more than 1.5 s. For emergency sets, these values may be increased to plus or minus 4% in not more than 5 s.

4.4.4 In the absence of precise information concerning the maximum values of the sudden loads, the following conditions may be assumed: 60% of the rated current with a power factor of between 0.4 lagging and zero to be suddenly switched on with the generator running at no load, and then switched off after steady - state conditions have been reached.

### 4.5 Rated load test and temperature rise measurements

#### 4.5.1

The temperature rises are to be measured at the rated output, voltage and frequency and for the duty for which the machine is rated and marked in accordance with the testing methods specified in IEC Publication 60034-1, or by means of a combination of other tests.

The limits of temperature rise are those specified in Table 6 of IEC Publication 60034-1 adjusted as necessary for the ambient reference temperatures specified in Sec 2.

### 4.6 Overload/overcurrent tests

4.6.1 Overload test is to be carried out as a type test for generators as proof of overload capability of generators and the excitation system, for motors as proof of momentary excess torque as required in IEC Publication 60034-1. The overload test can be replaced at a routine test by an overcurrent test. The overcurrent test is to be proof of the current capability of the windings, wires, connections etc. of each machine. The overcurrent test can be performed at reduced speed (motors) or at short-circuit (generators).

4.6.2 In the case of machines for special uses (e.g. for windlasses), overload values other than the above may be considered.

### 4.7 Verification of steady short-circuit conditions

4.7.1 It is to be verified that under steady state short-circuit conditions, the generator with its voltage regulating system is capable of maintaining, without sustaining any damage, a

current of at least three times the rated current for a duration of at least 2 s or, where precise data is available, for a duration of any time delay which may be fitted in a tripping device for discrimination purposes.

#### **4.8 Overspeed test**

**4.8.1** Machines are to withstand the overspeed test as specified in IEC Publication 60034-1. This test is not applicable for squirrel cage motors.

#### **4.9 Dielectric strength test**

**4.9.1** New and completed rotating machines are to withstand a dielectric test as specified in IEC Publication 60034-1.

**4.9.2** For high voltage machines an impulse test is to be carried out on the coils according to Sec 13.

**4.9.3** When it is necessary to perform an additional high voltage test, this is to be carried out after any further drying, with a test voltage of 80% of that specified in IEC Publication 60034-1.

**4.9.4** Completely rewound windings of used machines are to be tested with the full test voltage applied in the case of new machines.

**4.9.5** Partially rewound windings are to be tested at 75% of the test voltage required for new machines. Prior to the test, the old part of the winding is to be carefully cleaned and dried.

**4.9.6** Following cleaning and drying, overhauled machines are to be subjected to a test at a voltage equal to

1,5 times the rated voltage, with a minimum of 500 V if the rated voltage is less than 100 V, and with a minimum of 1000 V if the rated voltage is equal to or greater than 100 V.

**4.9.7** A repetition of the high voltage test for groups of machines and apparatus is to be avoided if possible, but if a test on an assembled group of several pieces of new apparatus, each of which has previously passed its high voltage test, is performed, the test voltage to be applied to such assembled group is 80% of the lowest test voltage appropriate for any part of the group.

Note 1: For windings of one or more machines connected together electrically, the voltage to be considered is the maximum voltage that occurs in relation to earth.

#### **4.10 No load test**

**4.10.1** Machines are to be operated at no load and rated speed whilst being supplied at rated voltage and frequency as a motor while generators are to be driven by a suitable means and excited to give rated terminal voltage.

During the running test, the vibration of the machine and operation of the bearing lubrication system, if appropriate, are to be checked.

#### **4.11 Verification of degree of protection**

**4.11.1** As specified in IEC Publication 60034-5.

#### **4.12 Verification of bearings**

**4.12.1** Upon completion of the above tests, machines which have sleeve bearings are to be opened upon request for examination by the Surveyor, to establish that the shaft is correctly seated in the bearing shells.

## SECTION 5

## TRANSFORMERS

### 1 Constructional and operational requirements

#### 1.1 Construction

**1.1.1** Transformers, except those for motor starting, are to be double wound (two or more separate windings).

**1.1.2** Transformers are normally to be of the dry, air-cooled type.

**1.1.3** When a forced air cooling system is used, an alarm is to be activated in the event of its failure.

**1.1.4** Liquid-cooled transformers may be used provided that:

- the liquid is non-toxic and of a type which does not readily support combustion
- the construction is such that the liquid is not spilled in inclined position
- temperature and pressure relief devices with an alarm are installed
- drip trays or other suitable arrangements for collecting the liquid from leakages are provided
- a liquid gauge indicating the normal liquid level range is fitted.

**1.1.5** Transformers are to have enclosures with a degree of protection in accordance with Sec 3, Tab 2.

#### 1.2 Terminals

**1.2.1** Suitable fixed terminal connections are to be provided in an accessible position with sufficient space for convenient connection of the external cables.

**1.2.2** Terminals are to be clearly identified.

#### 1.3 Short-circuit conditions and parallel operation

**1.3.1** In determining the voltage ratio and the impedance voltage of transformers, account is to be taken of the total permitted voltage drop from the main switchboard's busbars to the consumers (see Sec 3, [8.11.4]).

**1.3.2** Transformers are to be constructed to withstand, without damage, the thermal and mechanical effects of a secondary terminal short-circuit for 2 s, with rated primary voltage and frequency.

For transformers of 1 MVA and over, this is to be justified with appropriate tests or documentation.

**1.3.3** When transformers are so arranged that their secondary windings may be connected in parallel, their winding

connections are to be compatible, their rated voltage ratios are to be equal (with tolerances allowed) and their short-circuit impedance values, expressed as a percentage, are to have a ratio within 0,9 to 1,1.

When transformers are intended for operation in parallel, the rated power of the smallest transformer in the group is to be not less than half of the rated power of the largest transformer in the group.

#### 1.4 Electrical insulation and temperature rise

**1.4.1** Insulating materials for windings and other current carrying parts are to comply with the requirements of Sec 2.

**1.4.2** All windings of air-cooled transformers are to be suitably treated to resist moisture, air salt mist and oil vapours.

**1.4.3** The permissible limits of temperature rise with an ambient air temperature of 45°C for (natural or forced) air-cooled transformers are given in Tab 1. The temperature rises shown for windings refer to measurement by the resistance method while those for the core refer to the thermometer method.

**1.4.4** For dry-type transformers cooled with an external liquid cooling system, the permissible limits of temperature rise with a sea water temperature of 32°C are 13°C higher than those specified in Tab 1.

**1.4.5** For liquid-cooled transformers, the following temperature rises measured by the resistance method apply:

- 55°C where the fluid is cooled by air
- 68°C where the fluid is cooled by water.

#### 1.5 Insulation tests

**1.5.1** Transformers are to be subjected to a high voltage test in accordance with the procedure defined in Sec 4, [4.9].

**1.5.2** The test voltage is to be applied between each winding under test and the other windings not under test, core and enclosure all connected together.

Single-phase transformers for use in a polyphase group are to be tested in accordance with the requirements applicable to that group.

**1.5.3** The r.m.s. value of the test voltage is to be equal to  $2U + 1000$  V, with a minimum of 2500 V, where U is the rated voltage of the winding. The full voltage is to be maintained for 1 minute.

**1.5.4** Partially rewound windings are to be tested at 75% of the test voltage required for new machines.

**Table 1 : Temperature rise limits for transformers**

No.	Part of machine	Temperature rise by class of insulation, in °C				
		A	E	B	F	H
1	Windings	55	70	75	95	120
2	Cores and other parts: a) in contact with the windings b) not in contact with the windings	a) the same values as for the windings b) in no case is the temperature to reach values such as to damage either the core itself or other adjacent parts or materials				

**1.5.5** The insulation resistance of a new, clean and dry transformer, measured after the temperature rise test has been carried out (at or near operating temperature) at a voltage equal to 500 V d.c., is to be not less than 5 MΩ.

**1.5.6** Transformers are to be subjected to an induced voltage insulation test by applying to the terminals of the winding under test a voltage equal to twice the rated voltage. The duration of the test is to be 60 s for any test frequency  $f_p$  up to and including twice the rated frequency  $f_n$ .

If the test frequency exceeds twice the rated frequency, the test time in seconds will be  $120 f_n/f_p$  with a minimum of 15 s.

## 2 Testing

### 2.1 General

**2.1.1** On new transformers intended for essential services the tests specified in [2.2] are to be carried out.

**2.1.2** The manufacturer is to issue a test report giving, inter alia, information concerning the construction, type, serial number, insulation class and all other technical data relevant to the transformer, as well as the results of the tests required.

Such test reports are to be made available to the Society.

**2.1.3** In the case of transformers which are completely identical in rating and in all other constructional details, it will be acceptable for the temperature rise test to be performed on only one transformer.

The results of this test and the serial number of the tested transformer are to be inserted in the test reports for the other transformers.

**2.1.4** Where the test procedure is not specified, the requirements of IEC 60076 and 60726 apply.

**2.1.5** The tests and, if appropriate, manufacture of transformers of 100 kVA and over (60 kVA when single phase) intended for essential services are to be attended by a Surveyor of the Society.

Transformers of 5 kVA up to the limit specified above are approved on a case by case basis, at the discretion of the Society, subject to the submission of adequate documentation and routine tests.

Note 1: An alternative inspection scheme may be agreed by the Society with the Manufacturer whereby the attendance of the Surveyor will not be required as indicated above.

### 2.2 Tests on transformers

**2.2.1** Tests to be carried out on transformers are specified in Tab 2.

**Table 2 : Tests to be carried out on transformers**

No.	Tests	Type test (1)	Routine test (2)
1	Examination of the technical documentation, as appropriate, and visual inspection (3)	X	X
2	Insulation resistance measurement	X	X
3	High voltage test	X	X
4	Temperature rise measurement	X	
5	Induced voltage test	X	X
6	Voltage ratio	X	X

(1) Type test on prototype transformer or test on at least the first batch of transformers.

(2) The certificates of transformers routine tested are to contain the manufacturer's serial number of the transformer which has been type tested and the test result.

(3) A visual examination is to be made of the transformer to ensure, as far as practicable, that it complies with technical documentation.

## SECTION 6

## SEMICONDUCTOR CONVERTORS

### 1 Constructional and operational requirements

#### 1.1 Construction

**1.1.1** Semiconductor convertors are generally to comply with the requirements for switchgear assemblies (see Sec 8).

**1.1.2** The monitoring and control circuits are generally to comply with the requirements of Chapter 3.

**1.1.3** For liquid-cooled convertors the following provisions are to be satisfied:

- liquid is to be non-toxic and of low flammability
- drip trays or other suitable means are to be provided to contain any liquid leakages
- the resistivity of the cooling fluid in direct contact with semiconductor or other current carrying parts is to be monitored and an alarm initiated if the resistivity is outside the specified limits.

**1.1.4** Where forced cooling is used, the temperature of the heated cooling medium is to be monitored.

If the temperature exceeds a preset value an alarm is to be given and the shutdown of the convertor is to be activated.

**1.1.5** Where forced (air or liquid) cooling is provided, it is to be so arranged that the convertor cannot be or remain loaded unless effective cooling is maintained.

Alternatively, other effective means of protection against overtemperature may be provided.

**1.1.6** Stacks of semiconductor elements, and other equipment such as fuses, or control and firing circuit boards etc., are to be so arranged that they can be removed from equipment without dismantling the complete unit.

**1.1.7** Semiconductor convertors are to be rated for the required duty having regard to the peak loads, system transient and overvoltage and to be dimensioned so as to withstand the maximum short-circuit currents foreseen at the point of installation for the time necessary to trip the protection of the circuits they supply.

#### 1.2 Protection

**1.2.1** Semiconductor elements are to be protected against short-circuit by means of devices suitable for the point of installation in the network.

**1.2.2** Overcurrent and overvoltage protection is to be installed to protect the convertor. When the semiconductor convertor is designed to work as an inverter supplying the network in transient periods, precautions necessary to limit the current are to be taken.

**1.2.3** Semiconductor convertors are not to cause distortion in the voltage wave form of the power supply at levels exceeding the voltage wave form tolerances at the other user input terminals (see Sec 2, [2.2]).

**1.2.4** An alarm is to be provided for tripping of protective devices against overvoltages and overcurrents in electric propulsion convertors and for convertors for the emergency source of power.

#### 1.3 Parallel operation with other power sources

**1.3.1** For convertors arranged to operate in parallel with other power sources, load sharing is to be such that under normal operating conditions overloading of any unit does not occur and the combination of paralleled equipment is stable.

#### 1.4 Temperature rise

**1.4.1** The permissible limit of temperature rise of the enclosure of the semiconductors is to be assessed on the basis of an ambient air temperature of 45°C or sea water temperature of 32°C for water-cooled elements, taking into account its specified maximum permissible temperature value.

**1.4.2** The value of the maximum permissible temperature of the elements at the point where this can be measured (point of reference) is to be stated by the manufacturer.

**1.4.3** The value of the mean rated current of the semiconductor element is to be stated by the manufacturer.

#### 1.5 Insulation test

**1.5.1** The test procedure is that specified in IEC Publication 60146.

**1.5.2** The effective value of the test voltage for the insulation test is to be as shown in Tab 1.



**Table 1 : Test voltages for high voltage test on static converters**

$\frac{U_m}{\sqrt{2}} = U$ in V (1)	Test voltage V
$U \leq 60$	600
$60 < U \leq 90$	900
$90 < U$	$2U + 1000$ (at least 2000)
(1) $U_m$ : highest crest value to be expected between any pair of terminals.	

## 2 Testing

### 2.1 General

**2.1.1** Convertors intended for essential services are to be subjected to the tests stated in [2.2].

**2.1.2** The manufacturer is to issue a test report giving information on the construction, type, serial number and all

technical data relevant to the convertor, as well as the results of the tests required.

Note 1: An alternative inspection scheme may be agreed by the Society with the Manufacturer whereby the attendance of the Surveyor will not be required as indicated above.

**2.1.3** In the case of convertors which are completely identical in rating and in all other constructional details, it will be acceptable for the rated current test and temperature rise measurement stipulated in [2.2] not to be repeated.

**2.1.4** The tests and, if appropriate, manufacture of convertors of 50 kVA and over intended for essential services are to be attended by a Surveyor of the Society.

### 2.2 Tests on convertors

**2.2.1** Convertors are to be subjected to tests in accordance with Tab 2.

Type tests are the tests to be carried out on a prototype convertor or the first of a batch of convertors, and routine tests are the tests to be carried out on subsequent convertors of a particular type.

**2.2.2** Final approval of convertors is to include complete function tests after installation on board, performed with all ship's systems in operation and in all characteristic load conditions.

**Table 2 : Tests to be carried out on static converters**

No.	Tests	Type test (1)	Routine test (2)
1	Examination of the technical documentation, as appropriate, and visual inspection (3) including check of earth continuity	X	X
2	Light load function test to verify all basic and auxiliary functions	X	X
3	Rated current test	X	
4	Temperature rise measurement	X	
5	Insulation test (dielectric strength test and insulation resistance measurement)	X	X
6	Protection of the convertors in case of failure of forced cooling system	X	X
(1) Type test on prototype convertor or test on at least the first batch of convertors.			
(2) The certificates of convertors routine tested are to contain the manufacturer's serial number of the convertor which has been type tested and the test result.			
(3) A visual examination is to be made of the convertor to ensure, as far as practicable, that it complies with technical documentation.			

## SECTION 7

# STORAGE BATTERIES, CHARGERS AND UNINTERRUPTIBLE POWER SYSTEMS

### 1 Constructional requirements for batteries

#### 1.1 General

**1.1.1** The requirements of this Section apply to permanently installed storage batteries (not to portable batteries).

**1.1.2** Storage batteries may be of the lead-acid or nickel-alkaline type, due consideration being given to the suitability for any specific application.

Other types of storage batteries of satisfactorily proven design (e.g. silver/zinc) may be accepted provided they are suitable for shipboard use to the satisfaction of the Society.

**1.1.3** Cells are to be assembled in suitable crates or trays equipped with handles for convenient lifting.

#### 1.2 Vented batteries

**1.2.1** Vented batteries are those in which the electrolyte can be replaced and freely releases gas during periods of charge and overcharge.

**1.2.2** Vented batteries are to be constructed to withstand the movement of the ship and the atmosphere (salt mist, oil etc.) to which they may be exposed.

**1.2.3** Battery cells are to be so constructed as to prevent spilling of electrolyte at any inclination of the battery up to 40° from the vertical.

**1.2.4** It is to be possible to check the electrolyte level and the pH.

#### 1.3 Valve-regulated sealed batteries

**1.3.1** Valve-regulated sealed batteries are batteries whose cells are closed under normal conditions but which have an arrangement which allows the escape of gas if the internal pressure exceeds a predetermined value. The cells cannot normally receive addition to the electrolyte.

Note 1: The cells of batteries which are marketed as “sealed” or “maintenance free” are fitted with a pressure relief valve as a safety precaution to enable uncombined gas to be vented to the atmosphere; they should more properly be referred to as valve-regulated sealed batteries. In some circumstances the quantity of gas vented

can be up to 25% of the equivalent vented design. The design is to take into consideration provision for proper ventilation.

**1.3.2** Cell design is to minimise risks of release of gas under normal and abnormal conditions.

#### 1.4 Tests on batteries

**1.4.1** The battery autonomy is to be verified on board in accordance with the operating conditions.

## 2 Constructional requirements for chargers

### 2.1 Characteristics

**2.1.1** Chargers are to be adequate for the batteries for which they are intended and provided with a voltage regulator.

**2.1.2** In the absence of indications regarding its operation, the battery charger is to be such that the completely discharged battery can be recharged to 80% capacity within a period of 10 hours without exceeding the maximum permissible charging current. A charging rate other than the above (e.g. fully charged within 6 hours for batteries for starting of motors) may be required in relation to the use of the battery.

**2.1.3** For floating service or for any other condition where the load is connected to the battery while it is on charge, the maximum battery voltage is not to exceed the safe value of any connected apparatus.

Note 1: Consideration is to be given to the temperature variation of the batteries.

**2.1.4** The battery charger is to be designed so that the charging current is set within the maximum current allowed by the manufacturer when the battery is discharged and the floating current to keep the battery fully charged.

**2.1.5** Trickle charging to neutralise internal losses is to be provided. An indication is to be provided to indicate a charging voltage being present at the charging unit.

**2.1.6** Protection against reversal of the charging current is to be provided.

**2.1.7** Battery chargers are to be constructed to simplify maintenance operation. Indications are to be provided to visualise the proper operation of the charger and for troubleshooting.

**2.2 Tests on chargers**

**2.2.1** Battery chargers are to be subjected to tests in accordance with Tab 1.

Type tests are the tests to be carried out on a prototype charger or the first of a batch of chargers, and routine tests

are the tests to be carried out on subsequent chargers of a particular type.

**2.2.2** The tests of battery chargers of 50 kVA and over intended for essential services are to be attended by a Surveyor of the Society.

Note 1: An alternative inspection scheme may be agreed by the Society with the Manufacturer whereby the attendance of the Surveyor will not be required as indicated above.

**Table 1 : Tests to be carried out on battery chargers**

No.	Tests	Type test (1)	Routine test (2)
1	Examination of the technical documentation, as appropriate, and visual inspection (3) including check of earth continuity	X	X
2	Functional tests (current and voltage regulation, quick, slow, floating charge, alarms)	X	X
3	Temperature rise measurement	X	
4	Insulation test (dielectric strength test and insulation resistance measurement)	X	X

(1) Type test on prototype battery charger or test on at least the first batch of battery chargers.  
 (2) The certificates of battery chargers routine tested are to contain the manufacturer's serial number of the battery charger which has been type tested and the test result.  
 (3) A visual examination is to be made of the battery charger to ensure, as far as practicable, that it complies with technical documentation.

**3 Uninterruptible power system (UPS) units as alternative and/or transitional power**

**3.1 Application**

**3.1.1** These requirements for UPS units apply when providing an alternative power supply or transitional power supply to services as defined in SOLAS Chapter II-1, Regulations 42 and 43.

A UPS unit complying with these requirements may provide an alternative power supply as an accumulator battery in terms of being an independent power supply for services defined in SOLAS Chapter II-1, Regulation 42, 2.3 or 43, 2.4.

**3.2 Definitions**

**3.2.1**

**Uninterruptible Power System (UPS)** - combination of converters, switches and energy storage means, for example batteries, constituting a power system for maintaining continuity of load power in case of input power failure

**Off-line UPS unit** - a UPS unit where under normal operation the output load is powered from the bypass line (raw mains) and only transferred to the inverter if the bypass supply fails or goes outside preset limits. This transition will invariably result in a brief (typically 2 to 10 ms) break in the load supply.

**Line interactive UPS unit** - an off-line UPS unit where the bypass line switches to stored energy power when the input power goes outside the preset voltage and frequency limits.

**On-line UPS unit** - a UPS unit where, under normal operation, the output load is powered from the inverter and will therefore continue to operate without a break in the event of the supply input failing or going outside preset limits.

**3.3 Design and construction**

**3.3.1** UPS units are to be constructed in accordance with IEC 62040 or an acceptable and relevant national or international standard.

**3.3.2** The operation of the UPS is not to depend upon external services.

**3.3.3** The type of UPS unit employed, whether off-line, line interactive or on-line, is to be appropriate to the power supply requirements of the connected load equipment.

**3.3.4** An external bypass is to be provided.

**3.3.5** The UPS unit is to be monitored and audible and visual alarm is to be given in a normally attended location for:

- power supply failure (voltage and frequency) to the connected load,
- earth fault,
- operation of a battery protective device,
- when the battery is being discharged, and
- when the bypass is in operation for on-line UPS units.

### 3.4 Location

**3.4.1** The UPS unit is to be suitably located for use in an emergency.

**3.4.2** UPS units using valve regulated sealed batteries may be located in compartments with normal electrical equipment, provided the ventilation arrangements are in accordance with the requirements of IEC 62040 or an acceptable and relevant national or international standard.

### 3.5 Performance

**3.5.1** The output power is to be maintained for the duration required for the connected equipment as stated in SOLAS Chapter II-1, Regulation 42 or 43.

**3.5.2** No additional circuits are to be connected to the UPS unit without verification that the latter has adequate capacity. The UPS battery capacity is, at all times, to be capable of supplying the designated loads for the time specified in the regulations.

**3.5.3** On restoration of the input power, the rating of the charge unit is to be sufficient to recharge the batteries while maintaining the output supply to the load equipment.

### 3.6 Testing and survey

**3.6.1** UPS units of 50 kVA and over are to be surveyed by the Society during manufacturing and testing.

**3.6.2** Appropriate testing is to be carried out to demonstrate that the UPS unit is suitable for its intended environment. This is expected to include, as a minimum, the following tests:

- Functionality, including operation of alarms;
- Temperature rise;
- Ventilation rate;
- Battery capacity.

**3.6.3** Where the supply is to be maintained without a break following a power input failure, this is to be verified after installation by means of a practical test.

## SECTION 8

## SWITCHGEAR AND CONTROLGEAR ASSEMBLIES

### 1 Constructional requirements for main and emergency switchboards

#### 1.1 Construction

**1.1.1** Construction is to be in accordance with IEC Publication 60092-302.

**1.1.2** Where the framework, panels and doors of the enclosure are of steel, suitable measures are to be taken to prevent overheating due to the possible circulation of eddy currents.

**1.1.3** Insulating material for panels and other elements of the switchboard is at least to be moisture-resistant and flame-retardant.

**1.1.4** Switchboards are to be of dead front type, with enclosure protection according to Sec 3, Tab 2.

**1.1.5** Switchboards are to be provided with insulated handrails or handles fitted in an appropriate position at the front of the switchboard. Where access to the rear is necessary for operational or maintenance purposes, an insulated handrail or insulated handles are to be fitted.

**1.1.6** Where the aggregate capacity of generators connected to the main busbars exceeds 100 kVA, a separate cubicle for each generator is to be arranged with flame-retardant partitions between the different cubicles. Similar partitions are to be provided between the generator cubicles and outgoing circuits.

**1.1.7** Instruments, handles or push-buttons for switchgear operation are to be placed on the front of the switchboard. All other parts which require operation are to be accessible and so placed that the risk of accidental touching of live parts, or accidental making of short-circuits and earthings, is reduced as far as practicable.

**1.1.8** Where it is necessary to make provision for the opening of the doors of the switchboard, this is to be in accordance with one of the following requirements:

- a) opening is to necessitate the use of a key or tool (e.g. when it is necessary to replace a lamp or a fuse-link)
- b) all live parts which can be accidentally touched after the door has been opened are to be disconnected before the door can be opened
- c) the switchboard is to include an internal barrier or shutter with a degree of protection not less than IP2X shielding all live parts such that they cannot accidentally be touched when the door is open. It is not to be possible to remove this barrier or shutter except by the use of a key or tool.

**1.1.9** All parts of the switchboard are to be readily accessible for maintenance, repair or replacement. In particular, fuses are to be able to be safely inserted and withdrawn from their fuse-bases.

**1.1.10** Hinged doors which are to be opened for operation of equipment on the door or inside are to be provided with fixing devices for keeping them in open position.

**1.1.11** Means of isolation of the circuit-breakers of generators and other important parts of the installation are to be provided so as to permit safe maintenance while the main busbars are alive.

**1.1.12** Where components with voltage exceeding the safety voltage are mounted on hinged doors, the latter are to be electrically connected to the switchboard by means of a separate, flexible protective conductor.

**1.1.13** All measuring instruments and all monitoring and control devices are to be clearly identified with indelible labels of durable, flame-retardant material.

**1.1.14** The rating of each circuit, together with the rating of the fuse or the appropriate setting of the overload protective device (circuit-breaker, thermal relay etc.) for each circuit is to be permanently indicated at the location of the fuse or protective device.

#### 1.2 Busbars and bare conductors

**1.2.1** Busbars are to be of copper or of copper-surrounded aluminium alloy if suitable for use in the marine environment and if precautions are taken to avoid galvanic corrosion.

**1.2.2** All connections are to be so made as to inhibit corrosion.

**1.2.3** Busbars are to be dimensioned in accordance with IEC Publication 60092-302.

The mean temperature rise of busbars is not to exceed 45°C under rated current condition with an ambient air temperature of 45°C (see Sec 2, [1.2.5]) and is not to have any harmful effect on adjacent components. Higher values of temperature rise may be accepted to the satisfaction of the Society.

**1.2.4** The cross-section of neutral connection on an a.c. three-phase, four-wire system is to be at least 50% of the cross-section for the corresponding phases.

**1.2.5** Bare main busbars, excluding the conductors between the main busbars and the supply side of outgoing units, are to have the minimum clearances and creepage distances given in Tab 1.

The values shown apply to clearances and creepage distances between live parts as well as between live parts and exposed conductive parts.

**Table 1 : Clearance and creepage distances**

Rated insulation voltage a.c. r.m.s. or d.c. V	Minimum clearance mm	Minimum creepage distance mm
≤ 250	15	20
> 250 to ≤ 690	20	25
> 690	25	35

Note 1: Clearance is the distance between two conductive parts along a string stretched the shortest way between such parts. Creepage distance is the shortest distance along the surface of an insulating material between two conductive parts.

**1.2.6** Reduced values as specified in IEC Publication 60092-302 may be accepted for type tested and partially type tested assemblies.

The reference values for the evaluation of the minimum clearances and creepage distances for these assemblies are based on the following:

- pollution degree 3 (conductive pollution occurs, or dry non-conductive pollution occurs which becomes conductive due to condensation which is expected)
- overvoltage category III (distribution circuit level)
- inhomogenous field conditions (case A)
- rated operational voltage 1000 V a.c., 1500 V d.c.
- group of insulating material IIIa.

Special consideration is to be given to equipment located in spaces where a pollution degree higher than 3 is applicable, e.g. in diesel engine rooms.

**1.2.7** Busbars and other bare conductors with their supports are to be mechanically dimensioned and fixed such that they can withstand the stresses caused by short-circuits.

**1.2.8** Busbars and bare conductors are to be protected, where necessary, against falling objects (e.g. tools, fuses or other objects).

### 1.3 Internal wiring

**1.3.1** Insulated conductors for internal wiring of auxiliary circuits of switchboards are to be constructed in accordance with Sec 9, [1.1.5].

**1.3.2** All insulated conductors provided for in [1.3.1] are to be of flexible construction and of the stranded type.

**1.3.3** Connections from busbars to protective devices are to be as short as possible. They are to be laid and secured in such a way to minimise the risk of a short-circuit.

**1.3.4** All conductors are to be secured to prevent vibration and are to be kept away from sharp edges.

**1.3.5** Connections leading to indicating and control instruments or apparatus mounted in doors are to be installed

such that they cannot be mechanically damaged due to movement of the doors.

**1.3.6** Non-metallic trays for internal wiring of switchboards are to be of flame-retardant material.

**1.3.7** Control circuits are to be installed and protected such that they cannot be damaged by arcs from the protective devices.

**1.3.8** Where foreseen, fixed terminal connectors for connection of the external cables are to be arranged in readily accessible positions.

### 1.4 Switchgear and controlgear

**1.4.1** Switchgear and controlgear are to comply with IEC 60947 series and to be type tested or type approved when required in accordance with Sec 15.

**1.4.2** The characteristics of switchgear, controlgear and protective devices for the various consumers are to be in compliance with Sec 3, [6].

### 1.5 Auxiliary circuits

**1.5.1** Auxiliary circuits are to be designed in such a manner that, as far as practicable, faults in such circuits do not impair the safety of the system. In particular, control circuits are to be designed so as to limit the dangers resulting from a fault between the control circuit and earth (e.g. inadvertent operation or malfunction of a component in the installation), also taking account of the earthing system of their supply.

**1.5.2** Auxiliary circuits of essential systems are to be independent of other auxiliary circuits.

**1.5.3** Common auxiliary circuits for groups of consumers are permitted only when the failure of one consumer jeopardises the operation of the entire system to which it belongs.

**1.5.4** Auxiliary circuits are to be branched off from the main circuit in which the relevant switchgear is used.

**1.5.5** The supply of auxiliary circuits by specifically arranged control distribution systems will be specially considered by the Society.

**1.5.6** Means are to be provided for isolating the auxiliary circuits as well when the main circuit is isolated (e.g. for maintenance purposes).

**1.5.7** For the protection of auxiliary circuits see Sec 3, [6.13].

### 1.6 Instruments

**1.6.1** The upper limit of the scale of every voltmeter is to be not less than 120% of the rated voltage of the circuit in which it is installed.

**1.6.2** The upper limit of the scale of every ammeter is to be not less than 130% of the normal rating of the circuit in which it is installed.

**1.6.3** The upper limit of the scale of every wattmeter is to be not less than 120% of the rated voltage of the circuit in which it is installed.

**1.6.4** Wattmeters for use with a.c. generators which may be operated in parallel are to be capable of indicating 15% reverse power.

**1.6.5** For wattmeters using one current circuit only, the measurement of the current of all generators is to be made in the same phase.

**1.6.6** The rated value of the measure read, at full load, is to be clearly indicated on the scales of instruments.

**1.6.7** Frequency meters are to have a scale at least  $\pm 5\%$  of the nominal frequency.

**1.6.8** The secondary windings of instrument transformers are to be earthed.

**1.6.9** Each a.c. generator not operated in parallel is to be provided with:

- 1 voltmeter
- 1 frequency meter
- 1 ammeter in each phase or 1 ammeter with a selector switch to enable the current in each phase to be read
- 1 three-phase wattmeter in the case of generators rated more than 50 kVA.

**1.6.10** Each a.c. generator operated in parallel is to be provided with:

- 1 three-phase wattmeter
- 1 ammeter in each phase or 1 ammeter with a selector switch to enable the current in each phase to be read.

**1.6.11** For paralleling purposes the following are to be provided:

- 2 voltmeters
- 2 frequency meters
- 1 synchroscope and synchronising indicating lamps or equivalent means.

A switch is to be provided to enable one voltmeter and one frequency meter to be connected to each generator before the latter is connected to the busbars.

The other voltmeter and frequency meter are to be permanently connected to the busbars.

**1.6.12** Each secondary distribution system is to be provided with one voltmeter.

**1.6.13** Switchboards are to be fitted with means for monitoring the insulation level of insulated distribution systems as stipulated in Sec 3, [3.2.1].

**1.6.14** The main switchboard is to be fitted with a voltmeter or signal lamp indicating that the cable between the

shore-connection box and the main switchboard is energised (see Sec 3, [3.6.7]).

**1.6.15** For each d.c. power source (e.g. convertors, rectifiers and batteries), one voltmeter and one ammeter are to be provided, except for d.c. power sources for starting devices (e.g. starting motor for emergency generator).

## 2 Constructional requirements for section boards and distribution boards

### 2.1 Construction

**2.1.1** Section boards and distribution boards are to be constructed, insofar as applicable, as specified for main and emergency switchboards.

**2.1.2** All parts which require operation in normal use are to be placed on the front.

**2.1.3** Distribution switchboards which are provided with two or more supply circuits arranged for automatic standby connection are to be provided with positive indication of which of the circuits is feeding the switchboard.

## 3 Testing

### 3.1 General

**3.1.1** Switchboards are to be subjected to the tests specified from [3.2] to [3.4].

**3.1.2** The manufacturer is to issue the relative test reports providing information concerning the construction, serial number and technical data relevant to the switchboard, as well as the results of the tests required.

**3.1.3** The tests are to be carried out prior to installation on board.

**3.1.4** The test procedures are as specified in IEC Publication 60092-302.

**3.1.5** The attendance of the Surveyor is not required for low voltage distribution panels and single starters having nominal current of 100 A or less, except those intended for steering gear motors.

### 3.2 Inspection of equipment, check of wiring and electrical operation test

**3.2.1** It is to be verified that the switchboard:

- complies with the approved drawings
- maintains the prescribed degree of protection
- is constructed in accordance with the relevant constructional requirements, in particular as regards creepage and clearance distances.

**3.2.2** The connections, especially screwed or bolted connections, are to be checked for adequate contact, possibly by random tests.

**3.2.3** Depending on the complexity of the switchboard it may be necessary to carry out an electrical functioning test. The test procedure and the number of tests depend on whether or not the switchboard includes complicated interlocks, sequence control facilities, etc. In some cases it may be necessary to conduct or repeat this test following installation on board.

### 3.3 High voltage test

**3.3.1** The test is to be performed with alternating voltage at a frequency between 25 and 100 Hz of approximately sinusoidal form.

**3.3.2** The test voltage is to be applied:

- between all live parts connected together and earth
- between each polarity and all the other polarities connected to earth for the test.

During the high voltage test, measuring instruments, ancillary apparatus and electronic devices may be disconnected and tested separately in accordance with the appropriate requirements.

**3.3.3** The test voltage at the moment of application is not to exceed half of the prescribed value. It is then to be increased steadily within a few seconds to its full value. The prescribed test voltage is to be maintained for 1 minute.

**3.3.4** The value of the test voltage for main and auxiliary circuits is given in Tab 2 and Tab 3.

### 3.4 Measurement of insulation resistance

**3.4.1** Immediately after the high voltage test, the insulation resistance is to be measured using a device with a direct current voltage of at least 500 V.

**3.4.2** The insulation resistance between all current carrying parts and earth (and between each polarity and the other polarities) is to be at least equal to 1 MΩ.

**Table 2 : Test voltages for main circuits**

Rated insulation voltage $U_i$ V	Test voltage c.a (r.m.s.) V
$U_i \leq 60$	1000
$60 < U_i \leq 300$	2000
$300 < U_i \leq 660$	2500
$660 < U_i \leq 800$	3000
$800 < U_i \leq 1000$	3500

**Table 3 : Test voltage for auxiliary circuits**

Rated insulation voltage $U_i$ V	Test voltage c.a (r.m.s.) V
$U_i \leq 12$	250
$12 < U_i \leq 60$	500
$U_i > 60$	$2 U_i + 1000$ (at least 1500)



## SECTION 9

## CABLES

### 1 Constructional requirements

#### 1.1 Construction

**1.1.1** Cables manufactured in accordance with the relevant recommendations of IEC Publications 60092-350, 60092-351, 60092-352, 60092-353, 60092-354, 60092-359, 60092-373, 60092-374, 60092-375 and 60092-376 are acceptable to the Society provided that they are tested as specified in this Chapter.

**1.1.2** Mineral-insulated cables are to be constructed according to IEC Publication 60702.

**1.1.3** Optical fibre cables are to be constructed in accordance with IEC Publication 60794.

**1.1.4** Flexible cables constructed according to national standards will be specially considered by the Society.

**1.1.5** Cables manufactured and tested to standards other than those specified in [1.1.1] will be accepted provided they are in accordance with an acceptable and relevant international or national standard.

**1.1.6** Insulated wiring for auxiliary circuits of switchboards may be constituted by cables with a single conductor of the stranded type for all sections, PVC- or rubber-insulated in accordance with the Publications cited in [1.1.1] and without further protection.

The insulated wiring is to be at least of the flame-retardant type according to IEC Publication 60332-1. Equivalent types of flame-retardant switchboard wires will be specially considered by the Society.

#### 1.2 Conductors

**1.2.1** Conductors are to be of annealed electrolytic copper with a resistivity not exceeding  $17,241 \Omega \text{ mm}^2/\text{km}$  at  $20^\circ\text{C}$  according to IEC 60228.

**1.2.2** Individual conductor wires of rubber-insulated cables are to be tinned or coated with a suitable alloy.

**1.2.3** All conductors are to be stranded, except for cables of nominal cross-sectional area  $2,5 \text{ mm}^2$  and less (provided that adequate flexibility of the finished cable is assured).

**1.2.4** For the minimum nominal cross-sectional areas permitted, see Sec 3, [8.10].

#### 1.3 Insulating materials

**1.3.1** The materials used for insulation are to comply with IEC Publication 60092-351 and to have the thicknesses specified for each type of cable in the relevant standard.

The maximum permissible rated temperature is specified for the various materials.

**1.3.2** Materials and thicknesses other than those in [1.3.1] will be specially considered by the Society.

#### 1.4 Inner covering, fillers and binders

**1.4.1** The cores of a multicore cable are to be laid up. The spaces between the cores are to be filled so as to obtain an assembly having an essentially circular cross-section. The filling may be omitted in multicore cables having a conductor cross-sectional area not exceeding  $4 \text{ mm}^2$ .

When a non-metallic sheath is applied directly over the inner covering or the fillers, it may substitute partially for the inner covering or fillers.

**1.4.2** The materials used, the binders and the thicknesses of the inner coverings are generally to be in accordance with IEC Publications of the series 60092-3., in relation to the type of cable.

#### 1.5 Protective coverings (armour and sheath)

**1.5.1** Metallic armour, if not otherwise protected against corrosion, is to be protected by means of a coating of protective paint (see Sec 3, [8.3]).

**1.5.2** The paint is to be non-flammable and of adequate viscosity. When dry, it is not to flake off.

**1.5.3** The materials and construction used for (metal) armour are to be in accordance with IEC Publication 60092-350 and their dimensions are to be those specified for each type of cable in the relevant standard.

**1.5.4** The materials used for sheaths are to be in accordance with IEC Publication 60092-359 and are to have the thicknesses specified for each type of cable in the relevant standard.

The quality of the materials is to be adequate to the service temperature of the cable.

**1.5.5** Materials other than those in [1.5.3] and [1.5.4] will be specially considered by the Society.

#### 1.6 Identification

**1.6.1** Each cable is to have clear means of identification so that the manufacturer can be determined.

**1.6.2** Fire non propagating cables are to be clearly labelled with indication of the standard according to which this characteristic has been verified and, if applicable, of the category to which they correspond.

**1.6.3** Fire-resisting cables are to be clearly labelled with the indication of the standard according to which this characteristic has been verified.

## 2 Testing

### 2.1 Type tests

**2.1.1** Type tests are to be in accordance with the relevant IEC 60092-3.. Series Publications and IEC 60332-1, IEC 60332-3 Category A, and IEC 60331 where applicable.

### 2.2 Routine tests

**2.2.1** Every length of finished cable is to be subjected to the tests specified in [2.2.2].

**2.2.2** The following routine tests are to be carried out:

- a) visual inspection
- b) check of conductor cross-sectional area by measuring electrical resistance

- c) high voltage test
- d) insulation resistance measurement
- e) dimensional checks (as necessary).

**2.2.3** The manufacturer is to issue a statement providing information on the type and characteristics of the cable, as well as the results of the tests required and the Type Approval Certificates.

**2.2.4** The test procedure is as specified in IEC Publication 60092-350.

**2.2.5** Power cables for electrical propulsion systems, other than internal wiring in switchboards, are to be type approved and tested for acceptance in the presence of the Surveyor. Acceptance tests are to include at least:

- a) a high voltage test
- b) insulation resistance measurement.

**2.2.6** Where an alternative scheme, e.g. a certified quality assurance system, is recognised by the Society, attendance of the Surveyor may not be required.

## SECTION 10

## MISCELLANEOUS EQUIPMENT

### 1 Switchgear and controlgear, protective devices

#### 1.1 General

**1.1.1** Switchgear and controlgear are to comply with IEC Publication 60947.

**1.1.2** For materials and construction see Sec 2, [4] and Sec 2, [5].

#### 1.2 Circuit-breakers

**1.2.1** Power-driven circuit-breakers are to be equipped with an additional separate drive operated by hand.

**1.2.2** Power circuit-breakers with a making capacity exceeding 10 kA are to be equipped with a drive which performs the make operation independently of the actuating force and speed.

**1.2.3** Where the conditions for closing the circuit-breaker are not satisfied (e.g. if the undervoltage trip is not energised), the closing mechanism is not to cause the closing of the contacts.

**1.2.4** All circuit-breakers rated more than 16 A are to be of the trip-free type, i.e. the breaking action initiated by over-current or undervoltage releases is to be fulfilled independently of the position of the manual handle or other closing devices.

#### 1.3 Protection devices

**1.3.1** Short-circuit releases are generally to be independent of energy supplied from circuits other than that to be protected. Tripping due to short-circuit is to be reliable even in the event of a total loss of voltage in the protected circuit.

**1.3.2** Short-circuit releases for generators are to be equipped with reclosing inhibitors and are to be delayed for selective tripping.

**1.3.3** Overload releases or relays are to operate reliably at any voltage variation of the supply voltage in the protected circuit.

**1.3.4** Undervoltage relays or releases are to cause the circuit-breaker to open if the voltage drops to 70%-35% of the rated voltage.

**1.3.5** Shunt releases are to ensure the disconnection of the circuit-breaker even when the supply voltage of the release drops to 85% of the rated supply voltage.

**1.3.6** The reverse power protection device is to respond to the active power regardless of the power factor, and is to operate only in the event of reverse power.

**1.3.7** Single-phase failure devices in three-phase circuits are to operate without a time lag.

**1.3.8** Insulation monitoring devices are to continuously monitor the insulation resistance to earth and trigger an alarm should the insulation resistance fall below a predetermined value.

The measuring current of such devices is not to exceed 30 mA in the event of a total short to earth.

## 2 Lighting fittings

### 2.1 Applicable requirements

**2.1.1** Lighting fittings are to comply with IEC Publications 60598 and 60092-306.

Lighting fittings complying with other standards will be specially considered by the Society.

### 2.2 Construction

**2.2.1** The temperature of terminals for connection of supplying cables is not to exceed the maximum conductor temperature permitted for the cable (see Sec 3, [8.9]).

Where necessary, luminaires are to be fitted with terminal boxes which are thermally insulated from the light source.

**2.2.2** Wires used for internal connections are to be of a temperature class which corresponds to the maximum temperature within the luminaire.

**2.2.3** The temperature rise of parts of luminaires which are in contact with the support is not to exceed 50°C. The rise is not to exceed 40°C for parts in contact with flammable materials.

**2.2.4** The temperature rise of surface parts which can easily be touched in service is not to exceed 15°C.

**2.2.5** High-power lights with higher surface temperatures than those in [2.2.2] and [2.2.3] are to be adequately protected against accidental contact.

## 3 Accessories

### 3.1 Applicable requirements

**3.1.1** Accessories are to be constructed in accordance with the relevant IEC Publications, and in particular with Publication 60092-306.

## 3.2 Construction

**3.2.1** Enclosures of accessories are to be of metal having characteristics suitable for the intended use on board, or of flame-retardant insulating material.

**3.2.2** Terminals are to be suitable for the connection of stranded conductors, except in the case of rigid conductors for mineral-insulated cables.

## 4 Plug-and-socket connections

### 4.1 Applicable requirements

**4.1.1** Plug-and-socket connections are to comply with IEC Publication 60092-306 and with the following additional standards in relation to their use:

- in accommodation spaces, day rooms and service rooms (up to 16 A, 250 V a.c.): IEC Publication 60083 or 60320, as applicable
- for power circuits (up to 250 A, 690 V a.c.): IEC Publication 60309
- for electronic switchgear: IEC Publications, e.g. 60130 and 60603
- for refrigerated containers: ISO 1496-2.

## 5 Heating and cooking appliances

### 5.1 Applicable requirements

**5.1.1** Heating and cooking appliances are to comply with the relevant IEC Publications (e.g. those of series 60335), with particular attention to IEC 60092-307.

### 5.2 General

**5.2.1** Heating elements are to be enclosed and protected with metal or refractory material.

**5.2.2** The terminals of the power supply cable are not to be subjected to a higher temperature than that permitted for the conductor of the connection cable.

**5.2.3** The temperature of parts which are to be handled in service (switch knobs, operating handles and the like) is not to exceed the following values:

- 55°C for metal parts
- 65°C for vitreous or moulded material.

### 5.3 Space heaters

**5.3.1** The casing or enclosure of heaters is to be so designed that clothing or other flammable material cannot be placed on them.

**5.3.2** The temperature of the external surface of space heaters is not to exceed 60°C.

**5.3.3** Space heaters are to be provided with a temperature limiting device without automatic reconnection which automatically trips all poles or phases not connected to

earth when the temperature exceeds the maximum permissible value.

## 5.4 Cooking appliances

**5.4.1** Live parts of cooking appliances are to be protected such that any foods or liquids which boil over or spill do not cause short-circuits or loss of insulation.

## 5.5 Fuel oil and lube oil heaters

**5.5.1** In continuous-flow fuel oil and lube oil heaters, the maximum temperature of the heating elements is to be below the boiling point of the oil.

**5.5.2** Each oil heater is to be provided with a thermostat maintaining the oil temperature at the correct level.

**5.5.3** In addition to the thermostat in [5.5.2], each oil heater is to be provided with a temperature limiting device without automatic reconnection, and with the sensing device installed as close as possible to the heating elements and permanently submerged in the liquid.

## 5.6 Water heaters

**5.6.1** Water heaters are to be provided with a thermostat and safety temperature limiter.

## 6 Cable trays/protective casings made of plastics materials

### 6.1 General requirement

**6.1.1** Cable trays/protective casings (see Note 1) made of plastic (see Note 2) materials are to be type tested (See Note 3).

Note 1: "Protective casing" means a closed cover in the form of a pipe or other closed ducts of non-circular shape.

Note 2: "Plastics" means both thermoplastic and thermosetting plastic materials with or without reinforcement, such as PVC and fibre reinforced plastics - FRP.

Note 3: Cable trays/protective casings made of plastic materials are to be type tested in accordance with IACS REC 73.

### 6.2 Installation Requirements

**6.2.1** Cable trays/protective casings made of plastics materials are to be supplemented by metallic fixing and straps such that in the event of a fire they, and the cables affixed, are prevented from falling and causing an injury to personnel and/or an obstruction to any escape route.

Note 1: When plastic cable trays/protective casings are used on open deck, they are additionally to be protected against UV light.

#### 6.2.2

The load on the cable trays/protective casings is to be within the Safe Working Load (SWL). The support spacing is to be not greater than the Manufacturer's recommendation or in excess of the spacing at the SWL test. In general it is not to exceed 2 metres.

The selection and spacing of cable tray/protective casing supports are to take into account:

- dimensions of cable trays/protective casings;
- mechanical and physical properties of their material;
- mass of cable trays/protective casings;
- loads due to weight of cables, external forces, thrust forces and vibrations;

- maximum accelerations to which the system may be subjected;
- combination of loads.

**6.2.3** The sum of the cables' total cross-sectional area, based on the cables' external diameter, is not to exceed 40% of the protective casing's internal cross-sectional area. This does not apply to a single cable in a protective casing.

## SECTION 11

## LOCATION

### 1 General

#### 1.1 Location

**1.1.1** The degree of protection of the enclosures and the environmental categories of the equipment are to be appropriate to the spaces or areas in which they are located; see Sec 3, Tab 2, Sec 3, Tab 3 and Sec 2, [5.2.2].

#### 1.2 Areas with a risk of explosion

**1.2.1** Except where the installation of equipment for explosive gas atmosphere is provided for by the Rules, electrical equipment is not to be installed where flammable gases or vapours are liable to accumulate; see Sec 3, [9].

### 2 Main electrical system

#### 2.1 Location in relation to the emergency system

**2.1.1** The arrangement of the emergency electrical system is to be such that a fire or other casualty in spaces containing the emergency source of electrical power, associated converting equipment, if any, the emergency switchboard and the emergency lighting switchboard will not render inoperative the main electric lighting system and the other primary essential services.

#### 2.2 Main switchboard

**2.2.1** The main switchboard shall be so placed relative to one main generating station that, as far as is practicable, the integrity of the normal electrical supply may be affected only by a fire or other casualty in one space.

**2.2.2** An environmental enclosure for the main switchboard, such as may be provided by a machinery control room situated within the main boundaries of the space, is not to be considered as separating switchboards from generators.

**2.2.3** The main generating station is to be situated within the machinery space, i.e. within the extreme main transverse watertight bulkheads.

**2.2.4** Any bulkhead between the extreme main transverse watertight bulkheads is not regarded as separating the equipment in the main generating station provided that there is access between the spaces.

**2.2.5** The main switchboard is to be located as close as practicable to the main generating station, within the same machinery space and the same vertical and horizontal A60 fire boundaries.

**2.2.6** Where essential services for steering and propulsion are supplied from section boards, these and any transformers, converters and similar appliances constituting an essential part of the electrical supply system are also to satisfy the above provisions.

**2.2.7** A non-required subdivision bulkhead, with sufficient access, located between the switchboard and generators, or between two or more generators, is not to be considered as separating the equipment.

### 3 Emergency electrical system

#### 3.1 Spaces for the emergency source

**3.1.1** The emergency source of electrical power, associated transforming equipment, if any, transitional source of emergency power, emergency switchboard and emergency lighting switchboard shall be located above the uppermost continuous deck and shall be readily accessible from the open deck.

They shall not be located forward of the collision bulkhead.

**3.1.2** The spaces containing the emergency source of electrical power, associated transforming equipment, if any, the transitional source of emergency electrical power and the emergency switchboard are not to be contiguous to the boundaries of machinery spaces of Category A or those spaces containing the main source of electrical power, associated transforming equipment, if any, and the main switchboard.

Where this is not practicable, the contiguous boundaries are to be Class A60.

#### 3.2 Location in relation to the main electrical system

**3.2.1** The location of the emergency source of electrical power, associated transforming equipment, if any, the transitional source of emergency power, the emergency switchboard and the emergency lighting switchboard in relation to the main source of electrical power, associated transforming equipment, if any, and the main switchboard shall be such as to ensure to the satisfaction of the Society that a fire or other casualty in the space containing the main source of electrical power, associated transforming equipment, if any, and the main switchboard or in any machinery space of Category A will not interfere with the supply, control and distribution of emergency electrical power.

**3.2.2** The arrangement of the main electrical system is to be such that a fire or other casualty in spaces containing the main source of electrical power, associated converting equipment, if any, the main switchboard and the main lighting switchboard will not render inoperative the emergency electric lighting system and the other emergency services other than those located within the spaces where the fire or casualty has occurred.

### 3.3 Emergency switchboard

**3.3.1** The emergency switchboard shall be installed as near as is practicable to the emergency source of electrical power.

**3.3.2** Where the emergency source of electrical power is a generator, the emergency switchboard shall be located in the same space unless the operation of the emergency switchboard would thereby be impaired.

### 3.4 Emergency battery

**3.4.1** No accumulator battery fitted in accordance with the provisions of Sec 3, [2.3] shall be installed in the same space as the emergency switchboard.

**3.4.2** Accumulator batteries fitted in accordance with the provisions of Sec 3, [2.3] and connected to a charging device of power of 2 kW or less may be accepted in the same space as the emergency switchboard but outside the emergency switchboard to the satisfaction of the Society.

Note 1: In case SOLAS Requirements are to be complied with, 3.4.2 does not apply.

## 4 Distribution boards

### 4.1 Distribution boards for cargo spaces and similar spaces

**4.1.1** Distribution boards containing multipole switches for the control of power and lighting circuits in bunkers and cargo spaces are to be situated outside such spaces.

### 4.2 Distribution board for navigation lights

**4.2.1** The distribution board for navigation lights is to be placed in an accessible position on the bridge.

## 5 Cable runs

### 5.1 General

**5.1.1** Cable runs are to be selected so as to be as far as practicable accessible, with the exception of single cables, situated behind walls or ceilings constructed of incombustible materials, supplying lighting fittings and socket-outlets in accommodation spaces, or cables enclosed in pipes or conduits for installation purposes.

**5.1.2** Cable runs are to be selected so as to avoid action from condensed moisture and from dripping of liquids.

**5.1.3** Connection and draw boxes are to be accessible.

**5.1.4** Cables are generally not to be installed across expansion joints.

Where this is unavoidable, however, a loop of cable of length proportional to the expansion of the joint is to be provided (see Sec 12, [7.2.2]).

### 5.2 Location of cables in relation to the risk of fire and overheating

**5.2.1** Cables and wiring serving essential or emergency power, lighting, internal communications or signals are, so far as is practicable, to be routed clear of galleys, laundries, machinery spaces of Category A and their casings and other high fire risk areas, except for supplying equipment in those spaces.

**5.2.2** When it is essential that a circuit functions for some time during a fire and it is unavoidable to carry the cable for such a circuit through a high fire risk area (e.g. cables connecting fire pumps to the emergency switchboard), the cable is to be of a fire-resistant type or adequately protected against direct exposure to fire.

**5.2.3** Main cable runs (see Note 1) and cables for the supply and control of essential services are, as far as is practicable, to be kept away from machinery parts having an increased fire risk (see Note 2) unless:

- the cables have to be connected to the subject equipment,
- the cables are protected by a steel bulkhead or deck, or
- the cables in that area are of the fire-resisting type.

Note 1: Main cable runs are for example:

- cable runs from generators and propulsion motors to main and emergency switchboards
- cable runs directly above or below main and emergency switchboards, centralised motor starter panels, section boards and centralised control panels for propulsion and essential auxiliaries.

Note 2: Machinery, machinery parts or equipment handling combustibles are considered to present an increased fire risk.

**5.2.4** Cables and wiring serving essential or emergency power, lighting, internal communications or signals are to be arranged, as far as practicable, in such a manner as to preclude their being rendered unserviceable by heating of the bulkheads that may be caused by a fire in an adjacent space.

**5.2.5** Cables are to be arranged as remote as possible from sources of heat such as hot pipes, resistors, etc. Where installation of cables near heat sources cannot be avoided, and where there is consequently a risk of damage to the cables by heat, suitable shields are to be installed, or other precautions to avoid overheating are to be taken, for example use of ventilation, heat insulation materials or special heat-resisting cables.

### 5.3 Location of cables in relation to electromagnetic interference

**5.3.1** For the installation of cables in the vicinity of radio equipment or of cables belonging to electronic control and monitoring systems, steps are to be taken in order to limit the effects of unwanted electromagnetic interference (see Ch 3, Sec 5).

### 5.4 Services with a duplicate feeder

**5.4.1** In the case of essential services requiring a duplicate supply (e.g. steering gear circuits), the supply and associated control cables are to follow different routes which are to be as far apart as practicable, separated both vertically and horizontally.

### 5.5 Emergency circuits

**5.5.1** Cables supplying emergency circuits are not to run through spaces containing the main source of electrical power, associated transforming equipment, if any, the main switchboard and the main lighting switchboard, except for cables supplying emergency equipment located within such spaces (see [3.2.2]).

## 6 Storage batteries

### 6.1 General

**6.1.1** Batteries are to be located where they are not exposed to excessive heat, extreme cold, spray, steam or other conditions which would impair performance or accelerate deterioration. They are to be installed in such a way that no damage may be caused to surrounding appliances by the vapours generated.

**6.1.2** Storage batteries are to be suitably housed, and compartments (rooms, lockers or boxes) used primarily for their accommodation are to be properly constructed and efficiently ventilated so as to prevent accumulation of flammable gas.

**6.1.3** Starter batteries are to be located as close as practicable to the engine or engines served.

**6.1.4** Accumulator batteries shall not be located in sleeping quarters except where hermetically sealed to the satisfaction of the Society.

**6.1.5** Lead-acid batteries and alkaline batteries are not to be installed in the same compartment (room, locker, box), unless of valve-regulated sealed type.

### 6.2 Large vented batteries

**6.2.1** Batteries connected to a charging device of power exceeding 2 kW, calculated from the maximum obtainable charging current and the nominal voltage of the battery (hereafter referred to as "large batteries") are to be installed in a room assigned to batteries only.

Where this is not possible, they may be arranged in a suitable locker on deck.

**6.2.2** Rooms assigned to large batteries are to be provided with mechanical exhaust ventilation.

Natural ventilation may be employed for boxes located on open deck.

**6.2.3** The provisions of [6.2.1] and [6.2.2] also apply to several batteries connected to charging devices of total power exceeding 2 kW calculated for each one as stated in [6.2.1].

### 6.3 Moderate vented batteries

**6.3.1** Batteries connected to a charging device of power between 0,2 kW and 2 kW calculated as stated in [6.2.1] (hereafter referred to as "moderate batteries") are to be arranged in the same manner as large batteries or placed in a box or locker in suitable locations such as machinery spaces, storerooms or similar spaces. In machinery spaces and similar well-ventilated compartments, these batteries may be installed without a box or locker provided they are protected from falling objects, dripping water and condensation where necessary.

**6.3.2** Rooms, lockers or boxes assigned to moderate batteries are to be provided with natural ventilation or mechanical exhaust ventilation, except for batteries installed without a box or locker (located open) in well-ventilated spaces.

**6.3.3** The provisions of [6.3.1] and [6.3.2] also apply to several batteries connected to charging devices of total power between 0,2 kW and 2 kW calculated for each one as stated in [6.2.1].

### 6.4 Small vented batteries

**6.4.1** Batteries connected to a charging device of power less than 0,2 kW calculated as stated in [6.2.1] (hereafter referred to as "small batteries") are to be arranged in the same manner as moderate or large batteries, or without a box or locker, provided they are protected from falling objects, or in a box in a ventilated area.

**6.4.2** Boxes for small batteries may be ventilated only by means of openings near the top to permit escape of gas.

### 6.5 Ventilation

**6.5.1** The ventilation of battery compartments is to be independent of ventilation systems for other spaces.

**6.5.2** The quantity of air expelled (by natural or forced ventilation) for compartments containing vented type batteries is to be at least equal to:

$$Q = 110 \cdot I \cdot n$$

where:

- Q : Quantity of air expelled, in litres per hour  
 I : Maximum current delivered by the charging equipment during gas formation, but not less than one quarter of the maximum obtainable charging current in amperes  
 n : Number of cells in series.



**6.5.3** The quantity of air expelled (by natural or forced ventilation) for compartments containing valve-regulated sealed batteries is to be at least 25% of that given in [6.5.2].

**6.5.4** Ducts are to be made of a corrosion-resisting material or their interior surfaces are to be painted with corrosion-resistant paint.

**6.5.5** Adequate air inlets (whether connected to ducts or not) are to be provided near the floor of battery rooms or the bottom of lockers or boxes (except for that of small batteries).

Air inlet may be from the open air or from another space (for example from machinery spaces).

**6.5.6** Exhaust ducts of natural ventilation systems:

- a) are to be run directly from the top of the compartment to the open air above (they may terminate in the open or in well-ventilated spaces)
- b) are to terminate not less than 90 cm above the top of the battery compartment
- c) are to have no part more than 45° from the vertical
- d) are not to contain appliances (for example for barring flames) which may impede the free passage of air or gas mixtures.

Where natural ventilation is impracticable or insufficient, mechanical exhaust ventilation is to be provided.

**6.5.7** In mechanical exhaust ventilation systems:

- a) electric motors are to be outside the exhaust ducts and battery compartment and are to be of safe type if installed within 3 m from the exhaust of the ventilation duct
- b) fans are to be so constructed and of a material such as to render sparking impossible in the event of the impeller touching the fan casing
- c) steel or aluminium impellers are not to be used
- d) the system is to be interlocked with the charging device so that the battery cannot be charged without ventilation (trickle charge may be maintained)
- e) a temperature sensor is to be located in the battery compartment to monitor the correct behaviour of the battery in cases where the battery element is sensitive to temperature.

**6.5.8** For natural ventilation systems for deck boxes:

- a) holes for air inlet are to be provided on at least two opposite sides of the box
- b) the exhaust duct is to be of ample dimensions
- c) the duct is to terminate at least 1,25 m above the box in a goose-neck or mushroom-head or the equivalent
- d) the degree of protection is to be in accordance with Sec 3, Tab 2.

## SECTION 12

## INSTALLATION

### 1 General

#### 1.1 Protection against injury or damage caused by electrical equipment

**1.1.1** All electrical equipment is to be so installed as not to cause injury when handled or touched in the normal manner.

**1.1.2** All electrical equipment is to be installed in such a way that live parts cannot be inadvertently touched, unless supplied at a safety voltage.

**1.1.3** For protective earthing as a precaution against indirect contact, see [2].

**1.1.4** Equipment is to be installed so as not to cause, or at least so as to reduce to a minimum, electromagnetic interference.

#### 1.2 Protection against damage to electrical equipment

**1.2.1** Electrical equipment is to be so placed that as far as practicable it is not exposed to risk of damage from water, steam, oil or oil vapours.

**1.2.2** The air supply for internal ventilation of electrical equipment is to be as clean and dry as practicable; cooling air for internal ventilation is not to be drawn from below the floor plates in engine and/or boiler rooms.

**1.2.3** Equipment is to be so mounted that its enclosing arrangements and the functioning of the built-in equipment will not be affected by distortions, vibrations and movements of the ship's structure or by other damage liable to occur.

**1.2.4** If electrical fittings, not of aluminium, are attached to aluminium, suitable provision is to be made to prevent galvanic corrosion.

#### 1.3 Accessibility

**1.3.1** Equipment is to be so installed that sufficient space is available for inspection and maintenance as required for all its parts (see [6.1.3]).

### 2 Earthing of non-current carrying parts

#### 2.1 Parts which are to be earthed

**2.1.1** Exposed metal parts of both fixed and portable electrical machines or equipment which are not intended to be live but which are liable under fault conditions to become live and similar metal parts inside non-metallic enclosures are to be earthed unless the machines or equipment are:

- a) supplied at a voltage not exceeding 50 V direct current or 50 V, root mean square between conductors, achieved without the use of auto-transformers (safety voltage); or
- b) supplied at a voltage not exceeding 250 V by safety isolating transformers supplying one consuming device only; or
- c) constructed in accordance with the principle of double insulation.

**2.1.2** To minimise shock from high frequency voltage induced by the radio transmitter, handles, handrails and other metal elements on the bridge or upper decks are to be in electrical connection with the hull or superstructures.

#### 2.2 Methods of earthing

**2.2.1** Metal frames or enclosures of apparatus and electrical machinery may be fixed to, and in metallic contact with, the ship's structure, provided that the surfaces in contact are clean and free from rust, scale or paint when installed and are firmly bolted together.

**2.2.2** For metal frames or enclosures which are not earthed as specified in [2.2.1], earthing connections complying with [2.3] and [2.4] are to be used.

**2.2.3** For requirements regarding the earthing of coverings of cables and the mechanical protection of cables, see [7.11] and [7.12].

#### 2.3 Earthing connections

**2.3.1** Every earthing connection is to be of copper or other corrosion-resistant material and is to be securely installed and protected, where necessary, against damage and electrolytic corrosion.

**2.3.2** The nominal cross-sectional area of each copper earthing connection is to be not less than that required in Tab 1.

Earthing connections of other metals are to have conductance at least equal to that specified for a copper earthing connection.

**Table 1 : Cross-sectional area of earth-continuity conductors and earthing connections**

Type of earthing connection		Cross-sectional area of associated current carrying conductor	Minimum cross-sectional area of copper earthing connection	
1	Earth-continuity conductor in flexible cable or flexible cord	any	Same as current carrying conductor up to and including 16 mm <sup>2</sup> and one half above 16 mm <sup>2</sup> but at least 16 mm <sup>2</sup>	
2	Earth-continuity conductor incorporated in fixed cable	any	a) for cables having an insulated earth-continuity conductor <ul style="list-style-type: none"> <li>• a cross-section equal to the main conductors up to and including 16 mm<sup>2</sup>, but minimum 1,5 mm<sup>2</sup></li> <li>• a cross-section not less than 50% of the cross-section of the main conductor when the latter is more than 16 mm<sup>2</sup>, but at least 16 mm<sup>2</sup></li> </ul>	
			b) for cables with a bare earth wire in direct contact with the lead sheath	
			Cross-section of main conductor mm <sup>2</sup>	Earthing connection mm <sup>2</sup>
			1 ÷ 2,5	1
			4 ÷ 6	1,5
3	Separate fixed earthing conductor	≤ 2,5 mm <sup>2</sup>	Same as current carrying conductor subject to minimum of 1,5 mm <sup>2</sup> for stranded earthing connection or 2,5 mm <sup>2</sup> for unstranded earthing connection	
		> 2,5 mm <sup>2</sup> but ≤ 120 mm <sup>2</sup>	One half the cross-sectional area of the current carrying conductor, subjected to a minimum of 4 mm <sup>2</sup>	
		> 120 mm <sup>2</sup>	70 mm <sup>2</sup>	

**2.3.3** Metal parts of portable appliances are to be earthed, where required (see [2.1.1]), by means of an earth-continuity conductor in the flexible supply cable or cord, which has the cross-sectional area specified in Tab 1 and which is earthed, for example, through the associated plug and socket.

**2.3.4** In no circumstances is the lead sheathing or armour of cables to be relied upon as the sole means of earthing.

## 2.4 Connection to the ship's structure

**2.4.1** Every connection of an earth-continuity conductor or earthing lead to the ship's structure is to be secured by means of a screw of brass or other corrosion-resistant material of diameter not less than 6 mm.

**2.4.2** Such earthing connection is not to be used for other purposes.

**2.4.3** The connection described in [2.4.1] is to be located in an accessible position where it may readily be checked.

## 2.5 Earthed distribution systems

**2.5.1** The system earthing of earthed distribution systems is to be effected by means independent of any earthing arrangements of non-current carrying parts and is to be connected to the hull at one point only.

**2.5.2** In an earthed distribution system in which the earthing connection does not normally carry current, this con-

nection is to conform with the requirements of [2.3], except that the lower limit of 70 mm<sup>2</sup> (see Tab 1) does not apply.

**2.5.3** In a distribution system with hull return, the system earthing connection is to have at least the same cross-sectional area as the feeder lines.

**2.5.4** The earthing connection is to be in an accessible position where it may readily be inspected and disconnected for insulation testing.

## 2.6 Aluminium superstructures

**2.6.1** When aluminium superstructures are insulated from the steel hull to prevent electrolytic corrosion, they are to be secured to the hull by means of a separate bonding connection.

**2.6.2** The connections are to be adequately close together and are to have a resistance less than 0.1 Ω.

**2.6.3** The connections are to be located where they may readily be inspected.

## 3 Rotating machines

### 3.1

**3.1.1** Every rotating machine is preferably to be installed with the shaft in the fore-and-aft direction. Where a rotating machine of 100 kW and over is installed athwartship, or vertically, it is to be ensured that the design of the bearings

and the arrangements for lubrication are satisfactory to withstand the rolling specified in Sec 2, Tab 4.

## 4 Semiconductor convertors

### 4.1 Semiconductor power convertors

**4.1.1** Naturally air-cooled semiconductor convertors are to be installed such that the circulation of air to and from the stacks or enclosures is not impeded and that the temperature of the cooling inlet air to convertor stacks does not exceed the ambient temperature for which the stacks are specified.

## 5 Vented type storage batteries

### 5.1 General

**5.1.1** Batteries are to be arranged so that each cell or crate of cells is accessible from the top and at least one side to permit replacement and periodical maintenance.

**5.1.2** Cells or crates are to be carried on insulating supports of material non-absorbent to the electrolyte (e.g. treated wood).

**5.1.3** Cells are to be securely chocked by means of insulating material non-absorbent to the electrolyte, e.g. strips of treated wood.

**5.1.4** All batteries should be secured in a position where excessive movement is prevented during ice-transiting operations and explosive gas ventilation is not restricted by the accumulation of ice or snow.

**5.1.5** Special mechanical precautions are to be taken to prevent the emergency battery from being damaged by the shock due to a collision.

**5.1.6** Provision is to be made for the free circulation of air.

### 5.2 Protection against corrosion

**5.2.1** The interior of battery compartments (rooms, lockers, boxes) including all metal parts subject to the electrolyte is to be protected against the deteriorating effect of the latter by electrolyte-resistant coating or other equivalent means, unless corrosion-resistant materials are used.

**5.2.2** Interior surfaces of metal shelves for battery cells, whether or not grouped in crates or trays, are to be protected by a lining of electrolyte-resistant material, watertight and carried up to at least 75 mm on all sides. In particular, linings are to have a minimum thickness of 1,5 mm, if of lead sheet for lead-acid batteries, and of 0,8 mm, if of steel for alkaline batteries.

Alternatively, the floor of the room or locker is to be lined as specified above to a height of at least 150 mm.

**5.2.3** Battery boxes are to be lined in accordance with [5.2.2] to a height of at least 75 mm.

## 6 Switchgear and controlgear assemblies

### 6.1 Main switchboard

**6.1.1** The main switchboard is to be so arranged as to give easy access as may be needed to apparatus and equipment, without danger to personnel.

**6.1.2** An unobstructed space is to be left in front of the switchboard wide enough to allow access for operation; such width is generally about 1 metre.

When withdrawable equipment is contained in the switchboard, the width of the space is to be not less than 0,5 m when the equipment is fully withdrawn.

Reduced widths may be considered for small ships.

**6.1.3** Where necessary, an unobstructed space is to be provided at the rear of the switchboard ample to permit maintenance; in general, the width of this passage is to be not less than 0,6 m, except that this may be reduced to 0,5 m in way of stiffeners and frames, and the height sufficient for the operation foreseen.

**6.1.4** Where the switchboard is open at the rear, the rear space in [6.1.3] is to form a locked space provided at each end with an access door. The required IP protection for the corresponding location is to be fulfilled.

**6.1.5** If necessary, the clear height above the switchboard specified by the manufacturer is to be maintained for pressure relief in the event of a short-circuit.

**6.1.6** When the voltage exceeds the safety voltage, non-conducting mats or gratings are to be provided at the front and rear of the switchboard as necessary.

**6.1.7** Piping and conduits are not to be installed directly above or in the vicinity of switchboards and controlgear assemblies.

Where this is unavoidable, pipes and conduits are to have welded joints only or to be provided with protection against spray from steam or pressurised liquids or dripping.

### 6.2 Emergency switchboard

**6.2.1** For the installation of the emergency switchboard, the same requirements apply as given in [6.1] for the installation of the main switchboard.

### 6.3 Section boards and distribution boards

**6.3.1** For the installation of section and distribution boards, the same requirements apply, as far as applicable, as given in [6.1] for the installation of the main switchboard.

## 7 Cables

### 7.1 General

**7.1.1** Cables having insulating materials with different maximum permissible conductor temperatures are not to be bunched together.

Where this is not practicable, the cables are to be so installed that no cable reaches a temperature higher than its rating.

**7.1.2** Cables having a protective covering which may damage the covering of more vulnerable cables are not to be bunched with the latter.

**7.1.3** Cables having a bare metallic sheath (e.g. of copper) or braid or armour are to be installed in such a way that galvanic corrosion by contact with other metals is prevented.

**7.1.4** All cables and wiring external to equipment are to be so installed as not to impair their original flame-retarding properties.

To this end, the following methods may be used:

- a) the use of cables which have been tested in accordance with IEC Publication 332-3 Category A or an equivalent test procedure for cables installed in bunches, or
- b) the use of fire stops having at least B0 penetrations fitted as follows (see Fig 1, Fig 2, Fig 3 and Fig 4):
  - cable entries at the main and emergency switch-board
  - where cables enter engine control rooms
  - cable entries at centralised control panels for propulsion machinery and essential auxiliaries
  - at each end of totally enclosed cable trunks
  - at every second deck or approximately 6 metres for vertical runs and every 14 metres for horizontal runs in enclosed and semi-enclosed spaces
  - at the boundaries of the spaces in cargo areas.
- c) the use of fire protection coating applied to at least 1 metre in every 14 metres on horizontal cable runs and over the entire length of vertical cable runs for cables installed in enclosed and semi-enclosed spaces.

The cable penetrations are to be installed in steel plates of at least 3 mm thickness extending all around to twice the

largest dimension of the cable run for vertical runs and once for horizontal runs, but need not extend through ceilings, decks, bulkheads or solid sides of trunks. These precautions apply in particular to bunches of 5 or more cables in areas with a high fire risk (such as Category A machinery spaces, galleys etc.) and to bunches of more than 10 cables in other areas.

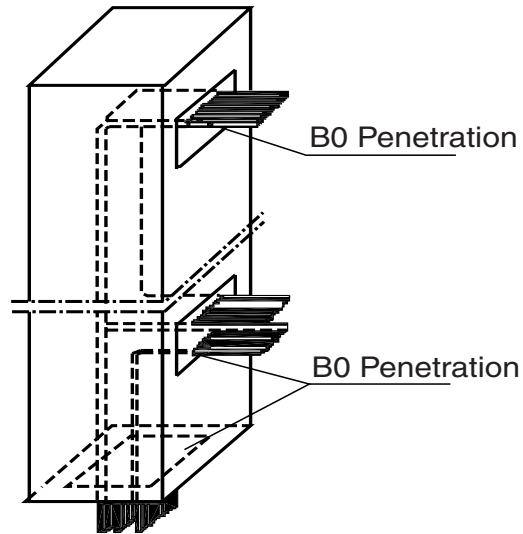
### 7.2 Radius of bend

**7.2.1** The internal radius of bend for the installation of cables is to be chosen according to the type of cable as recommended by the manufacturer.

Its value is generally to be not less than the figure given in Tab 2.

**7.2.2** Where the installation of cables across expansion joints is unavoidable, the minimum internal radius of the loop at the end of the travel of the expansion joint is to be not less than 12 times the external diameter of the cable.

**Figure 1 : Totally enclosed trunks**



**Table 2 : Bending radii**

Cable construction		Overall diameter of cable (D)	Minimum internal radius of bend
Insulation	Outer covering		
Thermoplastic or thermosetting with circular copper conductors	Unarmoured or unbraided	≤ 25 mm	4 D
		> 25 mm	6 D
	Metal braid screened or armoured	Any	6 D
	Metal wire armoured	Any	6 D
	Composite polyester/metal laminate tape screened units or collective tape screening	Any	8 D
Thermoplastic or thermosetting with shaped copper conductors	Any	Any	8 D

Figure 2 : Non-totally enclosed trunks, vertical

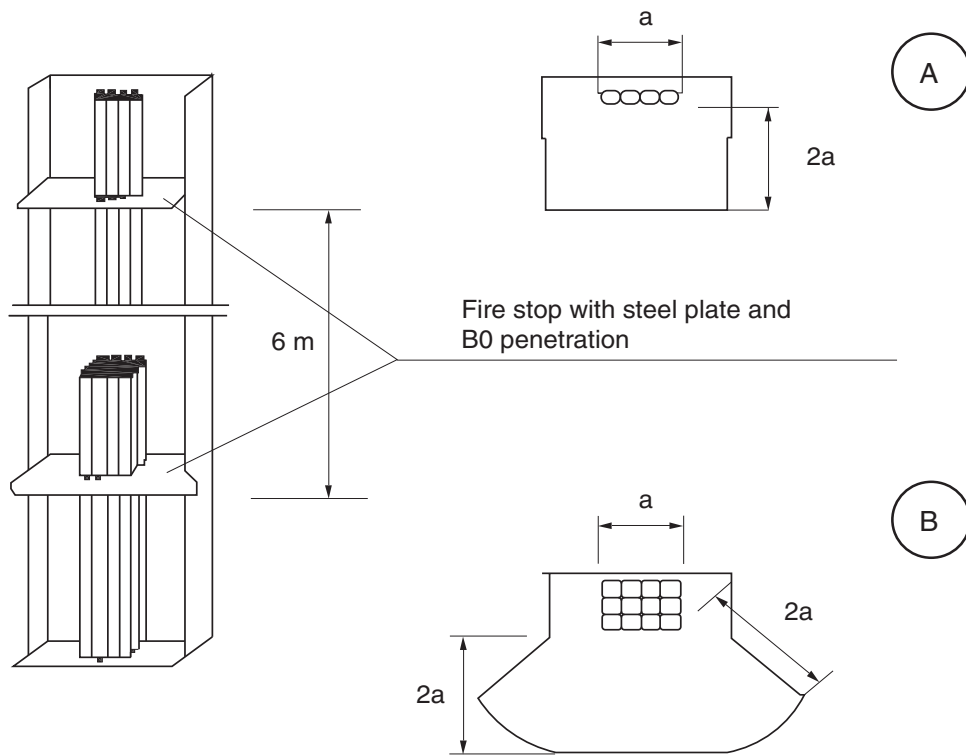


Figure 3 : Non-totally enclosed trunks, horizontal

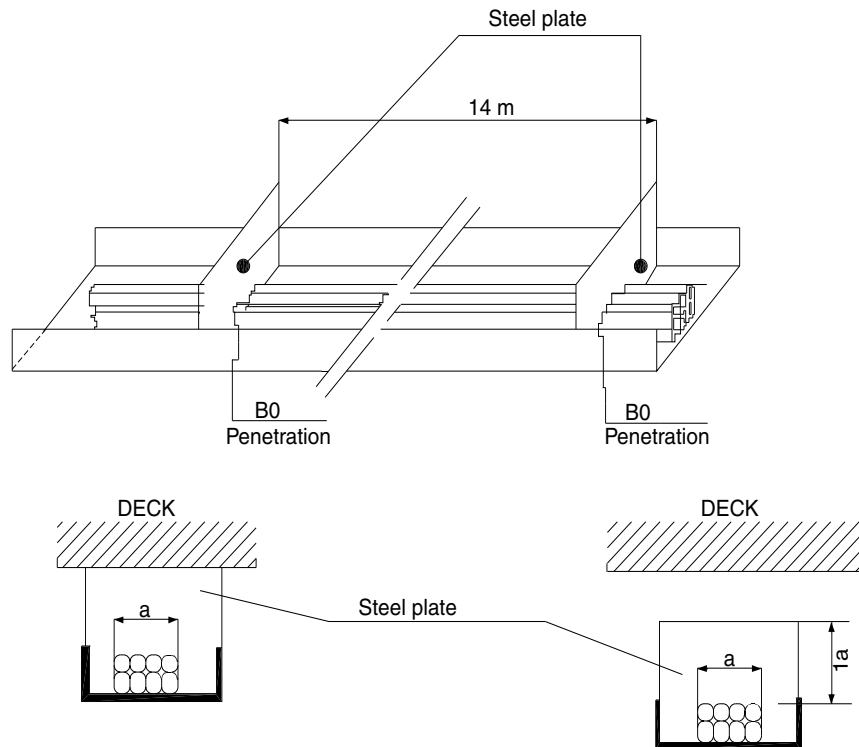
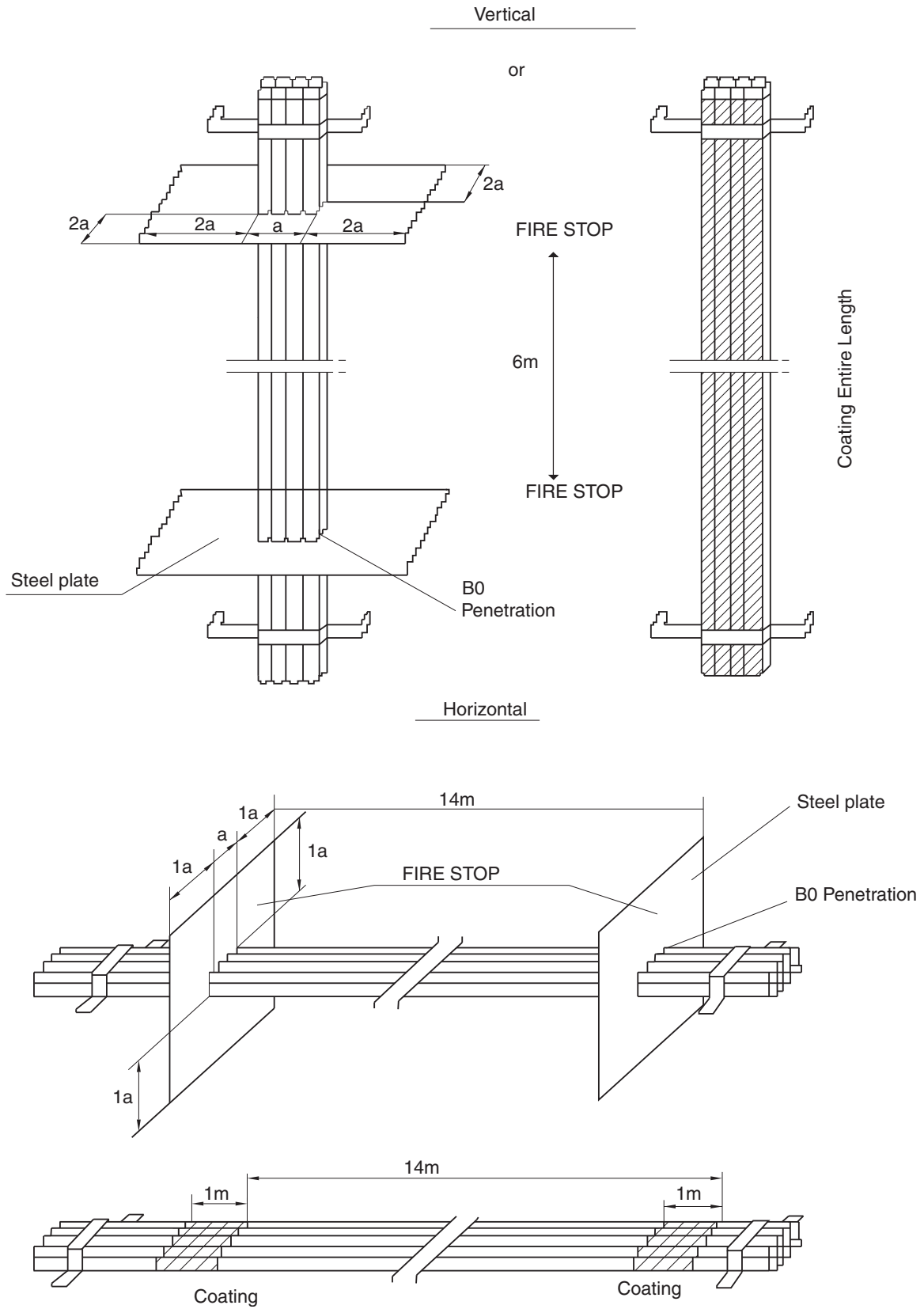


Figure 4 : Open cables runs



### 7.3 Fixing of cables

**7.3.1** Cables shall be installed and supported in such a manner as to avoid chafing or other damage.

**7.3.2** The supports (tray plates, separate support brackets or hanger ladders) and the corresponding accessories are to be of robust construction and of corrosion-resistant material or suitably treated before erection to resist corrosion.

When cables are installed directly on aluminium structures, fixing devices of aluminium or suitably treated steel are to be used.

For mineral-insulated cables with copper sheath, fixing devices in contact with the sheath are to be of copper alloy.

**7.3.3** With the exception of cables installed in pipes, conduits, trunkings or special casings, cables are to be fixed by means of clips, saddles or straps of suitable material, in order to tighten the cables without their coverings being damaged.

**7.3.4** Cable clips or straps made from a material other than metal are to be manufactured of a flame-retardant material.

**7.3.5** The distances between fastenings and between supports are to be suitably chosen according to the type and number of cables and the probability of vibration.

**7.3.6** When cables are fixed by means of clips or straps made from a material other than metal and these cables are not laid on top of horizontal cable supports (e.g. in the case of vertical installation), suitable metal clips or saddles spaced not more than 1 metre apart are to be used in addition in order to prevent the release of cables during a fire.

**7.3.7** Suspended cables of fire-resisting type are to be fixed by means of steel straps spaced not more than 500 mm apart.

### 7.4 Mechanical protection

**7.4.1** Cables exposed to risk of mechanical damage are to be protected by metal casing, profiles or grids or enclosed in metal pipes or conduits, unless the cable covering (e.g. armour or sheath) provides adequate mechanical protection.

**7.4.2** In situations where there would be an exceptional risk of mechanical damage, e.g. in holds, storage spaces, cargo spaces, etc., cables are to be protected by metal casing, trunkings or conduits, even when armoured, if the ship's structure or attached parts do not afford sufficient protection for the cables.

**7.4.3** For the protection of cables passing through decks, see [7.5.3].

**7.4.4** Metal casing used for mechanical protection of cables is to be effectively protected against corrosion.

### 7.5 Penetrations of bulkheads and decks

**7.5.1** If cables have to pass without adequate support through non-watertight bulkheads and generally through

holes drilled in sheets of structural steel, these holes are to be fitted with glands or bushings of suitable material.

**7.5.2** If cables have to pass through a watertight bulkhead or deck, the penetration is to be effected in a watertight manner.

Either suitable individual watertight glands for single cables or boxes containing several cables and filled with a flame-retardant packing may be used for this purpose.

Whichever type of penetration is used, the watertight integrity of the bulkheads or deck is to be maintained.

**7.5.3** Cables passing through decks and continuing vertically are to be protected against mechanical damage to a suitable height above the deck.

**7.5.4** Where cables pass through bulkheads or decks separating areas with a risk of explosion, arrangements are to be such that hazardous gas or dust cannot penetrate through openings for the passage of cables into other areas.

**7.5.5** Where cables pass through a bulkhead or deck which is required to have some degree of fire integrity, penetration is to be so effected as to ensure that the required degree of fire integrity is not impaired.

### 7.6 Expansion joints

**7.6.1** If there is reason to fear that a tray plate, pipe or conduit may break because of the motion of the ship, different load conditions and temperature variations, appropriate expansion joints are to be provided.

This may apply in particular in the case of cable runs on the weather deck.

### 7.7 Cables in closed pipes or conduits

**7.7.1** Closed pipes or conduits are to have such internal dimensions and radius of bend as will permit the easy drawing in and out of the cables which they are to contain; the internal radius of bend is to be not less than that permitted for cables and, for pipes exceeding 63 mm external diameter, not less than twice the external diameter of the pipe where this value is greater.

**7.7.2** Closed pipes and conduits are to be suitably smooth on the interior and are to have their ends shaped or bushed in such a way as not to damage the cable covering.

**7.7.3** The space factor (ratio of the sum of the cross-sectional areas corresponding to the external diameters of the cables to the internal cross-sectional areas of the pipe or conduit) is to be not greater than 0,4.

**7.7.4** If necessary, openings are to be provided at the highest and lowest points so as to permit air circulation and ensure that the heat from the cables can be dissipated, and to obviate the possibility of water accumulating at any part of the pipe or conduit.

**7.7.5** Vertical trunking for electrical cables is to be so constructed as not to jeopardise the required passive fire protection between the spaces.



**7.7.6** Metal pipes or conduits are to be protected against corrosion.

**7.7.7** Non-metallic pipes or conduits are to be flame-retardant.

## **7.8 Cables in casings or trunking and conduits with removable covers**

**7.8.1** Covers are to be removable and when they are open, cables are to be accessible.

**7.8.2** Materials used are to comply with [7.7.6] and [7.7.7].

**7.8.3** If the fixing of covers is by means of screws, the latter are to be of non-rusting material and arranged so as not to damage the cables.

**7.8.4** Means are to be provided to ensure that the heat from the cables can be dissipated and water accumulation is avoided (see [7.7.4]).

## **7.9 Cable ends**

**7.9.1** Terminations in all conductors are to be so made as to retain the original electrical, mechanical, flame-retarding properties of the cable.

**7.9.2** Where mechanical clamps are not used, the ends of all conductors having a cross-sectional area greater than 4 mm<sup>2</sup> are to be fitted with soldering sockets or compression-type sockets of sufficient size to contain all the strands of the conductor.

**7.9.3** Cables not having a moisture-resistant insulation (e.g. mineral-insulated) are to have their ends effectively sealed against ingress of moisture.

## **7.10 Joints and tappings (branch circuit)**

**7.10.1** Cable runs are normally not to include joints. Where absolutely necessary, cable joints are to be carried out by a junction method with rebuilding of the insulation and protective coverings.

**7.10.2** Joints in all conductors are to be so made as to retain the original electrical (continuity and isolation), mechanical (strength and protection), flame-retarding and, where necessary, fire-resisting properties of the cable.

**7.10.3** Tappings (branch circuits) are to be made via suitable connections or in suitable boxes of such design that the conductors remain adequately insulated and protected from atmospheric action and are fitted with terminals or busbars of dimensions appropriate to the current rating.

**7.10.4** Cables for safety voltages are not to terminate in the same connection boxes as cable for higher voltages unless separated by suitable means.

## **7.11 Earthing and continuity of metal coverings of cables**

**7.11.1** All metal coverings of cables are to be electrically connected to the metal hull of the ship.

**7.11.2** Metal coverings are generally to be earthed at both ends of the cable, except for [7.11.3] and [7.11.4].

**7.11.3** Single-point earthing is admitted for final sub-circuits (at the supply end), except for those circuits located in areas with a risk of explosion.

**7.11.4** Earthing is to be at one end only in those installations (mineral-insulated cables, intrinsically safe circuits, control circuits (see Ch 3, Sec 5), etc.) where it is required for technical or safety reasons.

**7.11.5** Metal coverings of single-core a.c. cables and special d.c. cables with high "ripple" content (e.g. for thyristor equipment) are to be earthed at one point only (e.g. at the mid-point).

**7.11.6** The electrical continuity of all metal coverings of cables throughout the length of the latter, particularly at joints and tappings, is to be ensured.

**7.11.7** The metal covering of cables may be earthed by means of glands intended for the purpose and so designed as to ensure an effective earth connection.

The glands are to be firmly attached to, and in effective electrical contact with, a metal structure earthed in accordance with these requirements.

**7.11.8** The metal covering of cables may also be earthed by means of clamps or clips of corrosion-resistant material making effective contact with the covering and earthed metal.

## **7.12 Earthing and continuity of metal pipes, conduits and trunking or casings**

**7.12.1** Metal casings, pipes, conduits and trunking are to be effectively earthed.

**7.12.2** Pipes or conduits may be earthed by being screwed into a metal enclosure, or by nuts on both sides of the wall of a metallic enclosure, provided the surfaces in contact are clean and free from rust, scale or paint and that the enclosure is in accordance with these requirements on earthing. The connection is to be painted immediately after assembly in order to inhibit corrosion.

**7.12.3** Pipes and conduits may be earthed by means of clamps or clips of corrosion-resistant metal making effective contact with the earthed metal.

**7.12.4** Pipes, conduits or trunking together with connection boxes of metallic material are to be electrically continuous.

**7.12.5** All joints in metal pipes and conduits used for earth continuity are to be soundly made and protected, where necessary, against corrosion.

**7.12.6** Individual short lengths of pipes or conduits need not be earthed.

### 7.13 Precautions for single-core cables for a.c.

**7.13.1** For the earthing of metal coverings see [7.11.5].

**7.13.2** Where it is necessary to use single-core cables for alternating current circuits rated in excess of 20 A, the requirements of [7.13.3] to [7.13.7] are to be complied with.

**7.13.3** Conductors belonging to the same circuit are to be contained within the same pipe, conduit or trunking, unless this is of non-magnetic material.

**7.13.4** Cable clips are to include cables of all phases of a circuit unless the clips are of non-magnetic material.

**7.13.5** In the installation of two, three or four single-core cables forming respectively single-phase circuits, three-phase circuits, or three-phase and neutral circuits, the cables are to be in contact with one another, as far as possible. In any event, the distance between the external covering of two adjacent cables is to be not greater than one diameter.

**7.13.6** When single-core cables having a current rating greater than 250 A are installed near a steel bulkhead, the clearance between the cables and the bulkhead is to be at least 50 mm, unless the cables belonging to the same circuit are installed in trefoil twisted formation.

**7.13.7** Magnetic material is not to be used between single-core cables of a group. Where cables pass through steel plates, all the conductors of the same circuit are to pass through a plate or gland, so made that there is no magnetic material between the cables, and the clearance between the cables and the magnetic material is to be no less than 75 mm, unless the cables belonging to the same circuit are installed in trefoil twisted formation.

### 7.14 Cables in refrigerated spaces

**7.14.1** For the types of cables permitted in refrigerated spaces, see Sec 3, [8.4].

**7.14.2** Power cables installed in refrigerated spaces are not to be covered by thermal insulation. Moreover, such cables are not to be placed directly on the face of the refrigerated space unless they have a thermoplastic or elastomeric extruded sheath.

**7.14.3** Power cables entering a refrigerated space are to pass through the walls and thermal insulation at right angles, in tubes sealed at each end and protected against oxidation.

### 7.15 Cables in areas with a risk of explosion

**7.15.1** For the types of cables permitted in areas with a risk of explosion, see Sec 3, [9.2].

**7.15.2** For penetration of bulkheads or decks separating areas with a risk of explosion, see [7.5.4].

**7.15.3** Cables of intrinsically safe circuits are to be separated from the cables of all other circuits (minimum 50 mm).

### 7.16 Cables in the vicinity of radio equipment

**7.16.1** All cables between antennas and transmitters are to be routed separately of any other cable.

**7.16.2** Where it is necessary to use single-core cables, the arrangement of conductors is to be such as to avoid complete or partial loops.

### 7.17 Cables for submerged bilge pumps

**7.17.1** See Sec 3, [8.7].

## 8 Various appliances

### 8.1 Lighting fittings

**8.1.1** Lighting fittings are to be so arranged as to prevent temperature rises which could damage the cables and wiring.

Note 1: Where the temperature of terminals of lighting fittings exceeds the maximum conductor temperature permitted for the supplied cable (see Sec 3, [8.9] ), special installation arrangements, such as terminal boxes thermally insulated from the light source, are to be provided.

**8.1.2** Lighting fittings are to be so arranged as to prevent surrounding material from becoming excessively hot.

**8.1.3** Lighting fittings are to be secured in place such that they cannot be displaced by the motion of the vessel.

### 8.2 Heating appliances

**8.2.1** Space heaters are to be so installed that clothing, bedding and other flammable material cannot come in contact with them in such a manner as to cause risk of fire.

Note 1: To this end, for example, hooks or other devices for hanging garments are not to be fitted above space heaters or, where appropriate, a perforated plate of incombustible material is to be mounted above each heater, slanted to prevent hanging anything on the heater itself.

**8.2.2** Space heaters are to be so installed that there is no risk of excessive heating of the bulkheads or decks on which or next to which they are mounted.

**8.2.3** Combustible materials in the vicinity of space heaters are to be protected by suitable incombustible and thermal-insulating materials.

### 8.3 Heating cables and tapes or other heating elements

**8.3.1** Heating cables and tapes or other heating elements are not to be installed in contact with combustible materials.

Where they are installed close to such materials, they are to be separated by means of a non-flammable material.

**8.3.2** In case of electric heating cables, special attention is to be paid to the heat transfer from the cables to the parts to be heated. The cables are to be adequately spaced in order to provide sufficient heating. The fastening of the cables is to be adequate in order to efficiently transmit the heat.

Heating cables are to be short circuit and overload protected. However, self-regulated cables do not require overload protection.

Motors on open deck are to be naturally cooled, i.e. without external fan.

## SECTION 13

## HIGH VOLTAGE INSTALLATIONS

### 1 General

#### 1.1 Field of application

**1.1.1** The following requirements apply to a.c. three-phase systems with nominal voltage exceeding 1kV, the nominal voltage being the voltage between phases.

If not otherwise stated herein, construction and installation applicable to low voltage equipment generally apply to high voltage equipment.

#### 1.2 Nominal system voltage

**1.2.1** The nominal system voltage is not to exceed 15 kV.

Note 1: Where necessary for special application, higher voltages may be accepted by the Society.

#### 1.3 High-voltage, low-voltage segregation

**1.3.1** Equipment with voltage above about 1 kV is not to be installed in the same enclosure as low voltage equipment, unless segregation or other suitable measures are taken to ensure that access to low voltage equipment is obtained without danger.

### 2 System Design

#### 2.1 Distribution

##### 2.1.1 Network configuration for continuity of ship services

It is to be possible to split the main switchboard into at least two independent sections, by means of at least one circuit breaker or other suitable disconnecting devices, each supplied by at least one generator. If two separate switchboards are provided and interconnected with cables, a circuit breaker is to be provided at each end of the cable.

Services which are duplicated are to be divided between the sections.

##### 2.1.2 Earthed neutral systems

In the event of an earth fault, the current is not to be greater than full load current of the largest generator on the switchboard or relevant switchboard section and not less than three times the minimum current required to operate any device against earth fault.

It is to be assured that at least one source neutral to ground connection is available whenever the system is in the energised mode. Electrical equipment in directly earthed neutral or other neutral earthed systems is to withstand the current due to a single phase fault against earth for the time necessary to trip the protection device.

##### 2.1.3 Neutral disconnection

Means of disconnection are to be fitted in the neutral earthing connection of each generator so that the generator may be disconnected for maintenance and for insulation resistance measurement.

##### 2.1.4 Hull connection of earthing impedance

All earthing impedances are to be connected to the hull. The connection to the hull is to be so arranged that any circulating currents in the earth connections do not interfere with radio, radar, communication and control equipment circuits.

##### 2.1.5 Divided systems

In systems with neutral earthed, connection of the neutral to the hull is to be provided for each section.

#### 2.2 Degrees of protection

##### 2.2.1 General

Each part of the electrical installation is to be provided with a degree of protection appropriate to the location, as a minimum the requirements of IEC Publication 60092-201.

##### 2.2.2 Rotating machines

The degree of protection of enclosures of rotating electrical machines is to be at least IP 23.

The degree of protection of terminals is to be at least IP44.

For motors installed in spaces accessible to unqualified personnel, a degree of protection against approaching or contact with live or moving parts of at least IP4X is required.

##### 2.2.3 Transformers

The degree of protection of enclosures of transformers is to be at least IP23.

For transformers installed in spaces accessible to unqualified personnel a degree of protection of at least IP4X is required.

For transformers not contained in enclosures, see [7.1].

##### 2.2.4 Switchgear, controlgear assemblies and convertors

The degree of protection of metal enclosed switchgear, controlgear assemblies and static convertors is to be at least IP32. For switchgear, control gear assemblies and static convertors installed in spaces accessible to unqualified personnel, a degree of protection of at least IP4X is required.

#### 2.3 Insulation

**2.3.1** In general, for non Type Tested equipment phase-to-phase air clearances and phase-to-earth air clearances between non-insulated parts are to be not less than those specified in Tab 1.

Intermediate values may be accepted for nominal voltages provided that the next highest air clearance is observed.

In the case of smaller distances, an appropriate voltage impulse test is to be applied.

**Table 1 : Minimum clearances**

Rated voltage, in kV	Minimum clearance, in mm
3 - 3,3	55
6 - 6,6	90
10 - 11	120
15	160

**2.3.2** Creepage distances between live parts and between live parts and earthed metal parts for standard components are to be in accordance with relevant IEC Publications for the nominal voltage of the system, the nature of the insulation material and the transient overvoltage developed by switch and fault conditions.

For non-standardised parts within the busbar section of a switchgear assembly, the minimum creepage distance is to be at least 25 mm/kV and behind current limiting devices, 16mm/kV.

## 2.4 Protection

### 2.4.1 Faults on the generator side of the circuit breaker

Protective devices are to be provided against phase-to-phase faults in the cables connecting the generators to the main switchboard and against interwinding faults within the generators. The protective devices are to trip the generator circuit breaker and to automatically de-excite the generator.

In distribution systems with a neutral earthed, phase to earth faults are also to be treated as above.

### 2.4.2 Faults to earth

Any earth fault in the system is to be indicated by means of a visual and audible alarm.

In low impedance or direct earthed systems provision is to be made to automatically disconnect the faulty circuits. In high impedance earthed systems, where outgoing feeders will not be isolated in case of an earth fault, the insulation of the equipment is to be designed for the phase to phase voltage (see Note 1).

A system is defined effectively earthed (low impedance) when this factor is lower than 0.8. A system is defined non-effectively earthed (high impedance) when this factor is higher than 0,8.

Note 1: Earthing factor is defined as the ratio between the phase to earth voltage of the health phase and the phase to phase voltage. This factor may vary between  $1/3^{1/2}$  and 1.

### 2.4.3 Power transformers

Power transformers are to be provided with overload and short circuit protection.

When transformers are connected in parallel, tripping of the protective devices on the primary side is to automatically trip the switch connected on the secondary side.

### 2.4.4 Voltage transformers for control and instrumentation

Voltage transformers are to be provided with overload and short circuit protection on the secondary side.

### 2.4.5 Fuses

Fuses are not to be used for overload protection.

### 2.4.6 Low voltage systems

Lower voltage systems supplied through transformers from high voltage systems are to be protected against overvoltages. This may be achieved by:

- direct earthing of the lower voltage system
- appropriate neutral voltage limiters
- earthed screen between the primary and secondary windings of transformers.

## 3 Rotating machinery

### 3.1 Stator windings of generators

**3.1.1** Generator stator windings are to have all phase ends brought out for the installation of the differential protection.

### 3.2 Temperature detectors

**3.2.1** Rotating machinery is to be provided with temperature detectors in its stator windings to actuate a visual and audible alarm in a normally attended position whenever the temperature exceeds the permissible limit.

If embedded temperature detectors are used, means are to be provided to protect the circuit against overvoltage.

### 3.3 Tests

#### 3.3.1

In addition to the tests normally required for rotating machinery, a high frequency high voltage test in accordance with IEC Publication 60034-15 is to be carried out on the individual coils in order to demonstrate a satisfactory withstand level of the inter-turn insulation to steep fronted switching surges.

## 4 Power Transformers

### 4.1 General

**4.1.1** Dry type transformers are to comply with IEC Publication 60726.

Liquid cooled transformers are to comply with IEC Publication 60076.

Oil immersed transformers are to be provided with the following alarms and protection:

- liquid level (Low) - alarm
- liquid temperature (High) - alarm
- liquid level (Low) - trip or load reduction
- liquid temperature (High) - trip or load reduction
- gas pressure relay (High) - trip

## 5 Cables

### 5.1 General

**5.1.1** Cables are to be constructed in accordance with IEC Publication 60092-353 and 60092-354 or other equivalent Standard.

## 6 Switchgear and controlgear assemblies

### 6.1 General

**6.1.1** Switchgear and controlgear assemblies are to be constructed according to IEC Publication 60298 and the following additional requirements.

### 6.2 Construction

#### 6.2.1 Mechanical construction

Switchgear is to be of metal - enclosed type in accordance with IEC Publication 60298 or of the insulation - enclosed type in accordance with IEC Publication 60466.

#### 6.2.2 Locking facilities

Withdrawable circuit breakers and switches are to be provided with mechanical locking facilities in both service and disconnected positions. For maintenance purposes, key locking of withdrawable circuit breakers and switches and fixed disconnectors is to be possible.

Withdrawable circuit breakers are to be located in the service position so that there is no relative motion between fixed and moving portions.

#### 6.2.3 Shutters

The fixed contacts of withdrawable circuit breakers and switches are to be so arranged that in the withdrawable position the live contacts are automatically covered.

#### 6.2.4 Earthing and short-circuiting

For maintenance purposes an adequate number of earthing and short-circuiting devices is to be provided to enable circuits to be worked on in safety.

### 6.3 Auxiliary systems

#### 6.3.1 Source of supply

If electrical energy and/or physical energy is required for the operation of circuit breakers and switches, a store supply of such energy is to be provided for at least two operations of all the components.

However, the tripping due to overload or short-circuit, and under-voltage is to be independent of any stored electrical energy sources. This does not preclude shunt tripping provided that alarms are activated upon lack of continuity in the release circuits and power supply failures.

#### 6.3.2 Number of supply sources

When external supply is necessary for auxiliary circuits, at least two external sources of supply are to be provided and so arranged that a failure or loss of one source will not

cause the loss of more than one generator set and/or set of essential services.

Where necessary, one source of supply is to be from the emergency source of electrical power for the start up from dead ship condition.

### 6.4 High voltage test

#### 6.4.1

A power-frequency voltage test is to be carried out on any switchgear and controlgear assemblies. The test procedure and voltages are to be according to IEC Publication 60298.

## 7 Installation

### 7.1 Electrical equipment

**7.1.1** Where equipment is not contained in an enclosure but a room forms the enclosure of the equipment, the access doors are to be so interlocked that they cannot be opened until the supply is isolated and the equipment earthed down.

At the entrance to spaces where high-voltage electrical equipment is installed, a suitable marking is to be placed indicating danger of high-voltage. As regards high-voltage electrical equipment installed outside the aforementioned spaces, similar marking is to be provided.

### 7.2 Cables

#### 7.2.1 Runs of cables

In accommodation spaces, high voltage cables are to be run in enclosed cable transit systems.

#### 7.2.2 Segregation

High voltage cables are to be segregated from cables operating at different voltage ratings; in particular, they are not to be run in the same cable bunch, in the same ducts or pipes, or in the same box.

Where high voltage cables of different voltage ratings are installed on the same cable tray, the air clearance between cables is not to be less than the minimum air clearance for the higher voltage side in [2.3.1]. However, high voltage cables are not to be installed on the same cable tray for cables operating at the nominal system voltage of 1 kV and less.

#### 7.2.3 Installation arrangements

High voltage cables are generally to be installed on carrier plating when they are provided with a continuous metallic sheath or armour which is effectively bonded to earth; otherwise they are to be installed for their entire length in metallic castings effectively bonded to earth.

#### 7.2.4 Terminations

Terminations in all conductors of high voltage cables are, as far as practicable, to be effectively covered with suitable insulating material. In terminal boxes, if conductors are not insulated, phases are to be separated from earth and from each other by substantial barriers of suitable insulating materials.

High voltage cables of the radial field type, i.e. having a conductive layer to control the electric field within the insulation, are to have terminations which provide electric stress control.

Terminations are to be of a type compatible with the insulation and jacket material of the cable and are to be provided with means to ground all metallic shielding components (i.e. tapes, wires etc).

### **7.2.5 Marking**

High voltage cables are to be readily identifiable by suitable marking.

### **7.2.6 Test after installation**

Before a new high voltage cable installation, or an addition to an existing installation, is put into service a voltage withstand test is to be satisfactorily carried out on each completed cable and its accessories.

The test is to be carried out after an insulation resistance test.

When a d.c. voltage withstand test is carried out, the voltage is to be not less than:

- $1.6 (2.5 U_0 + 2\text{kV})$  for cables of rated voltage ( $U_0$ ) up to and including 3,6 kV, or
- $4.2 U_0$  for higher rated voltages

where  $U_0$  is the rated power frequency voltage between conductor and earth or metallic screen, for which the cable is designed.

The test voltage is to be maintained for a minimum of 15 minutes.

After completion of the test the conductors are to be connected to earth for a sufficient period in order to remove any trapped electric charge.

An insulation resistance test is then repeated.

Alternatively, an a.c. voltage withstand test may be carried out on the advice of the high voltage cable manufacturer at a voltage not less than the normal operating voltage of the cable, to be maintained for a minimum of 24 hours.

Note 1: Tests specified in IEC Publication 60502 will be considered adequate too.

## SECTION 14

## ELECTRIC PROPULSION PLANT

### 1 General

#### 1.1 Applicable requirements

**1.1.1** The following requirements apply to ships for which the main propulsion plants are provided by at least one electric propulsion motor and its electrical supply. All electrical components of the propulsion plants are to comply with these requirements.

**1.1.2** Prime movers are to comply with the requirements of Ch 1, Sec 2.

**1.1.3** For the torsional vibration characteristics of the electric propulsion plant, the provisions of Ch 1, Sec 9 apply.

**1.1.4** Cooling and lubricating oil systems are to comply with the requirements of Ch 1, Sec 10.

**1.1.5** Monitoring and control systems are to comply with the requirements of Chapter 3.

**1.1.6** Installations assigned an additional notation for automation are to comply with the requirements of Part F.

#### 1.2 Operating conditions

**1.2.1** The normal torque available on the electric propulsion motors for manoeuvring is to be such as to enable the vessel to be stopped or reversed when sailing at its maximum service speed.

**1.2.2** Adequate torque margin is to be provided for three-phase synchronous motors to avoid the motor pulling out of synchronism during rough weather and when turning.

**1.2.3** When an electric generating plant has a continuous rating greater than the electric propulsion motor rating, means are to be provided to limit the continuous input to the motor. This value is not to exceed the continuous full load torque for which motor and shafts are designed.

**1.2.4** The plant as a whole is to have sufficient overload capacity to provide the torque, power and reactive power needed during starting and manoeuvring conditions.

Locked rotor torque which may be required in relation to the operation of the vessel (e.g. for navigation in ice) is to be considered.

**1.2.5** The electric motors and shaftline are to be constructed and installed so that, at any speed reached in service, all the moving components are suitably balanced.

### 2 Design of the propulsion plant

#### 2.1 General

**2.1.1** The electrical power for the propulsion system may be supplied from generating sets, dedicated to the propulsion system, or from a central power generation plant, which supplies the ship's services and electric propulsion.

The minimum configuration of an electric propulsion plant consists of one prime mover, one generator and one electric motor. When the electrical production used for propulsion is independent of the shipboard production, the diesel engines driving the electric generators are to be considered as main engines.

**2.1.2** For plants having only one propulsion motor controlled via a static convertor, a standby convertor which it is easy to switch over to is to be provided. Double stator windings with one convertor for each winding are considered as an alternative solution.

**2.1.3** In electric propulsion plants having two or more constant voltage propulsion generating sets, the electrical power for the ship's auxiliary services may be derived from this source. Additional ship's generators for auxiliary services need not be fitted provided that effective propulsion and the services mentioned in Sec 3, [2.2.3] are maintained with any one generating set out of service.

Where transformers are used to supply the ship's auxiliary services, see Sec 5.

**2.1.4** Plants having two or more propulsion generators, two or more static convertors or two or more motors on one propeller shaft are to be so arranged that any unit may be taken out of service and disconnected electrically, without affecting the operation of the others.

#### 2.2 Power supply

**2.2.1** Where the plant is intended exclusively for electric propulsion, voltage variations and maximum voltage are to be maintained within the limits required in Sec 2.

**2.2.2** In special conditions (e.g. during crash-stop manoeuvres), frequency variations may exceed the limits stipulated in Sec 2 provided that other equipment operating on the same network is not unduly affected.

**2.2.3** The electric plant is to be so designed as to prevent the harmful effects of electromagnetic interference generated by semiconductor convertors, in accordance with Sec 2.



## 2.3 Auxiliary machinery

**2.3.1** Propeller/thruster auxiliary plants are to be supplied directly from the main switchboard or from the main distribution board or from a distribution board reserved for such circuits, at the auxiliary rated voltage.

**2.3.2** When the installation has one or more lubrication systems, devices are to be provided to ensure the monitoring of the lubricating oil return temperature.

**2.3.3** Propelling machinery installations with a forced lubrication system are to be provided with alarm devices which will operate in the event of oil pressure loss.

## 2.4 Electrical Protection

**2.4.1** Automatic disconnections of electric propulsion plants which adversely affect the manoeuvrability of the ship are to be restricted to faults liable to cause severe damage to the equipment.

**2.4.2** The following protection of convertors is to be provided:

- protection against overvoltage in the supply systems to which convertors are connected
- protection against overcurrents in semiconductor elements during normal operation
- short-circuit protection.

**2.4.3** Overcurrent protective devices in the main circuits are to be set sufficiently high so that there is no possibility of activation due to the overcurrents caused in the course of normal operation, e.g. during manoeuvring or in heavy seas.

**2.4.4** Overcurrent protection may be replaced by automatic control systems ensuring that overcurrents do not reach values which may endanger the plant, e.g. by selective tripping or rapid reduction of the magnetic fluxes of the generators and motors.

**2.4.5** In the case of propulsion plants supplied by generators in parallel, suitable controls are to ensure that, if one or more generators are disconnected, those remaining are not overloaded by the propulsion motors.

**2.4.6** In three-phase systems, phase-balance protective devices are to be provided for the motor circuit which de-excite the generators and motors or disconnect the circuit concerned.

## 2.5 Excitation of electric propulsion motor

**2.5.1** Each propulsion motor is to have its own exciter.

**2.5.2** For plants where only one generator or only one motor is foreseen, each machine is to be provided with a standby static electronic exciter, which it is easy to switch over to.

**2.5.3** In the case of multi-propeller propulsion ships, one standby static electronic exciter which it is easy to switch over to is to be provided.

**2.5.4** For the protection of field windings and cables, means are to be provided for limiting the induced voltage when the field circuits are opened. Alternatively, the induced voltage when the field circuits are opened is to be maintained at the nominal design voltage.

**2.5.5** In excitation circuits, there is to be no overload protection causing the opening of the circuit, except for excitation circuits with semiconductor convertors.

## 3 Construction of rotating machines and semiconductor convertors

### 3.1 Ventilation

**3.1.1** Where electrical machines are fitted with an integrated fan and are to be operated at speeds below the rated speed with full load torque, full load current, full load excitation or the like, the design temperature rise is not to be exceeded.

**3.1.2** Where electrical machines or convertors are force-ventilated, at least two fans, or other suitable arrangements, are to be provided so that limited operation is possible in the event of one fan failing.

### 3.2 Protection against moisture and condensate

**3.2.1** Machines and equipment which may be subject to the accumulation of moisture and condensate are to be provided with effective means of heating. The latter is to be provided for motors above 500 kW, in order to maintain the temperature inside the machine at about 3°C above the ambient temperature.

**3.2.2** Provision is to be made to prevent the accumulation of bilge water, which is likely to enter inside the machine.

### 3.3 Rotating machines

**3.3.1** Electrical machines are to be able to withstand the excess speed which may occur during operation of the ship.

**3.3.2** The design of rotating machines supplied by static convertors is to consider the effects of harmonics.

**3.3.3** The winding insulation of electrical machines is to be capable of withstanding the overvoltage which may occur in manoeuvring conditions.

**3.3.4** The design of a.c. machines is to be such that they can withstand without damage a sudden short-circuit at their terminals under rated operating conditions.

**3.3.5** The obtainable current and voltage of exciters and their supply are to be suitable for the output required during manoeuvring and overcurrent conditions, including short-circuit in the transient period.

### 3.4 Semiconductor convertors

**3.4.1** The following limiting repetitive peak voltages  $U_{RM}$  are to be used as a base for each semiconductor valve:

- when connected to a supply specifically for propeller drives:

$$U_{RM} = 1,5 U_p$$

- when connected to a common main supply:

$$U_{RM} = 1,8 U_p$$

where

$U_p$  : is the peak value of the rated voltage at the input of the semiconductor convertor.

**3.4.2** For semiconductor convertor elements connected in series, the values in [3.4.1] are to be increased by 10%. Equal voltage distribution is to be ensured.

**3.4.3** For parallel-connected convertor elements, an equal current distribution is to be ensured.

**3.4.4** Means are to be provided, where necessary, to limit the effects of the rate of harmonics to the system and to other semiconductor convertors. Suitable filters are to be installed to keep the current and voltage within the limits given in Sec 2.

## 4 Control and monitoring

### 4.1 General

**4.1.1** The control and monitoring systems, including programmable electronic systems, are to be type approved, according to Ch 3, Sec 6.

### 4.2 Power plant control systems

**4.2.1** The power plant control systems are to ensure that adequate propulsion power is available, by means of automatic control systems and/or manual remote control systems.

**4.2.2** The automatic control systems are to be such that, in the event of a fault, the propeller speed and direction of thrust do not undergo substantial variations.

**4.2.3** Failure of the power plant control system is not to cause complete loss of generated power (i.e. blackout) or loss of propulsion.

**4.2.4** The loss of power plant control systems is not to cause variations in the available power; i.e. starting or stopping of generating sets is not to occur as a result.

**4.2.5** Where power-aided control (for example with electrical, pneumatic or hydraulic aid) is used for manual operation, failure of such aid is not to result in interruption of power to the propeller, any such device is to be capable of purely manual operation.

**4.2.6** The control system is to include the following main functions:

- monitoring of the alarms: any event critical for the proper operation of an essential auxiliary or a main ele-

ment of the installation requiring immediate action to avoid a breakdown is to activate an alarm

- speed or pitch control of the propeller
- shutdown or slow down when necessary.

**4.2.7** Where the electric propulsion system is supplied by the main switchboard together with the ship's services, load shedding of the non-essential services and /or power limitation of the electric propulsion is to be provided. An alarm is to be triggered in the event of power limitation or load shedding.

**4.2.8** The risk of blackout due to electric propulsion operation is to be eliminated. At the request of the Society, a failure mode and effects analysis is to be carried out to demonstrate the reliability of the system.

### 4.3 Indicating instruments

**4.3.1** In addition to the provisions of Chapter 3 of the Rules, instruments indicating consumed power and power available for propulsion are to be provided at each propulsion remote control position.

**4.3.2** The instruments specified in [4.3.3] and [4.3.4] in relation to the type of plant are to be provided on the power control board or in another appropriate position.

**4.3.3** The following instruments are required for each propulsion alternator:

- an ammeter on each phase, or with a selector switch to all phases
- a voltmeter with a selector switch to all phases
- a wattmeter
- a tachometer or frequency meter
- a power factor meter or a var-meter or a field ammeter for each alternator operating in parallel
- a temperature indicator for direct reading of the temperature of the stator windings, for each alternator rated above 500 kW.

**4.3.4** The following instruments are required for each a.c. propulsion motor:

- an ammeter on the main circuit
- an embedded sensor for direct reading of the temperature of the stator windings, for motors rated above 500 kW
- an ammeter on the excitation circuit for each synchronous motor
- a voltmeter for the measurement of the voltage between phases of each motor supplied through a semiconductor frequency convertor.

**4.3.5** Where a speed measuring system is used for control and indication, the system is to be duplicated with separate sensor circuits and separate power supply.

**4.3.6** An ammeter is to be provided on the supply circuit for each propulsion semiconductor bridge.

## 4.4 Alarm system

**4.4.1** An alarm system is to be provided, in accordance with the requirements of Chapter 3. The system is to give an indication at the control positions when the parameters specified in [4.4] assume abnormal values or any event occurs which can affect the electric propulsion.

**4.4.2** Where an alarm system is provided for other essential equipment or installations, the alarms in [4.4.1] may be connected to such system.

**4.4.3** Critical alarms for propulsion may be grouped, but are to be indicated to the bridge separately from other alarms.

**4.4.4** The following alarms are to be provided, where applicable:

- high temperature of the cooling air of machines and semiconductor convertors provided with forced ventilation (see Note 1)
- reduced flow of primary and secondary coolants of machines and semiconductor convertors having a closed cooling system with a heat exchanger
- leakage of coolant inside the enclosure of machines and semiconductor convertors with liquid-air heat exchangers
- high winding temperature of generators and propulsion motors, where required (see [4.3])
- low lubricating oil pressure of bearings for machines with forced oil lubrication
- tripping of protective devices against overvoltages in semiconductor convertors (critical alarm)
- tripping of protection on filter circuits to limit the disturbances due to semiconductor convertors
- tripping of protective devices against overcurrents up to and including short-circuit in semiconductor convertors (critical alarm)
- voltage unbalance of three-phase a.c. systems supplied by semiconductor frequency convertors
- earth fault for the main propulsion circuit (see Note 2)
- earth fault for excitation circuits of propulsion machines (see Note 3).

Note 1: As an alternative to the air temperature of convertors or to the airflow, the supply of electrical energy to the ventilator or the temperature of the semiconductors may be monitored.

Note 2: In the case of star connected a.c. generators and motors with neutral points earthed, this device may not detect an earth fault in the entire winding of the machine.

Note 3: This may be omitted in brushless excitation systems and in the excitation circuits of machines rated up to 500 kW. In such cases, lamps, voltmeters or other means are to be provided to detect the insulation status under operating conditions.

## 4.5 Reduction of power

**4.5.1** Power is to be automatically reduced in the following cases:

- low lubricating oil pressure of bearings of propulsion generators and motors
- high winding temperature of propulsion generators and motors
- fan failure in machines and convertors provided with forced ventilation, or failure of cooling system
- lack of coolant in machines and semiconductor convertors
- load limitation of generators or inadequate available power.

**4.5.2** When power is reduced automatically, this is to be indicated at the propulsion control position (critical alarm).

**4.5.3** Switching-off of the semiconductors in the event of abnormal service operation is to be provided in accordance with the manufacturer's specification.

## 5 Installation

### 5.1 Ventilation of spaces

**5.1.1** Loss of ventilation to spaces with forced air cooling is not to cause loss of propulsion. To this end, two sets of ventilation fans are to be provided, one acting as a standby unit for the other. Equivalent arrangements using several independently supplied fans may be considered.

### 5.2 Cable runs

**5.2.1** Instrumentation and control cables are to comply with the requirements of Ch 3, Sec 5.

**5.2.2** Where there is more than one propulsion motor, all cables for any one machine are to be run as far as is practicable away from the cables of other machines.

**5.2.3** Cables which are connected to the sliprings of synchronous motors are to be suitably insulated for the voltage to which they are subjected during manoeuvring.

## 6 Tests

### 6.1 Test of rotating machines

**6.1.1** The test requirements are to comply with Sec 4.

**6.1.2** For rotating machines, such as synchronous generators and synchronous electric motors, of a power of more than 3 MW, a test program is to be submitted to the Society for approval.

**6.1.3** In relation to the evaluation of the temperature rise, it is necessary to consider the supplementary thermal losses induced by harmonic currents in the stator winding. To this end, two methods may be used:

- direct test method, when the electric propulsion motor is being supplied by its own frequency convertor, and/or

back to back arrangement according to the supplier's facility

- indirect test method as defined in App 1; in this case, a validation of the estimation of the temperature excess due to harmonics is to be documented. A justification based on a computer program calculation may be taken into consideration, provided that validation of such program is demonstrated by previous experience.

## 7 Specific requirements for PODs

### 7.1 General

**7.1.1** The requirements for the structural part of a POD are specified in Pt B, Ch 10, Sec 1, [11].

**7.1.2** When used as steering manoeuvring system, the POD is to comply with the requirements of Ch 1, Sec 9.

### 7.2 Rotating commutators

**7.2.1** As far as the electrical installation is concerned, the electric motor is supplied by a rotating commutator which rotates with the POD. The fixed part of the power transmission is connected to the ship supply, which uses the same components as a conventional propulsion system. Sliding contacts with a suitable support are used between the fixed and rotating parts.

**7.2.2** Type tests are to be carried out, unless the manufacturer can produce evidence based on previous experience indicating the satisfactory performance of such equipment on board ships.

**7.2.3** A test program is to be submitted to the Society for approval. It is to be demonstrated that the power transmission and transmission of low level signals are not affected by the environmental and operational conditions prevailing on board. To this end, the following checks and tests are to be considered:

- check of the protection index (I.P.), in accordance with the location of the rotating commutator
- check of the clearances and creepage distances
- check of insulation material (according to the test procedure described in IEC Publication 60112)
- endurance test:

After the contact pressure and rated current are set, the commutator is subjected to a rotation test. The number of rotations is evaluated taking into consideration the ship operation and speed rotation control system. The

possibility of turning the POD 180° to proceed astern and 360° to return to the original position is to be considered. The commutator may be submitted to cycles comprising full or partial rotation in relation to the use of the POD as steering gear. The voltage drops and current are to be recorded.

An overload test is to be carried out in accordance with Sec 4 (minimum 150%, 15 seconds)

- check of the behaviour of the sliprings when subjected to the vibration defined in Ch 3, Sec 6
- check of the behaviour of the sliprings, after damp heat test, as defined in Chapter 3, and possible corrosion of the moving parts and contacts

After the damp heat test, are to be carried out the here-under listed tests.

- Insulation measurement resistance test. The minimum resistance is to be in accordance with Sec 4, Tab 3.
- Dielectric strength test as defined in Sec 4.

### 7.3 Electric motors

**7.3.1** The thermal losses are dissipated by the liquid cooling of the bulb and by the internal ventilation of the POD. The justification for the evaluation of the heating balance between the sea water and air cooling is to be submitted to the Society.

Note 1: The calculation method used for the evaluation of the cooling system (mainly based on computer programs) is to be documented. The calculation method is to be justified based on the experience of the designer of the system. The results of scale model tests or other methods may be taken into consideration.

**7.3.2** Means to adjust the air cooler characteristics are to be provided on board, in order to obtain an acceptable temperature rise of the windings. Such means are to be set following the dock and sea trials.

### 7.4 Instrumentation and associated devices

**7.4.1** Means are to be provided to transmit the low level signals connected to the sensors located in the POD.

### 7.5 Additional tests

**7.5.1** Tests of electric propulsion motors are to be carried out in accordance with Sec 4, and other tests in accordance with Ch 1, Sec 15.

**7.5.2** Tests are to be performed to check the validation of the temperature rise calculation.

## SECTION 15 TESTING

### 1 General

#### 1.1 Rule application

**1.1.1** Before a new installation, or any alteration or addition to an existing installation, is put into service, the electrical equipment is to be tested in accordance with [3], [4] and [5] to the satisfaction of the Surveyor in charge.

#### 1.2 Insulation-testing instruments

**1.2.1** Insulation resistance may be measured with an instrument applying a voltage of at least 500 V. The measurement will be taken when the deviation of the measuring device is stabilised.

Note 1: Any electronic devices present in the installation are to be disconnected prior to the test in order to prevent damage.

### 2 Type approved components

#### 2.1

**2.1.1** The following components are to be type tested or type approved or in accordance with [2.1.2]:

- electrical cables (internal wiring of equipment excluded)
- transformers
- electric motors
- electrical convertors
- circuit-breakers, contactors and overcurrent protective devices (fuses excluded)
- sensors, alarm panels, electronic protective devices, automatic and remote control equipment, actuators, safety devices for installations intended for essential services (steering, controllable pitch propellers, propulsion machinery, etc.), electronic speed regulators for main or auxiliary engines, electronic devices for alarm, safety and control of electrical convertors for primary essential services
- programmable electronic systems intended for functions which are subject to classification requirements.

**2.1.2** Case by case approval based on submission of adequate documentation and execution of tests may also be granted at the discretion of the Society.

### 3 Insulation resistance

#### 3.1 Lighting and power circuits

**3.1.1** The insulation resistance between all insulated poles (or phases) and earth and, where practicable, between

poles (or phases), is to be at least 1 M $\Omega$  in ordinary conditions.

The installation may be subdivided to any desired extent and appliances may be disconnected if initial tests give results less than that indicated above.

#### 3.2 Internal communication circuits

**3.2.1** Circuits operating at a voltage of 50 V and above are to have an insulation resistance between conductors and between each conductor and earth of at least 1 M $\Omega$ .

**3.2.2** Circuits operating at voltages below 50 V are to have an insulation resistance between conductors and between each conductor and earth of at least 0,33 M $\Omega$ .

**3.2.3** If necessary, any or all appliances connected to the circuit may be disconnected while the test is being conducted.

#### 3.3 Switchboards

**3.3.1** The insulation resistance between each busbar and earth and between each insulated busbar and the busbar connected to the other poles (or phases) of each main switchboard, emergency switchboard, section board, etc. is to be not less than 1 M $\Omega$ .

**3.3.2** The test is to be performed before the switchboard is put into service with all circuit-breakers and switches open, all fuse-links for pilot lamps, earth fault-indicating lamps, voltmeters, etc. removed and voltage coils temporarily disconnected where otherwise damage may result.

#### 3.4 Generators and motors

**3.4.1** The insulation resistance of generators and motors, in normal working condition and with all parts in place, is to be measured and recorded.

**3.4.2** The test is to be carried out with the machine hot immediately after running with normal load.

**3.4.3** The insulation resistance of generator and motor connection cables, field windings and starters is to be at least 1 M $\Omega$ .

### 4 Earth

#### 4.1 Electrical constructions

**4.1.1** Tests are to be carried out, by visual inspection or by means of a tester, to verify that all earth-continuity conductors and earthing leads are connected to the frames of apparatus and to the hull, and that in socket-outlets having earthing contacts, these are connected to earth.

## 4.2 Metal-sheathed cables, metal pipes or conduits

**4.2.1** Tests are to be performed, by visual inspection or by means of a tester, to verify that the metal coverings of cables and associated metal pipes, conduits, trunking and casings are electrically continuous and effectively earthed.

## 5 Operational tests

### 5.1 Generating sets and their protective devices

**5.1.1** Generating sets are to be run at full rated load to verify that the following are satisfactory:

- electrical characteristics
- commutation (if any)
- lubrication
- ventilation
- noise and vibration level.

**5.1.2** Suitable load variations are to be applied to verify the satisfactory operation under steady state and transient conditions (see Sec 4, [2] ) of:

- voltage regulators
- speed governors.

**5.1.3** Generating sets intended to operate in parallel are to be tested over a range of loading up to full load to verify that the following are satisfactory:

- parallel operation
- sharing of the active load
- sharing of the reactive load (for a.c. generators).

Synchronising devices are also to be tested.

**5.1.4** The satisfactory operation of the following protective devices is to be verified:

- overspeed protection
- overcurrent protection (see Note 1)
- load-shedding devices
- any other safety devices.

For sets intended to operate in parallel, the correct operation of the following is also to be verified:

- reverse-power protection for a.c. installations (or reverse-current protection for d.c. installations)
- minimum voltage protection.

Note 1: Simulated tests may be used to carry out this check where appropriate.

**5.1.5** The satisfactory operation of the emergency source of power and of the transitional source of power, when required, is to be tested. In particular, the automatic starting and the automatic connection to the emergency switchboard, in case of failure of the main source of electrical power, are to be tested.

### 5.2 Switchgear

**5.2.1** All switchgear is to be loaded and, when found necessary by the attending Surveyor, the operation of overcurrent protective devices is to be verified (see Note 1).

Note 1: The workshop test is generally considered sufficient to ensure that such apparatus will perform as required while in operation.

**5.2.2** Short-circuit tests may also be required at the discretion of the Society in order to verify the selectivity characteristics of the installation.

### 5.3 Consuming devices

**5.3.1** Electrical equipment is to be operated under normal service conditions (though not necessarily at full load or simultaneously) to verify that it is suitable and satisfactory for its purpose.

**5.3.2** Motors and their starters are to be tested under normal operating conditions to verify that the following are satisfactory:

- power
- operating characteristics
- commutation (if any)
- speed
- direction of rotation
- alignment.

**5.3.3** The remote stops foreseen are to be tested.

**5.3.4** Lighting fittings, heating appliances etc. are to be tested under operating conditions to verify that they are suitable and satisfactory for their purposes (with particular regard to the operation of emergency lighting).

### 5.4 Communication systems

**5.4.1** Communication systems, order transmitters and mechanical engine-order telegraphs are to be tested to verify their suitability.

### 5.5 Installations in areas with a risk of explosion

**5.5.1** Installations and the relevant safety certification are to be examined to ensure that they are of a type permitted in the various areas and that the integrity of the protection concept has not been impaired.

### 5.6 Voltage drop

**5.6.1** Where it is deemed necessary by the attending Surveyor, the voltage drop is to be measured to verify that the permissible limits are not exceeded (see Sec 3, [8.11.4]).

# APPENDIX 1

# INDIRECT TEST METHOD FOR SYNCHRONOUS MACHINES

## 1 General

### 1.1 Test method

**1.1.1** The machine is to be subjected to the three separate running tests specified below (see Fig 1) when it is completed (with covers, heat exchangers, all control devices and sensors), the exciter circuit is connected to its normal supply or to a separate supply having the same characteristics, and the supply is fitted with the necessary measuring instruments:

- Test N° 1: No load test at rated voltage and current on rotor, stator winding in open circuit. The temperature rise of the stator winding depends, in such case, on the magnetic circuit losses and mechanical losses due to ventilation, where:
  - $\Delta t_{s1}$  is the stator temperature rise
  - $\Delta t_{r1}$  is the rotor temperature rise
- Test N° 2: Rated stator winding current with the terminals short-circuited. The temperature of the stator winding depends on the thermal Joule losses and mechanical losses, as above, where:
  - $\Delta t_{s2}$  is the stator temperature rise
  - $\Delta t_{r2}$  is the rotor temperature rise, which for test N° 2 is negligible
- Test N° 3: Zero excitation. The temperature of all windings depends on the mechanical losses due to friction and ventilation, where:
  - $\Delta t_{s3}$  is the stator temperature rise
  - $\Delta t_{r3}$  is the rotor temperature rise.

Note 1: The synchronous electric motor is supplied at its rated speed by a driving motor. The temperature balance will be considered as being obtained, when the temperature rise does not vary by more than 1°C per hour.

**1.1.2** Temperature measurements of the stator winding can be based on the use of embedded temperature sensors or measurement of winding resistance. When using the resist-

ance method for calculation of the temperature rise, the resistance measurement is to be carried out as soon as the machine is shut down.

The rotor temperature rise is obtained by calculation of rotor resistance,  $R_{rotor} = (U/I)_r$ , where U and I are the voltage and current in the magnetic field winding.

The following parameters are recorded, every 1/2 hour:

- temperature sensors as well as the stator current and voltage
- the main field voltage and current
- the bearing temperatures (embedded sensor or thermometer), and the condition of cooling of the bearings, which are to be compared to those expected on board.

**1.1.3** The tests described above allow the determination of the final temperature rise of stator and rotor windings with an acceptable degree of accuracy.

- The temperature rise of the stator winding is estimated as follows:

$$\Delta t_{stator} = \Delta t_{s1} + \Delta t_{s2} - \Delta t_{s3}$$

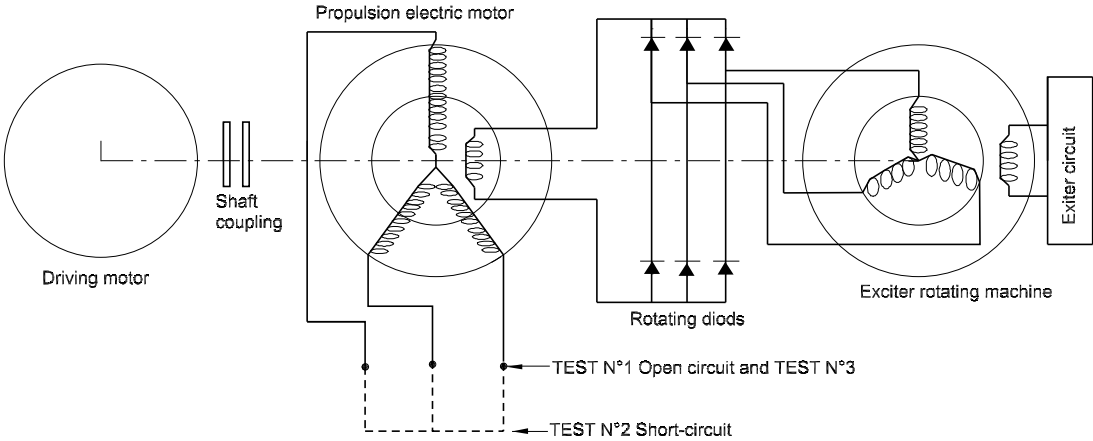
$\Delta t_{stator}$  winding is to be corrected by the supplementary temperature rise due to current harmonics evaluated by the manufacturer

- Considering that in test N° 1 the magnetic field winding current  $I_{rt}$  is different from the manufacturer's estimated value  $I_r$  (due to the fact that the  $\cos \phi$  in operation is not equal to 1), the temperature rise of the rotor is to be corrected as follows:

$$\Delta t_{rotor} = (\Delta t_{r1} - \Delta t_{r3}) \times (\text{rated loading conditions } I_r / \text{test loading conditions } I_{rt})^2 + \Delta t_{r3}$$

**1.1.4** In the indirect method, a possible mutual influence of the temperature rise between the stator and the rotor is not taken into consideration. The test results may be representative of the temperature rise on board ship, but a margin of 10 to 15°C is advisable compared with the permitted temperature of the Rules and the measure obtained during tests.

Figure 1 : Schematic diagram used for the test







Part C  
**Machinery, Systems and Fire Protection**

Chapter 3  
**AUTOMATION**

---

- SECTION 1      GENERAL REQUIREMENTS**
- SECTION 2      DESIGN REQUIREMENTS**
- SECTION 3      PROGRAMMABLE ELECTRONIC SYSTEMS**
- SECTION 4      CONSTRUCTIONAL REQUIREMENTS**
- SECTION 5      INSTALLATION REQUIREMENTS**
- SECTION 6      TESTING**



# SECTION 1

# GENERAL REQUIREMENTS

## 1 General

### 1.1 Field of application

**1.1.1** The following requirements apply to automation systems, installed on all ships, intended for essential services as defined in Ch 2, Sec 1. They also apply to systems required in Chapter 1 and Chapter 2, installed on all ships.

**1.1.2** This chapter is intended to avoid that failures or malfunctions of automation systems associated with essential and non-essential services cause danger to other essential services.

**1.1.3** Requirements for unattended machinery spaces and for additional notations are specified in Part F.

### 1.2 Regulations and standards

**1.2.1** The regulations and standards applicable are those defined in Ch 2, Sec 1.

### 1.3 Definitions

**1.3.1** Unless otherwise stated, the terms used in this chapter have the definitions laid down in Ch 2, Sec 1 or in the IEC standards. The following definitions also apply:

- Alarm indicator is an indicator which gives a visible and/or audible warning upon the appearance of one or more faults to advise the operator that his attention is required.
- Alarm system is a system intended to give a signal in the event of abnormal running condition.
- Application software is a software performing tasks specific to the actual configuration of the programmable electronic system and supported by the basic software.
- Automatic control is the control of an operation without direct or indirect human intervention, in response to the occurrence of predetermined conditions.
- Automation systems are systems including control systems and monitoring systems.
- Basic software is the minimum software, which includes firmware and middleware, required to support the application software.
- Cold standby system is a duplicated system with a manual commutation or manual replacement of cards which are live and non-operational. The duplicated system is to be able to achieve the operation of the main system

with identical performance, and be operational within 10 minutes.

- Programmable electronic system is a system of one or more computers, associated software, peripherals and interfaces, and the computer network with its protocol.
- Control station is a group of control and monitoring devices by means of which an operator can control and verify the performance of equipment.
- Control system is a system by which an intentional action is exerted on an apparatus to attain given purposes.
- Expert system is an intelligent knowledge-based system that is designed to solve a problem with information that has been compiled using some form of human expertise.
- Fail safe is a design property of an item in which the specified failure mode is predominantly in a safe direction with regard to the safety of the ship, as a primary concern.
- Full redundant is used to describe an automation system comprising two (identical or non-identical) independent systems which perform the same function and operate simultaneously.
- Hot standby system is used to describe an automation system comprising two (identical or non-identical) independent systems which perform the same function, one of which is in operation while the other is on standby with an automatic change-over switch.
- Instrumentation is a sensor or monitoring element.
- Integrated system is a system consisting of two or more subsystems having independent functions connected by a data transmission network and operated from one or more workstations.
- Local control is control of an operation at a point on or adjacent to the controlled switching device.
- Manual control is control of an operation acting on final control devices either directly or indirectly with the aid of electrical, hydraulic or mechanical power.
- Monitoring system is a system designed to observe the correct operation of the equipment by detecting incorrect functioning (measure of variables compared with specified value).
- Safety system is a system intended to limit the consequence of failure and is activated automatically when an abnormal condition appears.
- Software is the program, procedures and associated documentation pertaining to the operation of the computer system.
- Redundancy is the existence of more than one means for performing a required function.
- Remote control is the control from a distance of apparatus by means of an electrical or other link.

## 1.4 General

**1.4.1** The automation systems and components, as indicated in Ch 2, Sec 15, [2], are to be chosen from among the list of type approved products.

They are to be approved on the basis of the applicable requirements of these Rules and in particular those stated in this Chapter.

Case by case approval may also be granted at the discretion of the Society, based on submission of adequate documentation and subject to the satisfactory outcome of any required tests.

**1.4.2** Main and auxiliary machinery essential for the propulsion, control and safety of the ship shall be provided with effective means for its operation and control.

**1.4.3** Control, alarm and safety systems are to be based on the fail-to-safety principle.

**1.4.4** Failure of automation systems is to generate an alarm.

**1.4.5** Detailed indication, alarm and safety requirements regarding automation systems for individual machinery and installations are to be found in Chapter 1.

## 2 Documentation

### 2.1 General

**2.1.1** The Manufacturer, Designer or Shipbuilder is to submit to the Society the documents (plans, diagrams, specifications and calculations) requested in this Section.

The list of documents requested is to be intended as guidance for the complete set of information to be submitted, rather than an actual list of titles.

The Society reserves the right to request the submission of additional documents in the case of non-conventional design or if it is deemed necessary for the evaluation of the system, equipment or components.

Plans are to include all the data necessary for their interpretation, verification and approval.

Unless otherwise agreed with the Society, documents for approval are to be sent in triplicate if submitted by the Shipyard and in four copies if submitted by the equipment supplier. Documents requested for information are to be sent in duplicate.

In any case, the Society reserves the rights to require additional copies, when deemed necessary.

### 2.2 Documents to be submitted

**2.2.1** The documents listed in Tab 1 are to be submitted.

**Table 1 : Documentation to be submitted**

No.	I/A (1)	Documentation
1	A	The general specification for the automation of the ship
2	A	The detailed specification of the essential service systems
3	A	The list of components used in the automation circuits, and references (Manufacturer, type, etc.)
4	I	Instruction manuals
5	I	Test procedures for control, alarm and safety systems
6	A	A general diagram showing the monitoring and/or control positions for the various installations, with an indication of the means of access and the means of communication between the positions as well as with the engineers
7	A	The diagrams of the supply circuits of automation systems, identifying the power source
8	A	The list of monitored parameters for alarm/monitoring and safety systems
9	A	Diagram of the engineers' alarm system
(1) A = to be submitted for approval; I = to be submitted for information.		

**Table 2 : Documentation to be submitted for programmable electronic systems**

No.	I/A (1)	Documentation (2)
1	A	System block diagram, showing the arrangement of individual parts, input and output devices and interconnections
2	A	Wiring connection diagrams, including details of electrical power supplies, and of input and output devices
3	A	System functional description
4	I	System description and documentation
5	I	User interface description
6	I	Test programs
(1) A = to be submitted for approval; I = to be submitted for information.		
(2) See as guidance IEC 60092-504 clause 10.11		

## 2.3 Documents for programmable electronic system

### 2.3.1 General

For programmable electronic systems, the documents listed in Tab 2 are to be submitted.

## 3 Environmental and supply conditions

### 3.1 General

#### 3.1.1 General

The automation system is to operate correctly when conditions are within the range specified in Sec 2.

#### 3.1.2 Environmental conditions

The automation system is to be designed to operate satisfactorily in the environment in which it is located. The environmental conditions are described in Ch 2, Sec 2.

### 3.2 Power supply conditions

#### 3.2.1 Electrical power supply

The conditions of power supply to be considered are defined in Ch 2, Sec 2.

#### 3.2.2 Pneumatic power supply

For pneumatic equipment, the operational characteristics are to be maintained under permanent supply pressure variations of  $\pm 20\%$  of the rated pressure.

Detailed requirements are given in Ch 1, Sec 10.

#### 3.2.3 Hydraulic power supply

For hydraulic equipment, the operational characteristics are to be maintained under permanent supply pressure variations of  $\pm 20\%$  of the rated pressure.

Detailed requirements are given in Ch 1, Sec 10.

## 4 Materials and construction

### 4.1 General

**4.1.1** The choice of materials and components is to be made according to the environmental and operating conditions in order to maintain the proper function of the equipment.

**4.1.2** The design and construction of the automation equipment is to take into account the environmental and operating conditions in order to maintain the proper function of the equipment.

### 4.2 Type approved components

**4.2.1** See Ch 2, Sec 15.

## SECTION 2

## DESIGN REQUIREMENTS

### 1 General

#### 1.1

**1.1.1** All control systems essential for the propulsion, control and safety of the ship shall be independent or designed such that failure of one system does not degrade the performance of another system.

#### **1.1.2 Controlled systems are to have manual operation.**

Failure of any part of such systems shall not prevent the use of the manual override.

**1.1.3** Automation systems are to have constant performance.

**1.1.4** Safety functions are to be independent of control and monitoring functions. As far as practicable, control and monitoring functions are also to be independent.

**1.1.5** Control, monitoring and safety systems are to have self-check facilities. In the event of failure, an alarm is to be activated.

In particular, failure of the power supply of the automation system is to generate an alarm.

**1.1.6** When a programmable electronic system is used for control, alarm or safety systems, it is to comply with the requirements of Sec 3.

### 2 Power supply of automation systems

#### 2.1 General

**2.1.1** The source of power supply of automation systems is to be duplicated. Batteries or pneumatic or hydraulic accumulators, installed to allow the system to be continuously powered, are not considered as a duplication of the power supply. Failure of these power supplies is to generate an alarm.

#### 2.2 Electrical power supply

**2.2.1** The power supply is to be protected against short circuit and overload for each independent automation system.

**2.2.2** The capacity of the back-up source is to be sufficient to allow the normal operation of the alarm and safety system for at least half an hour.

### 3 Control systems

#### 3.1 Local control

**3.1.1** Each system is to be able to be operated manually from a position located so as to enable visual control of operation. For detailed instrumentation for each system, refer to Chapter 1 and Chapter 2.

It shall also be possible to control the auxiliary machinery, essential for the propulsion and safety of the ship, at or near the machinery concerned.

#### 3.2 Remote control systems

**3.2.1** When several control stations are provided, control of machinery is to be possible at one station at a time.

**3.2.2** At each location there shall be an indicator showing which location is in control of the propulsion machinery.

**3.2.3** Remote control is to be provided with the necessary instrumentation, in each control station, to allow effective control (correct function of the system, indication of control station in operation, alarm display).

**3.2.4** When transferring the control location, no significant alteration of the controlled equipment is to occur. Transfer of control is to be protected by an audible warning and acknowledged by the receiving control location. The main control location is to be able to take control without acknowledgement.

#### 3.3 Automatic control systems

**3.3.1** Automatic starting, operational and control systems shall include provisions for manually overriding the automatic controls.

**3.3.2** Automatic control is to be stable in the range of the controller in normal working conditions.

**3.3.3** Automatic control is to have instrumentation to verify the correct function of the system.

### 4 Control of propulsion machinery

#### 4.1 Remote control

**4.1.1** The requirements mentioned in [3] are to be applied for propulsion machinery.

**4.1.2** The design of the remote control system shall be such that in case of its failure an alarm will be given.

**4.1.3** Supply failure (voltage, fluid pressure, etc.) in propulsion plant remote control is to activate an alarm at the

control position. In the event of remote control system failure and unless the Society considers it impracticable, the preset speed and direction of thrust are to be maintained until local control is in operation. This applies in particular in the case of loss of electric, pneumatic or hydraulic supply to the system.

**4.1.4** Propulsion machinery orders from the navigation bridge shall be indicated in the main machinery control room, and at the manoeuvring platform.

**4.1.5** The control shall be performed by a single control device for each independent propeller, with automatic performance of all associated services, including, where necessary, means of preventing overload of the propulsion machinery. Where multiple propellers are designed to operate simultaneously, they must be controlled by one control device.

**4.1.6** Indicators shall be fitted on the navigation bridge, in the main machinery control room and at the manoeuvring platform, for:

propeller speed and direction of rotation in the case of fixed pitch propellers; and

propeller speed and pitch position in the case of controllable pitch propellers.

**4.1.7** The main propulsion machinery shall be provided with an emergency stopping device on the navigation bridge which shall be independent of the navigation bridge control system.

In the event that there is no reaction to an order to stop, provision is to be made for an alternative emergency stop. This emergency stopping device may consist of a simple and clearly marked control device, for example a push-button. This fitting is to be capable of suppressing the propeller thrust, whatever the cause of the failure may be.

## 4.2 Remote control from navigating bridge

**4.2.1** Where propulsion machinery is controlled from the navigating bridge, the remote control is to include an automatic device such that the number of operations to be carried out is reduced and their nature is simplified and such that control is possible in both the ahead and astern directions. Where necessary, means for preventing overload and running in critical speed ranges of the propulsion machinery is to be provided.

Note 1: Arrangements which are not in compliance with the provisions of this Article may be considered for the following ships:

- ships of less than 24 m in length
- cargo ships of less than 500 tons gross tonnage
- ships to be assigned restricted navigation notations
- non-propelled units.

**4.2.2** On board ships fitted with remote control, direct control of the propulsion machinery is to be provided locally. The local direct control is to be independent from the remote control circuits, and takes over any remote control when in use.

**4.2.3** Each local control position, including partial control (e.g. local control of controllable pitch propellers or clutches) is to be provided with means of communication with each remote control position. The local control positions are to be independent from remote control of propulsion machinery and continue to operate in the event of a blackout (see Note 1 in [4.2.1]).

**4.2.4** Remote control of the propulsion machinery shall be possible only from one location at a time; at such locations interconnected control positions are permitted.

**4.2.5** The transfer of control between the navigating bridge and machinery spaces shall be possible only in the main machinery space or the main machinery control room. The system shall include means to prevent the propelling thrust from altering significantly, when transferring control from one location to another (see Note 1 in [4.2.1]).

**4.2.6** At the navigating bridge, the control of the routine manoeuvres for one line of shafting is to be performed by a single control device: a lever, a handwheel or a push-button board. However each mechanism contributing directly to the propulsion, such as the engine, clutch, automatic brake or controllable pitch propeller, is to be able to be individually controlled, either locally or at a central monitoring and control position in the engine room (see Note 1 in [4.2.1]).

**4.2.7** Remote starting of the propulsion machinery is to be automatically inhibited if a condition exists which may damage the machinery, e.g. shaft turning gear engaged, drop of lubrication oil pressure or brake engaged.

**4.2.8** As a general rule, the navigating bridge panels are not to be overloaded by alarms and indications which are not required.

## 4.3 Automatic control

**4.3.1** The requirements in [3] are applicable. In addition, the following requirements are to be considered, if relevant.

**4.3.2** Main turbine propulsion machinery and, where applicable, main internal combustion propulsion machinery and auxiliary machinery shall be provided with automatic shutoff arrangements in the case of failures such as lubricating oil supply failure which could lead rapidly to complete breakdown, serious damage or explosion.

**4.3.3** The automatic control system is to be designed on a fail safe basis, and, in the event of failure, the system is to be adjusted automatically to a predetermined safe state.

**4.3.4** When the remote control system of the propulsion machinery includes automatic starting, the number of automatic consecutive attempts is to be limited at a preset value of the starting air pressure permitting 3 attempts, and an alarm is to be provided, on the navigation bridge and in the machinery space.

**4.3.5** Operations following any setting of the bridge control device (including reversing from the maximum ahead service speed in case of emergency) are to take place in an automatic sequence and with acceptable time intervals, as prescribed by the manufacturer.



#### 4.4 Automatic control of propulsion and manoeuvring units

**4.4.1** When the power source actuating the automatic control of propelling units fails, an alarm is to be triggered. In such case, the preset direction of thrust is to be maintained long enough to allow the intervention of engineers. Failing this, minimum arrangements, such as stopping of the shaft line, are to be provided to prevent any unexpected reverse of the thrust. Such stopping may be automatic or ordered by the operator, following an appropriate indication.

#### 4.5 Clutches

**4.5.1** Where the clutch of a propulsion engine is operated electrically, pneumatically or hydraulically, an alarm is to be given at the control station in the event of loss of energy; as far as practicable, this alarm is to be triggered while it is still possible to operate the equipment (see Note 1 in [4.2.1]).

**4.5.2** When only one clutch is installed, its control is to be fail-set. Other arrangements may be considered in relation to the configuration of the propulsion machinery.

#### 4.6 Brakes

**4.6.1** Automatic or remote controlled braking is to be possible only if:

- propulsion power has been shut off
- the turning gear is disconnected
- the shaftline speed (r.p.m.) is below the threshold stated by the builder (see Note 1 in [4.2.1]).

### 5 Remote control of valves

#### 5.1

**5.1.1** The following requirements are applicable to valves whose failure could impair essential services.

**5.1.2** Failure of the power supply is not to permit a valve to move to an unsafe condition.

**5.1.3** An indication is to be provided at the remote control station showing the actual position of the valve or whether the valve is fully open or fully closed.

**5.1.4** In case of failure of manually operated or automatic remote control systems, the local control of valves is to be possible.

**5.1.5** Equipment located in places which may be flooded is to be capable of operation even if submerged.

### 6 Alarm system

#### 6.1 General requirements

**6.1.1** Alarms are to be visual and audible and are to be clearly distinguishable, in the ambient noise and lighting in

the normal position of the personnel, from any other signals.

**6.1.2** Sufficient information is to be provided for proper handling of alarms.

**6.1.3** The alarm system is to be of the self-check type; failure within the alarm system, including the outside connection, is to activate an alarm. The alarm circuits are to be independent from each other. All alarm circuits are to be protected so as not to endanger each other.

#### 6.2 Alarm functions

##### 6.2.1 Alarm activation

Alarms are to be activated when abnormal conditions appear in the machinery, which need the intervention of personnel on duty, and on the automatic change-over, when standby machines are installed.

An existing alarm is not to prevent the indication of any further fault.

##### 6.2.2 Acknowledgement of alarm

The acknowledgment of an alarm consists in manually silencing the audible signal and additional visual signals (e.g. rotating light signals) while leaving the visual signal on the active control station. Acknowledged alarms are to be clearly distinguishable from unacknowledged alarms. Acknowledgement should not prevent the audible signal to operate for new alarm.

Alarms shall be maintained until they are accepted and visual indications of individual alarms shall remain until the fault has been corrected, when the alarm system shall automatically reset to the normal operating condition.

Acknowledgement of alarms is only to be possible at the active control station.

Alarms, including the detection of transient faults, are to be maintained until acknowledgement of the visual indication.

Acknowledgement of visual signals is to be separate for each signal or common to a limited group of signals. Acknowledgement is only to be possible when the user has visual information on the alarm condition for the signal or all signals in a group.

##### 6.2.3 Locking of alarms

Manual locking of separate alarms may be accepted when this is clearly indicated.

Locking of alarm and safety functions in certain operating modes (e.g. during start-up or trimming) is to be automatically disabled in other modes.

##### 6.2.4 Time delay of alarms

It is to be possible to delay alarm activation in order to avoid false alarms due to normal transient conditions (e.g. during start-up or trimming).

##### 6.2.5 Engineers' alarm

An engineers' alarm shall be provided to be operated from the engine control room or at the manoeuvring platform as appropriate, and shall be clearly audible in the engineers' accommodation.

### 6.2.6 Transfer of responsibility

Where several alarm control stations located in different spaces are provided, responsibility for alarms is not to be transferred before being acknowledged by the receiving location. Transfer of responsibility is to give an audible warning. At each control station it is to be indicated which location is in charge.

### 6.2.7 Alarm systems with limited number of monitored positions

For alarms with a limited number of monitored positions, relaxation to the requirements of [6.2] may be granted at judgement of the Society

## 7 Safety system

### 7.1 Design

#### 7.1.1 System failures

A safety system is to be designed so as to limit the consequence of failures. It is to be constructed on the fail-to-safety principle.

The safety system is to be of the self-check type; as a rule, failure within the safety system, including the outside connection, is to activate an alarm.

### 7.2 Function

#### 7.2.1 Safety activation

The safety system is to be activated automatically in the event of identified conditions which could lead to damage of associated machinery or systems, such that:

- normal operating conditions are restored (e.g. by the starting of the standby unit), or
- the operation of the machinery is temporarily adjusted to the prevailing abnormal conditions (e.g. by reducing the output of the associated machinery), or
- the machinery is protected, as far as possible, from critical conditions by shutting off the fuel or power supply, thereby stopping the machinery (shutdown), or appropriate shutdown.

### 7.2.2 Safety indication

When the safety system has been activated, it is to be possible to trace the cause of the safety action. This is to be accomplished by means of a central or local indication.

When a safety system is made inoperative by a manual override, this is to be clearly indicated at corresponding control stations.

Automatic safety actions are to activate an alarm at predefined control stations.

### 7.3 Shutdown

**7.3.1** For shutdown systems of machinery, the following requirements are to be applied:

- when the system has stopped a machine, the latter is not to be restarted automatically before a manual reset of the safety system has been carried out
- the shutdown of the propulsion system is to be limited to those cases which could lead to serious damage, complete breakdown or explosion.

### 7.4 Standby systems

**7.4.1** For the automatic starting system of the standby units, the following requirements are to be applied:

- faults in the electrical or mechanical system of the running machinery are not to prevent the standby machinery from being automatically started
- when a machine is on standby, ready to be automatically started, this is to be clearly indicated at its control position
- the change-over to the standby unit is to be indicated by a visual and audible alarm
- means are to be provided close to the machine, to prevent undesired automatic or remote starting (e.g. when the machine is being repaired)
- automatic starting is to be prevented when conditions are present which could endanger the standby machine.

### 7.5 Testing

**7.5.1** The safety systems are to be tested in accordance with the requirements in Sec 6.

## SECTION 3

## PROGRAMMABLE ELECTRONIC SYSTEMS

### 1 Scope

#### 1.1 General

**1.1.1** These Requirements apply to the use of programmable electronic systems that provide control, alarm, monitoring or safety functions which are subject to classification requirements.

Aids to navigation and loading instruments are excluded.

Note 1: For loading instrument / stability computer, IACS Rec. No. 48 may be considered.

### 2 Requirements applicable to programmable electronic systems

#### 2.1 General

**2.1.1** Programmable electronic systems are to fulfil the requirements of the system under control for all normally anticipated operating conditions, taking into account danger to persons, environmental impact, damage to the ship as well as equipment, usability of programmable electronic systems and operability of non-computer devices and systems etc.

**2.1.2** When an alternative design or arrangements deviating from these requirements are proposed, an engineering analysis is required to be carried out in accordance with a relevant International or National Standard acceptable to the Society.

Note 1: As a failure of a category III system may lead to an accident with catastrophic severity, the use of unconventional technology for such applications will only be permitted exceptionally in cases where evidence is presented that demonstrates acceptable and reliable system performance to the satisfaction of the Society.

#### 2.2 System categories

**2.2.1** Programmable electronic systems are to be assigned into three system categories as shown in Tab 1 according to the possible extent of the damage caused by a single failure within the programmable electronic systems.

Consideration is to be given to the extent of the damage directly caused by a failure, but not to any consequential damage.

Identical redundancy will not be taken into account for the assignment of a system category.

**2.2.2** The assignment of a programmable electronic system to the appropriate system category is to be made according to the greatest likely extent of direct damage. For examples, see Tab 2.

Note 1: Where independent effective backup or other means of averting danger is provided, system category III may be decreased by one category.

#### 2.3 Data communication links

**2.3.1** These requirements apply to system categories II and III using shared data communication links to transfer data between distributed programmable electronic equipment or systems.

**2.3.2** Where a single component failure results in loss of data communication, means are to be provided to automatically restore data communication.

**2.3.3** Loss of a data communication link is not to affect the ability to operate essential services by alternative means.

**2.3.4** Means are to be provided to protect the integrity of data and provide timely recovery of corrupted or invalid data.

**2.3.5** The data communication link is to be self-checking, detecting failures on the link itself and data communication failures on nodes connected to the link. Detected failures are to initiate an alarm.

**2.3.6** System self-checking capabilities shall be arranged to initiate transition to the least hazardous state for the complete installation in the event of data communication failure.

**2.3.7** The characteristics of the data communication link shall be such as to transmit that all necessary information in adequate time and overloading is prevented.

**Table 1 : System categories**

Category	Effects	System functionality
I	Those systems, failure of which will not lead to dangerous situations for human safety, safety of the vessel and/or a threat to the environment.	Monitoring function for informational / administrative tasks
II	Those systems, failure of which could eventually lead to dangerous situations for human safety, safety of the vessel and/or a threat to the environment.	<ul style="list-style-type: none"> <li>Alarm and monitoring functions</li> <li>Control functions which are necessary to maintain the ship in its normal operational and habitable conditions</li> </ul>
III	Those systems, failure of which could immediately lead to dangerous situations for human safety, safety of the vessel and/or a threat to the environment.	<ul style="list-style-type: none"> <li>Control functions for maintaining the vessel's propulsion and steering</li> <li>Safety functions</li> </ul>

**Table 2 : Examples of assignment to system categories**

Category	Examples
I	Maintenance support systems, Information and diagnostic systems
II	Alarm and monitoring equipment, Tank capacity measuring equipment, Control systems for auxiliary machinery, Main propulsion remote control systems, Fire detection systems, Fire-extinguishing systems, Bilge systems, Governors
III	Machinery protection systems/equipment, Burner control systems, Electronic fuel injection for diesel engines, Control systems for propulsion and steering, Synchronising units for switchboards
<b>Note 1:</b> The examples listed are not exhaustive.	

## 2.4 Additional requirements for wireless data links

**2.4.1** These requirements are in addition to the requirements of [2.3.1] to [2.3.7] and apply to system category II using wireless data communication links to transfer data between distributed programmable electronic equipment or systems. For system category III, the use of wireless data communication links is to be in accordance with [2.1.2].

**2.4.2** Functions that are required to operate continuously to provide essential services dependant on wireless data communication links shall have an alternative means of control that can be brought in action within an acceptable period of time .

**2.4.3** Wireless data communication is to employ recognised international wireless communication system protocols that incorporate the following:

- Message integrity. Fault prevention, detection, diagnosis, and correction so that the received message is not corrupted or altered when compared to the transmitted message;
- Configuration and device authentication. It is only to permit connection of devices that are included in the system design;
- Message encryption. Protection of the confidentiality and or criticality the data content;
- Security management. Protection of network assets, prevention of unauthorised access to network assets.

**2.4.4** The wireless system is to comply with the radio frequency and power level requirements of International Telecommunications Union and flag state requirements.

Note 1: Consideration should be given to system operation in the event of port state and local regulations that pertain to the use of radio-frequency transmission prohibiting the operation of a wireless data communication link due to frequency and power level restrictions

## 2.5 Protection against modification

**2.5.1** Programmable electronic systems of categories II and III are to be protected against program modification by the user.

**2.5.2** For systems of category III, modifications of parameters by the Manufacturer are to be approved by the Society.

**2.5.3** Any modifications made after performance of the tests witnessed by the Society as per item 6 in Table 3 are to be documented and traceable.

## 3 Documentation

### 3.1 Documents to be submitted

**3.1.1** For the evaluation of programmable electronic systems of categories II and III, documents according to IEC 60092-504 paragraph 10.11 are to be submitted (see Sec 1, Tab 2).

**3.1.2** When alternative design or arrangement is intended to be used, an engineering analysis is to be submitted in addition.

**3.1.3** For all tests required in accordance with the system category, a test plan is to be submitted and the tests are to be documented.

**3.1.4** Additional documentation may be required for systems of category III. The documentation is to include a description of the test methods and the required test results.

**3.1.5** For wireless data communication equipment, the following additional information is to be submitted:

- a) Details of manufacturers recommended installation and maintenance practices;
- b) Network plan with arrangement and type of antennas and identification of location;
- c) Specification of wireless communication system protocols and management functions; see [2.4.3];
- d) Details of radio frequency and power levels;
- e) Evidence of type testing in accordance with Ch 3, Sez 6;
- f) On-board test schedule, see [5.7.3].

**3.1.6** Documents for the evaluation of programmable electronic systems of category I are to be submitted if requested.

**3.1.7** Modifications are to be documented by the Manufacturer. Subsequent significant modifications to the software and hardware for system categories II and III are to be submitted for approval.

Note 1: A significant modification is a modification which influences the functionality and/or safety of the system.

## **4 Tests and Evidence**

### **4.1**

**4.1.1** Tests and evidence are to be in accordance with Tab 3. Definitions and notes relating to Tab 3 are given in item [5].

**Table 3 : Tests and evidence according to the system category**

No.	Tests and evidence	System Category		
		I	II	III
1	Evidence of quality system			
	Quality plan for software		M	M
	Inspection of components (hardware only ) from sub-suppliers		M	M
	Quality control in production		M	M
	Final test reports	M	M	S
	Traceability of software	M	M	S
2	Hardware and software description			
	Software description		M	S
	Hardware description		M	S
	Failure analysis for safety related functions only			S
3	Evidence of software testing			
	Evidence of software testing according to quality plan		M	S
	Analysis regarding existence and fulfilment of programming procedures for safety related functions			S
4	Hardware tests			
	Tests according to Sec 6		W	W
5	Software tests			
	Module tests		M	S
	Subsystem tests		M	S
	System test		M	S
6	Performance tests			
	Integration test		M	W
	Fault simulation		W	W
	Factory Acceptance Test (FAT)	M	W	W
7	On board test			
	Complete system test	M	W	W
	Integration test		W	W
	Operation of wireless equipment to demonstrate electromagnetic compatibility		W	W*
8	Modifications			
	Tests after modifications	M	S/W	S/W
<p><b>Note 1:</b> M = Evidence kept by the Manufacturer and submitted on request  S = Evidence checked by the Society  W = To be witnessed by the Society  * = The level of witnessing will be determined during the assessment required by [2.1.2]</p>				

## 5 Definitions and notes relating to Tab 3, tests and evidence

### 5.1 Evidence of quality system

#### 5.1.1 Quality plan for software

A plan for software lifecycle activities is to be produced which defines relevant procedures, responsibilities and system documentation, including configuration management.

#### 5.1.2 Inspection of components (hardware only) from sub-suppliers

Proof that components and/or sub-assemblies conform to specification.

#### 5.1.3 Quality control in production

Evidence of quality assurance measures on production.

#### 5.1.4 Final test reports

Reports from testing of the finished product and documentation of the test results.

#### 5.1.5 Traceability of software

Modification of program contents and data, as well as change of version is to be carried out in accordance with a procedure and is to be documented.

### 5.2 Hardware and software description

#### 5.2.1 Software description

Software is to be described, e.g.

- Description of the basic and communication software installed in each hardware unit
- Description of application software (not program listings)
- Description of functions, performance, constraints and dependencies between modules or other components.

#### 5.2.2 Hardware description

Hardware is to be described, e.g.

- System block diagram, showing the arrangement, input and output devices and interconnections
- Connection diagrams
- Details of input and output devices
- Details of power supplies.

#### 5.2.3 Failure analysis for safety related functions only (e.g. FMEA)

The analysis is to be carried out using appropriate means, e.g.

- Fault tree analysis
- Risk analysis
- FMEA or FMECA

The purpose is to demonstrate that, for single failures, systems will fail to safety and that systems in operation will not be lost or degraded beyond acceptable performance criteria when specified by the Society.

### 5.3 Evidence of software testing

#### 5.3.1 Evidence of software testing according to quality plan

Procedures for verification and validation activities are to be established, e.g.

- Methods of testing
- Production of test programs
- Simulation.

#### 5.3.2 Analysis regarding existence and fulfilment of programming procedures for safety related functions

Specific assurance methods are to be planned for verification and validation of fulfilment of requirements, e.g.

- Diverse programs
- Program analysis and testing to detect formal errors and discrepancies in the description
- Simple structure.

### 5.4 Hardware tests

#### 5.4.1

Testing according to Sec 6 will normally be a type approval test.

Special consideration may be given to tests witnessed and approved by another QSCS Classification Society (see Pt A, Ch 1, Sec 1, [1.2.1]).

### 5.5 Software tests

#### 5.5.1 Module tests

Software module tests are to provide evidence that each module performs its intended function and does not perform unintended functions.

#### 5.5.2 Subsystem tests

Subsystem testing is to verify that modules interact correctly to perform the intended functions and do not perform unintended functions.

#### 5.5.3 System tests

System testing is to verify that subsystems interact correctly to perform the functions in accordance with specified requirements and do not perform unintended functions.

### 5.6 Performance tests

#### 5.6.1 Integration tests

Programmable electronic system integration testing is to be carried out using satisfactorily tested system software, and as far as practicable intended system components.

#### 5.6.2 Fault simulation

Faults are to be simulated as realistically as possible to demonstrate appropriate system fault detection and system response. The results of any required failure analysis are to be observed.

### **5.6.3 Factory Acceptance Test (FAT)**

Factory acceptance testing is to be carried out in accordance with a test program accepted by the Society. Testing is to be based on demonstrating that the system fulfils the requirements specified by the Society.

## **5.7 On board tests**

### **5.7.1 Complete system test**

Testing is to be performed on the completed system comprising actual hardware components with the final application software, in accordance with an approved test program.

### **5.7.2 Integration tests**

On board testing is to verify that correct functionality has been achieved with all systems integrated.

**5.7.3** For wireless data communication equipment, tests during harbour and sea trials are to be conducted to demonstrate that radio-frequency transmission does not cause failure of any equipment and does not itself fail as a result of electromagnetic interference during expected operating conditions.

Note 1: Where electromagnetic interference caused by wireless data communication equipment is found to be causing failure of equipment required for Category II or III systems, the layout and / or equipment shall be changed to prevent further failures occurring.

## **5.8 Modifications**

### **5.8.1 Tests after modifications**

Modifications to approved systems are to be announced in advance and carried out to the Society's satisfaction; see item [3.1.7].



## SECTION 4

## CONSTRUCTIONAL REQUIREMENTS

### 1 General

#### 1.1 Construction

**1.1.1** Automation systems are to be so constructed as:

- to withstand the environmental conditions, as defined in Ch 2, Sec 2, [1], in which they operate
- to have necessary facilities for maintenance work.

#### 1.2 Materials

**1.2.1** Materials are generally to be of the flame-retardant type.

**1.2.2** Connectors are to be able to withstand standard vibrations, mechanical constraints and corrosion conditions as given in Sec 6.

#### 1.3 Component design

**1.3.1** Automation components are to be designed to simplify maintenance operations. They are to be so constructed as to have:

- easy identification of failures
- easy access to replaceable parts
- easy installation and safe handling in the event of replacement of parts (plug and play principle) without impairing the operational capability of the system, as far as practicable
- facility for adjustment of set points or calibration
- test point facilities, to verify the proper operation of components.

#### 1.4 Environmental and supply conditions

**1.4.1** The environmental and supply conditions are specified in Sec 1. Specific environmental conditions are to be considered for air temperature and humidity, vibrations, corrosion from chemicals and mechanical or biological attacks.

### 2 Electrical and/or electronic systems

#### 2.1 General

**2.1.1** Electrical and electronic equipment is to comply with the requirements of Chapter 2 and Chapter 3.

**2.1.2** A separation is to be done between any electrical components and liquids, if they are in a same enclosure. Necessary drainage will be provided where liquids are likely to leak.

**2.1.3** When plug-in connectors or plug-in elements are used, their contacts are not to be exposed to excessive mechanical loads. They are to be provided with a locking device.

**2.1.4** All replaceable parts are to be so arranged that it is not possible to connect them incorrectly or to use incorrect replacements. Where this not practicable, the replacement parts as well as the associated connecting devices are to be clearly identified. In particular, all connection terminals are to be properly tagged. When replacement cannot be carried out with the system on, a warning sign is to be provided.

**2.1.5** Forced cooling systems are to be avoided. Where forced cooling is installed, an alarm is to be provided in the event of failure of the cooling system.

**2.1.6** The interface connection is to be so designed to receive the cables required. The cables are to be chosen according to Ch 2, Sec 3.

#### 2.2 Electronic system

**2.2.1** Printed circuit boards are to be so designed that they are properly protected against the normal aggression expected in their environment.

**2.2.2** Electronic systems are to be constructed taking account of electromagnetic interferences.

Special precautions are to be taken for:

- measuring elements such as the analogue amplifier or analog/digital converter; and
- connecting different systems having different ground references.

**2.2.3** The components of electronic systems (printed circuit board, electronic components) are to be clearly identifiable with reference to the relevant documentation.

**2.2.4** Where adjustable set points are available, they are to be readily identifiable and suitable means are to be provided to protect them against changes due to vibrations and uncontrolled access.

**2.2.5** The choice of electronic components is to be made according to the normal environmental conditions, in particular the temperature rating.

**2.2.6** All stages of fabrication of printed circuit boards are to be subjected to quality control. Evidence of this control is to be documented.

**2.2.7** Burn-in tests or equivalent tests are to be performed.

**2.2.8** The programmable components are to be clearly tagged with the program date and reference.

Components are to be protected against outside alteration when loaded.

## **2.3 Electrical system**

**2.3.1** Cables and insulated conductors used for internal wiring are to be at least of the flame-retardant type, and are to comply with the requirements in Chapter 2.

**2.3.2** If specific products (e.g. oil) are likely to come into contact with wire insulation, the latter is to be resistant to such products or properly shielded from them, and to comply with the requirements in Chapter 2.

## **3 Pneumatic systems**

### **3.1**

**3.1.1** Pneumatic automation systems are to comply with Ch 1, Sec 10, [14].

**3.1.2** Pneumatic circuits of automation systems are to be independent of any other pneumatic circuit on board.

## **4 Hydraulic systems**

### **4.1**

**4.1.1** Hydraulic automation systems are to comply with Ch 1, Sec 10, [14].

**4.1.2** Suitable filtering devices are to be incorporated into the hydraulic circuits.

**4.1.3** Hydraulic circuits of automation systems are to be independent of any other hydraulic circuit on board.

## **5 Automation consoles**

### **5.1 General**

**5.1.1** Automation consoles are to be designed on ergonomic principles. Handrails are to be fitted for safe operation of the console.

### **5.2 Indicating instruments**

**5.2.1** The operator is to receive feed back information on the effects of his orders.

**5.2.2** Indicating instruments and controls are to be arranged according to the logic of the system in control. In addition, the operating movement and the resulting movement of the indicating instrument are to be consistent with each other.

**5.2.3** The instruments are to be clearly labelled. When installed in the wheelhouse, all lighted instruments of consoles are to be dimmable, where necessary.

### **5.3 VDU's and keyboards**

**5.3.1** VDU's in consoles are to be located so as to be easily readable from the normal position of the operator. The environmental lighting is not to create any reflection which makes reading difficult.

**5.3.2** The keyboard is to be located to give easy access from the normal position of the operator. Special precautions are to be taken to avoid inadvertent operation of the keyboard.

## SECTION 5

## INSTALLATION REQUIREMENTS

### 1 General

#### 1.1

**1.1.1** Automation systems are to be installed taking into account:

- the maintenance requirements (test and replacement of systems or components)
- the influence of EMI. The IEC 60533 standard is to be taken as guidance
- the environmental conditions corresponding to the location in accordance with Ch 2, Sec 1 and Ch 2, Sec 3, [6].

**1.1.2** Control stations are to be arranged for the convenience of the operator.

**1.1.3** Automation components are to be properly fitted. Screws and nuts are to be locked, where necessary.

### 2 Sensors and components

#### 2.1 General

**2.1.1** The location and selection of the sensor is to be done so as to measure the actual value of the parameter. Temperature, vibration and EMI levels are to be taken into account. When this is not possible, the sensor is to be designed to withstand the local environment.

**2.1.2** The enclosure of the sensor and the cable entry are to be appropriate to the space in which they are located.

**2.1.3** Means are to be provided for testing, calibration and replacement of automation components. Such means are to be designed, as far as practicable, so as to avoid perturbation of the normal operation of the system.

**2.1.4** A tag number is to identify automation components and is to be clearly marked and attached to the component. These tag numbers are to be collected on the instrument list mentioned in Sec 1, Tab 1.

**2.1.5** Electrical connections are to be arranged for easy replacement and testing of sensors and components. They are to be clearly marked.

**2.1.6** Low level signal sensors are to be avoided. When installed they are to be located as close as possible to amplifiers, so as to avoid external influences. Failing this, the wiring is to be provided with suitable EMI protection and temperature correction.

### 2.2 Temperature elements

**2.2.1** Temperature sensors, thermostats or thermometers are to be installed in a thermowell of suitable material, to permit easy replacement and functional testing. The thermowell is not to significantly modify the response time of the whole element.

### 2.3 Pressure elements

**2.3.1** Three-way valves or other suitable arrangements are to be installed to permit functional testing of pressure elements, such as pressure sensors, pressure switches or pressure gauges, without stopping the installation.

**2.3.2** In specific applications, where high pulsations of pressure are likely to occur, a damping element, such as a capillary tube or equivalent, is to be installed.

### 2.4 Level switches

**2.4.1** Level switches fitted to flammable oil tanks, or similar installations, are to be installed so as to reduce the risk of fire.

## 3 Cables

### 3.1 Installation

**3.1.1** Cables are to be installed according to the requirements in Ch 2, Sec 12, [7].

**3.1.2** Suitable installation features such as screening and/or twisted pairs and/or separation between signal and other cables are to be provided in order to avoid possible interference on control and instrumentation cables.

**3.1.3** Specific transmission cables (coaxial cables, twisted pairs, etc.) are to be routed in specific cable-ways and mechanically protected to avoid loss of any important transmitted data. Where there is a high risk of mechanical damage, the cables are to be protected with pipes or equivalent.

**3.1.4** The cable bend radius is to be in accordance with the requirements of Ch 2, Sec 12, [7.2].

For mineral insulated cables, coaxial cables or fibre optic cables, whose characteristics may be modified, special precautions are to be taken according to the manufacturer's instructions.

## 3.2 Cable terminations

**3.2.1** Cable terminations are to be arranged according to the requirements in Chapter 2. Particular attention is to be paid to the connections of cable shields. Shields are to be connected only at the sensor end when the sensor is earthed, and only at the processor end when the sensor is floating.

**3.2.2** Cable terminations are to be able to withstand the identified environmental conditions (shocks, vibrations, salt mist, humidity, etc.).

**3.2.3** Terminations of all special cables such as mineral insulated cables, coaxial cables or fibre optic cables are to be arranged according to the manufacturer's instructions.

## 4 Pipes

### 4.1

**4.1.1** For installation of piping circuits used for automation purposes, see the requirements in Ch 1, Sec 10.

**4.1.2** As far as practicable, piping containing liquids is not to be installed in or adjacent to electrical enclosures (see Sec 4, [2.1.2] ).

**4.1.3** Hydraulic and pneumatic piping for automation systems is to be marked to indicate its function.

## 5 Automation consoles

### 5.1 General

**5.1.1** Consoles or control panels are to be located so as to enable a good view of the process under control, as far as practicable. Instruments are to be clearly readable in the ambient lighting.

**5.1.2** The location is to be such as to allow easy access for maintenance operations.

## SECTION 6

## TESTING

### 1 General

#### 1.1 Commissioning

**1.1.1** Automation systems are to be tested for type approval, acceptance or commissioning, when required. Tests are to be carried out under the supervision of a Surveyor of the Society.

**1.1.2** The type testing conditions for electrical, control and instrumentation equipment, computers and peripherals are described in [2].

**1.1.3** Automation systems are to be inspected at works, according to the requirements of [3], in order to check that the construction complies with the Rules.

**1.1.4** Automation systems are to be commissioned when installed on board and prior to sea trials, to verify their performance and adaptation on site, according to [4].

### 2 Type approval

#### 2.1 General

**2.1.1** This test specification for type approval is applicable, but not confined, to all equipment used for (see Note 1):

- control, protection and safety
- internal communication.

Note 1: These test requirements are harmonised with IEC 60092-504 "Electrical Installations in Ships -Part 504: Special features - Control and Instrumentation" and IEC 60533 "Electrical and electronic installations in ships - Electromagnetic compatibility". Electrical and electronic equipment on board ships, required neither by the Rules nor by International Conventions, liable to cause electromagnetic disturbance are to be of type which fulfill the test requirements of test specification items 19 and 20 of Tab 1.

**2.1.2** The necessary documents to be submitted, prior to type testing, are listed in Sec 1, [2.4.1]. The type approval of automation systems refers to hardware type approval or software type approval, as applicable.

#### 2.2 Hardware type approval

**2.2.1** These tests are to demonstrate the ability of the equipment to function as intended under the specified testing conditions.

The extent of the testing, i.e. the selection and sequence of tests and the number of pieces to be tested is to be determined upon examination and evaluation of the equipment or component subject to testing giving due regard to its intended use.

Equipment is to be tested in its normal position unless otherwise specified in the test specification.

The relevant tests are listed in Tab 1.

**2.2.2** The following additional tests may be required, depending on particular manufacturing or operational conditions:

- mechanical endurance test
- temperature shock test (e.g. 12 shocks on exhaust gas temperature sensors from 20°C ± 5°C to maximum temperature of the range)
- immersion test
- oil resistance test
- shock test.

The test procedure is to be defined with the Society in each case.

Table 1 : Type tests

No.	Test	Procedure (1)	Test parameters	Other information
1	Visual inspection			<ul style="list-style-type: none"> <li>conformance to drawings, design data.</li> </ul>
2	Performance test	Manufacturer performance test programme based upon specification and relevant Rule requirements.	<ul style="list-style-type: none"> <li>standard atmosphere condition</li> <li>temperature: 25°C ± 10°C</li> <li>relative humidity: 60% ± 30%</li> <li>air pressure: 96 KPa ± 10 KPa</li> </ul>	<ul style="list-style-type: none"> <li>confirmation that operation is in accordance with the requirements specified for particular system or equipment</li> <li>checking of self-monitoring features</li> <li>checking of specified protection against an access to the memory</li> <li>checking against effect an erroneous use of control elements in the case of computer systems</li> </ul>
3	External power supply failure		<ul style="list-style-type: none"> <li>3 interruptions during 5 minutes</li> <li>switching-off time 30 s each case</li> </ul>	<ul style="list-style-type: none"> <li>The time of 5 minutes may be exceeded if the equipment under test needs a longer time for start up, e.g. booting sequence</li> <li>For equipment which requires booting, one additional power supply interruption during booting to be performed</li> </ul> <p>Verification of:</p> <ul style="list-style-type: none"> <li>equipment behaviour upon loss and restoration of supply;</li> <li>possible corruption of programme or data held in programmable electronic systems, where applicable.</li> </ul>

No.	Test	Procedure (1)	Test parameters	Other information																														
4	Power supply variations a) Electric		<p style="text-align: center;">AC SUPPLY</p> <table border="1"> <thead> <tr> <th>Combina- tion</th> <th>Voltage varia- tion permanent</th> <th>Frequency varia- tion permanent</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>+ 6%</td> <td>+ 5%</td> </tr> <tr> <td>2</td> <td>+ 6%</td> <td>- 5%</td> </tr> <tr> <td>3</td> <td>- 10%</td> <td>- 5%</td> </tr> <tr> <td>4</td> <td>- 10%</td> <td>+ 5%</td> </tr> <tr> <td></td> <td>voltage tran- sient</td> <td>frequency transient</td> </tr> <tr> <td></td> <td>1,5 s</td> <td>5 s</td> </tr> <tr> <td></td> <td>%</td> <td>%</td> </tr> <tr> <td>5</td> <td>+ 20%</td> <td>+ 10%</td> </tr> <tr> <td>6</td> <td>- 20%</td> <td>- 10%</td> </tr> </tbody> </table>	Combina- tion	Voltage varia- tion permanent	Frequency varia- tion permanent	1	+ 6%	+ 5%	2	+ 6%	- 5%	3	- 10%	- 5%	4	- 10%	+ 5%		voltage tran- sient	frequency transient		1,5 s	5 s		%	%	5	+ 20%	+ 10%	6	- 20%	- 10%	
			Combina- tion	Voltage varia- tion permanent	Frequency varia- tion permanent																													
1	+ 6%	+ 5%																																
2	+ 6%	- 5%																																
3	- 10%	- 5%																																
4	- 10%	+ 5%																																
	voltage tran- sient	frequency transient																																
	1,5 s	5 s																																
	%	%																																
5	+ 20%	+ 10%																																
6	- 20%	- 10%																																
<p style="text-align: center;">DC SUPPLY</p> <p>Voltage tolerance continuous: <math>\pm 10\%</math>  Voltage cyclic variation: 5%  Voltage ripple: 10%</p> <p>Electric battery supply:</p> <ul style="list-style-type: none"> <li>+30% to -25% for equipment connected to charging battery or as determined by the charging/discharging characteristics, including ripple voltage from the charging device;</li> <li>+20% to -25% for equipment not connected to the battery during charging</li> </ul>																																		
	b) Pneumatic and hydraulic		<p>Pressure: <math>\pm 20\%</math>  Duration: 15 minutes</p>																															
5	Dry heat	IEC Publication 60068-2-2	<ul style="list-style-type: none"> <li>Temperature: <math>55^{\circ}\text{C} \pm 2^{\circ}\text{C}</math> Duration: 16 hours, or</li> <li>Temperature: <math>70^{\circ}\text{C} \pm 2^{\circ}\text{C}</math> Duration: 2 hours (see (2))</li> </ul>	<ul style="list-style-type: none"> <li>equipment operating during conditioning and testing</li> <li>functional test during the last hour at the test temperature</li> </ul>																														

No.	Test	Procedure (1)	Test parameters	Other information
6	Damp heat	IEC Publication 60068-2-30 Test D <sub>b</sub>	Temperature: 55°C Humidity: 95% Duration: 2 cycles 2 x (12 + 12 hours)	<ul style="list-style-type: none"> <li>• measurement of insulation resistance before test</li> <li>• equipment operating during the complete first cycle and switched off during second cycle except for functional test</li> <li>• functional test during the first 2 hours of the first cycle at the test temperature and during the last 2 hours of the second cycle at the test temperature</li> <li>• recovery at standard atmosphere conditions</li> <li>• insulation resistance measurements and performance test</li> </ul>
7	Vibration	IEC Publication 60068-2-6 Test F <sub>c</sub>	<ul style="list-style-type: none"> <li>• 2 Hz ± 3/0 Hz to 13,2 Hz – amplitude: ± 1mm</li> <li>• 13,2 Hz to 100 Hz – acceleration: ± 0,7 g</li> </ul> For severe vibration conditions such as, e. g., on diesel engines, air compressors, etc.: <ul style="list-style-type: none"> <li>• 2,0 Hz to 25 Hz – amplitude: ± 1,6 mm</li> <li>• 25 Hz to 100 Hz – acceleration: ± 4,0 g</li> </ul> Note: More severe conditions may exist for example on exhaust manifolds of diesel engines especially for medium and high speed engines. Values may be required to be in these cases 40 Hz to 2000 Hz - acceleration: ± 10,0 g at 600°C, duration 90 min.	<ul style="list-style-type: none"> <li>• duration in case of no resonance condition 90 minutes at 30 Hz;</li> <li>• duration at each resonance frequency at which <math>Q \geq 2</math> is recorded - 90 minutes;</li> <li>• during the vibration test, functional tests are to be carried out;</li> <li>• tests to be carried out in three mutually perpendicular planes;</li> <li>• it is recommended as a guidance that Q does not exceed 5.</li> <li>• where sweep test is to be carried out instead of the discrete frequency test and a number of resonant frequencies are detected close to each other, duration of the test is to be 120 min. Sweep over a restricted frequency range between 0,8 and 1,2 times the critical frequencies can be used where appropriate. Note: Critical frequency is a frequency at which the equipment being tested may exhibit:               <ul style="list-style-type: none"> <li>• malfunction and/or performance deterioration</li> <li>• mechanical resonances and/or other response effects occur, e.g. chatter</li> </ul> </li> </ul>



No.	Test	Procedure (1)	Test parameters	Other information														
8	Inclination	IEC Publication 60092-504	Static 22,5°  Dynamic 22,5°	<p>a) inclined to the vertical at an angle of at least 22,5°</p> <p>b) inclined to at least 22,5° on the other side of the vertical and in the same plane as in (a)</p> <p>c) inclined to the vertical at an angle of at least 22,5° in plane at right angles to that used in (a)</p> <p>d) inclined to at least 22,5° on the other side of the vertical and in the same plane as in (c).</p> <p>Note: The period of testing in each position should be sufficient to fully evaluate the behaviour of the equipment.</p> <p>Using the directions defined in a) to d) above, the equipment is to be rolled to an angle of 22,5° each side of the vertical with a period of 10 seconds.</p> <p>The test in each direction is to be carried out for not less than 15 minutes.</p> <p>On ships for the carriage of liquified gases and chemicals, the emergency power supply is to remain operational with the ship flooded up to a maximum final athwart ship inclination of 30°.</p> <p>Note: These inclination tests are normally not required for equipment with no moving parts</p>														
9	Insulation resistance	<table border="0"> <tr> <td>Rated supply voltage <math>U_n(V)</math></td> <td>Test voltage <math>U_n(V)</math></td> </tr> <tr> <td><math>U_n \leq 65</math></td> <td><math>2 \times U_n</math></td> </tr> <tr> <td><math>U_n &gt; 65</math></td> <td>min. 24 500</td> </tr> </table>	Rated supply voltage $U_n(V)$	Test voltage $U_n(V)$	$U_n \leq 65$	$2 \times U_n$	$U_n > 65$	min. 24 500	<table border="0"> <tr> <td colspan="2">Minimum insulation resistance</td> </tr> <tr> <td>before test</td> <td>after test</td> </tr> <tr> <td>10 MΩ</td> <td>1,0 MΩ</td> </tr> <tr> <td>100 MΩ</td> <td>10 MΩ</td> </tr> </table>	Minimum insulation resistance		before test	after test	10 MΩ	1,0 MΩ	100 MΩ	10 MΩ	<p>For high voltage equipment, reference is made to Ch 2, Sec 13.</p> <ul style="list-style-type: none"> <li>insulation resistance test is to be carried out before and after: damp heat test, cold test and salt mist test, high voltage test;</li> <li>between all circuits and earth; and where appropriate</li> <li>between the phases.</li> </ul> <p>Note: Certain components e.g. for EMC protection may be required to be disconnected for this test.</p>
Rated supply voltage $U_n(V)$	Test voltage $U_n(V)$																	
$U_n \leq 65$	$2 \times U_n$																	
$U_n > 65$	min. 24 500																	
Minimum insulation resistance																		
before test	after test																	
10 MΩ	1,0 MΩ																	
100 MΩ	10 MΩ																	

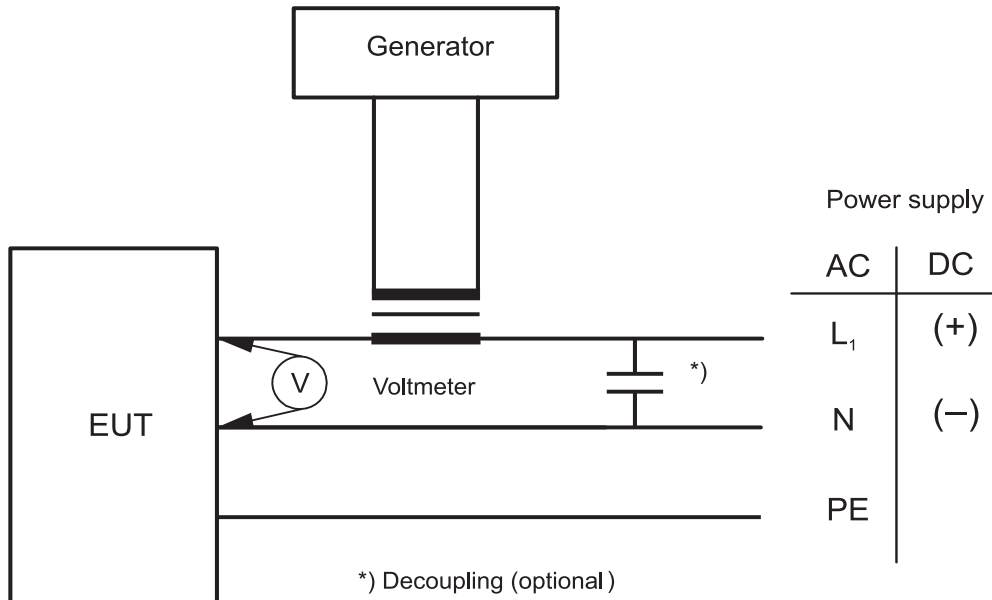
No.	Test	Procedure (1)	Test parameters	Other information
10	High voltage	Rated voltage $U_n$ (V)  Up to 65 66 to 250 251 to 500 501 to 690	Test voltage (V) (A.C. voltage 50 or 60Hz) $2 \times U_n + 500$ 1500 2000 2500	For high voltage equipment, reference is made to Ch 2, Sec 13. <ul style="list-style-type: none"> <li>• separate circuits are to be tested against each other and all circuits connected with each other tested against earth;</li> <li>• printed circuits with electronic components may be removed during the test;</li> <li>• period of application of the test voltage: 1 minute</li> </ul>
11	Cold	IEC Publication 60068-2-1	<ul style="list-style-type: none"> <li>• Temperature: <math>+5^\circ\text{C} \pm 3^\circ\text{C}</math> Duration: 2 hours, or</li> <li>• Temperature: <math>-25^\circ\text{C} \pm 3^\circ\text{C}</math> or at the expected minimum temperature Duration: 2 hours (see (3))</li> </ul>	<ul style="list-style-type: none"> <li>• initial measurement of insulation resistance;</li> <li>• equipment not operating during conditioning and testing except for operational test;</li> <li>• operational test during the last hour at the test temperature;</li> <li>• insulation resistance measurement and the operational test after recovery</li> </ul>
12	Salt mist	IEC Publication 60068-2-52 Test Kb	Four spraying periods with a storage of seven days after each.	<ul style="list-style-type: none"> <li>• initial measurement of insulation resistance and initial functional test</li> <li>• equipment not operating during conditioning</li> <li>• functional test on the 7th day of each storage period</li> <li>• insulation resistance measurement and performance test 4 to 6h after recovery (see (4))</li> </ul>
13	Electrostatic discharge	IEC Publication 61000-4-2	Contact discharge: 6 kV Air discharge: 8 kV Interval between single discharges: 1 s. No. of pulses: 10 per polarity According to level 3 severity standard	<ul style="list-style-type: none"> <li>• to simulate electrostatic discharge as may occur when persons touch the appliance</li> <li>• the test is to be confined to the points and surfaces that can normally be reached by the operator</li> <li>• performance Criterion B (see (5))</li> </ul>
14	Electromagnetic field	IEC Publication 61000-4-3	Frequency range: 80 MHz - 2 GHz Modulation**: 80% AM at 1000Hz Field strength: 10V/m Frequency sweep rate: $\leq 1,5 \cdot 10^{-3}$ decades/s (or 1% / 3 s) According to level 3 severity standard	<ul style="list-style-type: none"> <li>• to simulate electromagnetic fields radiated by different transmitters</li> <li>• the test is to be confined to the appliances exposed to direct radiation by transmitters at their place of installation</li> <li>• performance criterion A (see (6)).</li> </ul> <p>** If, for tests of equipment, an input signal with a modulation frequency of 1000 Hz is necessary, a modulation frequency of 400 Hz may be chosen</p>

No.	Test	Procedure (1)	Test parameters	Other information
15	Conducted low frequency		<p>A.C.:</p> <ul style="list-style-type: none"> <li>Frequency range: rated frequency to 200th harmonic</li> <li>Test voltage (rms): 10% of supply to 15th harmonic reducing to 1% at 100th harmonic and maintain this level to the 200th harmonic, min 3 V rms Max 2 W</li> </ul> <p>D.C.:</p> <ul style="list-style-type: none"> <li>Frequency range: 50 Hz - 10 kHz</li> <li>Test voltage (rms) :10% of supply max. 2 W</li> </ul>	<ul style="list-style-type: none"> <li>to simulate distortions in the power supply system generated for instance, by electronic consumers and coupled in as harmonics</li> <li>performance criterion A (see (6))</li> <li>See Figure in Notes in this Table</li> </ul>
16	Conducted Radio Frequency	IEC Publication 61000-4-6	<p>AC, DC, I/O ports and signal/control lines:</p> <p>Frequency range: 150 kHz - 80 MHz Amplitude: 3 V rms (see (7)) Modulation***: 80% AM at 1000 Hz Frequency sweep range: ≤1,5.10<sup>-3</sup> decades/s (or 1% / 3sec.) According to level 2 severity standard</p>	<ul style="list-style-type: none"> <li>Equipment design and the choice of materials is to simulate electromagnetic fields coupled as high frequency into the test specimen via the connecting lines</li> <li>performance criterion A (see (6)).</li> </ul> <p>*** If, for tests of equipment, an input signal with a modulation frequency of 1000 Hz is necessary, a modulation frequency of 400 Hz may be chosen</p>
17	Burst/ Fast Transients	IEC Publication 61000-4-4	<p>Single pulse time: 5ns (between 10% and 90% value) Single pulse width: 50 ns (50% value) Amplitude (peak): 2 kV line on power supply port/earth; 1 kV on I/O data control and communication ports (coupling clamp) Pulse period: 300 ms Burst duration: 15 ms Duration/polarity: 5 min According to level 3 severity standard</p>	<ul style="list-style-type: none"> <li>arcs generated when actuating electrical contacts</li> <li>interface effect occurring on the power supply, as well as at the external wiring of the test specimen</li> <li>performance criterion B (see (5))</li> </ul>
18	Surge /voltage	IEC Publication 61000-4-5	<p>Pulse rise time: 1,2 μs (between 10% and 90% value) Pulse width: 50 μs (50% value) Amplitude (peak) : 1 kV line/earth; 0,5 kV line/line Repetition rate: ≥ 1 pulse/min No of pulses: 5 per polarity Application: continuous According to level 2 severity standard</p>	<ul style="list-style-type: none"> <li>interference generated for instance, by switching "ON" or "OFF" high power inductive consumers</li> <li>test procedure in accordance with figure 10 of the standard for equipment where power and signal lines are identical</li> <li>performance criterion B (see (5))</li> </ul>

No.	Test	Procedure (1)	Test parameters	Other information																								
19	Radiated Emission	CISPR 16-1, 16-2	<p>For equipment installed in the bridge and deck zone:</p> <table> <thead> <tr> <th>Frequency range (MHz):</th> <th>Limits: (dB<math>\mu</math>V/m)</th> </tr> </thead> <tbody> <tr> <td>0,15 - 0,30</td> <td>80 - 52</td> </tr> <tr> <td>0,30 - 30</td> <td>50 - 34</td> </tr> <tr> <td>30 - 2000</td> <td>54</td> </tr> <tr> <td>except for:</td> <td></td> </tr> <tr> <td>156 - 165</td> <td>24</td> </tr> </tbody> </table> <p>For equipment installed in the general power distribution zone:</p> <table> <thead> <tr> <th>Frequency range: (MHz)</th> <th>Limits: (dB<math>\mu</math>V/m)</th> </tr> </thead> <tbody> <tr> <td>0,15 - 30</td> <td>80 - 50</td> </tr> <tr> <td>30 - 100</td> <td>60 - 54</td> </tr> <tr> <td>100 - 2000</td> <td>54</td> </tr> <tr> <td>except for:</td> <td></td> </tr> <tr> <td>156 - 165</td> <td>24</td> </tr> </tbody> </table>	Frequency range (MHz):	Limits: (dB $\mu$ V/m)	0,15 - 0,30	80 - 52	0,30 - 30	50 - 34	30 - 2000	54	except for:		156 - 165	24	Frequency range: (MHz)	Limits: (dB $\mu$ V/m)	0,15 - 30	80 - 50	30 - 100	60 - 54	100 - 2000	54	except for:		156 - 165	24	<ul style="list-style-type: none"> <li>procedure in accordance with the standard but distance 3 m between equipment and antenna</li> </ul>
Frequency range (MHz):	Limits: (dB $\mu$ V/m)																											
0,15 - 0,30	80 - 52																											
0,30 - 30	50 - 34																											
30 - 2000	54																											
except for:																												
156 - 165	24																											
Frequency range: (MHz)	Limits: (dB $\mu$ V/m)																											
0,15 - 30	80 - 50																											
30 - 100	60 - 54																											
100 - 2000	54																											
except for:																												
156 - 165	24																											
20	Conducted Emission	CISPR 16-1, 16-2	<p>For equipment installed in the bridge and deck zone:</p> <table> <thead> <tr> <th>Frequency range:</th> <th>Limits: (dB<math>\mu</math>V)</th> </tr> </thead> <tbody> <tr> <td>10 - 150 kHz</td> <td>96 - 50</td> </tr> <tr> <td>150 - 350 kHz</td> <td>60 - 50</td> </tr> <tr> <td>0,35 - 30 MHz</td> <td>50</td> </tr> </tbody> </table> <p>For equipment installed in the general power distribution zone:</p> <table> <thead> <tr> <th>Frequency range:</th> <th>Limits: (dB<math>\mu</math>V)</th> </tr> </thead> <tbody> <tr> <td>10 - 150 kHz</td> <td>120 - 69</td> </tr> <tr> <td>150 - 500 kHz</td> <td>79</td> </tr> <tr> <td>0,5 - 30 MHz</td> <td>73</td> </tr> </tbody> </table>	Frequency range:	Limits: (dB $\mu$ V)	10 - 150 kHz	96 - 50	150 - 350 kHz	60 - 50	0,35 - 30 MHz	50	Frequency range:	Limits: (dB $\mu$ V)	10 - 150 kHz	120 - 69	150 - 500 kHz	79	0,5 - 30 MHz	73									
Frequency range:	Limits: (dB $\mu$ V)																											
10 - 150 kHz	96 - 50																											
150 - 350 kHz	60 - 50																											
0,35 - 30 MHz	50																											
Frequency range:	Limits: (dB $\mu$ V)																											
10 - 150 kHz	120 - 69																											
150 - 500 kHz	79																											
0,5 - 30 MHz	73																											

No.	Test	Procedure (1)	Test parameters	Other information
21	Flame retardant	IEC Publication 60092-101 or IEC Publication 60695-11-5	Flame application: 5 times 15 s each Interval between each application: 15 s or one time 30 s. Test criteria based upon application. The test is performed with the EUT or housing of the EUT applying needle-flame test method.	<ul style="list-style-type: none"> <li>the burnt out or damaged part of the specimen by not more than 60mm long</li> <li>no flame, no incandescence or in the event of a flame or incandescence being present, it is to extinguish itself within 30 s of the removal of the needle flame without full combustion of the test specimen</li> <li>any dripping material is to extinguish itself in such a way as not to ignite a wrapping tissue. The drip height is 200 mm ± 5 mm.</li> </ul>

- (1) Column 3 indicates the testing procedure which is normally to be applied. However, equivalent testing procedure may be accepted by the Society provided that what required in the other columns is fulfilled.
- (2) Equipment to be mounted in consoles, housing etc. together with other equipment are to be tested with 70°C.
- (3) For equipment installed in non-weather protected locations or cold locations test is to be carried out at -25°C or at the expected minimum temperature.
- (4) Salt mist test is to be carried out for equipment installed in weather exposed areas.
- (5) Performance Criterion B: (for transient phenomena): the EUT is to continue to operate as intended after the tests. No degradation of performance or loss of function is allowed as defined in the technical specification published by the Manufacturer. During the test, degradation or loss of function or performance which is self recoverable is however allowed but no change of actual operating state or stored data is allowed.
- (6) Performance Criterion A (for continuous phenomena): the Equipment Under Test is to continue to operate as intended during and after the test. No degradation of performance or loss is allowed as defined in relevant equipment standard and the technical specification published by the Manufacturer.
- (7) For equipment installed on the bridge and deck zone, the test levels are to be increased to 10V rms for spot frequencies in accordance with IEC 60945 at 2; 3; 4; 6.2; 8.2; 12.6; 16.5; 18.8; 22; 25 MHz.



## 2.3 Software type approval

**2.3.1** Software type approval consists of evaluation of the development quality and verification of test results.

Documents in accordance with Sec 1, Tab 2 are required to demonstrate the development quality.

Repetition of unit tests, integration tests or validation tests is required to verify the consistency of test results.

Certificate may be issued at the request of the manufacturer when approval is granted.

**2.3.2** For programmable electronic systems, as a guidance, the documents to be submitted for information are listed in Tab 2:

**2.3.3** The software type approval applies only to basic software of the programmable electronic system.

The basic software approval is carried out in the following phases:

- Examination of the documents as required in Sec 1, [2.3.2],
- Verification that all the development work has been carried out according to the quality procedure. The complementary documents required in Tab 2 prove the quality of the development work.

Note 1: Particular attention will be given to the test results collected on unit testing file, integration test file and validation test file

- Repetition of tests of the essential function of the software. Comparison with documentation containing the test results of previous tests is to be carried out.

**2.3.4** The application software is to be approved on a case by case basis, according to [3.3.2].

## 2.4 Navigational and radio equipment

**2.4.1** The test conditions as specified in IEC 60945 (marine navigational and radiocommunication equipment and systems - general requirements, methods of testing and required test results) are to be applied for the above-mentioned equipment.

## 2.5 Loading instruments

**2.5.1** Loading instrument approval consists of:

- approval of hardware according to [2.2], unless two computers are available on board for loading calculations only
- approval of basic software according to [2.3]
- approval of application software, consisting in data verification which results in the Endorsed Test Condition according to Part B
- installation testing according to [4].

**Table 2 : Basic software development documents**

No.	I/A (2)	DOCUMENT
1	I	Follow-up of developed software: identification, safeguard, storage
2	I	Document showing the capability and training of the development team
3	I	Production of a specification file
4	I	Production of a preliminary design file
5	I	Production of a detailed design file
6	I	Production of a coding file
7	I	Production of a unit testing file <b>(1)</b>
8	I	Production of an integration test file <b>(1)</b>
9	I	Production of a validation test file <b>(1)</b>
10	I	Production of a maintenance facility file
11	I	Production of a quality plan
12	I	Follow-up of the quality plan: checks, audits, inspections, reviews
<b>(1)</b> Complementary test carried out, at random, at the request of the Surveyor <b>(2)</b> A : to be submitted for approval; I : to be submitted for information.		

## 3 Acceptance testing

### 3.1 General

**3.1.1** Acceptance tests are generally to be carried out at the manufacturer's facilities before the shipment of the equipment.

Acceptance tests refer to hardware and software tests as applicable.

### 3.2 Hardware testing

**3.2.1** Hardware acceptance tests include, where applicable:

- visual inspection
- operational tests and, in particular:
  - tests of all alarm and safety functions
  - verification of the required performance (range, calibration, repeatability, etc.) for analogue sensors
  - verification of the required performance (range, set points, etc.) for on/off sensors
  - verification of the required performance (range, response time, etc.) for actuators
  - verification of the required performance (full scale, etc.) for indicating instruments
- high voltage test
- hydrostatic tests.

Additional tests may be required by the Society.

**3.2.2** Final acceptance will be granted subject to:

- the results of the tests listed in [3.2.1]
- the type test report or type approval certificate.

### 3.3 Software testing

**3.3.1** Software acceptance tests of programmable electronic systems are to be carried out to verify their adaptation to their use on board, and concern mainly the application software.

**3.3.2** The software modules of the application software are to be tested individually and subsequently subjected to an integration test. The test results are to be documented and to be part of the final file. It is to be checked that:

- the development work has been carried out in accordance with the plan
- the documentation includes the proposed tests, the acceptance criteria and the result.

Repetition tests may be required to verify the consistency of test results.

**3.3.3** Software acceptance will be granted subject to:

- examination of the available documentation
- a functional test of the whole system.

The Society may ask for additional tests of systems which are part of safety systems or which integrate several functions.

## 4 Commissioning

### 4.1 General

**4.1.1** Commissioning tests are to be carried out on automation systems associated with essential services to verify their compliance with the Rules, by means of visual inspection and the performance and functionality according to Tab 3.

When completed, automation systems are to be such that a single failure, for example loss of power supply, is not to result in a major degradation of the propulsion or steering of the ship. In addition, a blackout test is to be carried out to show that automation systems are continuously supplied.

Upon completion of commissioning tests, test reports are to be made available to the Surveyor.

**Table 3 : Commissioning tests**

Equipment	Nature of tests
Electronic equipment	Main hardware functionality
Analogue sensors	Signal calibration, trip set point adjustment
On/off sensors	Simulation of parameter to verify and record the set points
Actuators	Checking of operation in whole range and performance (response time, pumping)
Reading instruments	Checking of calibration, full scale and standard reference value

Part C  
**Machinery, Systems and Fire Protection**

Chapter 4

**FIRE PROTECTION AND SAFETY SYSTEMS**

---

- SECTION 1      FIRE PROTECTION, DETECTION AND EXTINCTION**
- SECTION 2      EMERGENCY SHUTDOWN SYSTEMS**
- SECTION 3      GAS ALARM AND DETECTION SYSTEMS**





# SECTION 1 FIRE PROTECTION, DETECTION AND EXTINCTION

## 1 General

### 1.1 Purpose and application

**1.1.1** This Section applies to offshore units operating in the Caspian Sea and similar areas for which classification is requested.

Note 1: As from 1 January 2007, the statutory requirements of the SOLAS Convention and/or national safety regulations, as applicable, regarding fire protection, detection and extinction (hereinafter referred to as "fire protection statutory requirements") are no longer mandatory for the purpose of classification except where the Society carries out surveys relevant to fire protection statutory requirements on behalf of the flag Administration. In such cases, fire protection statutory requirements are considered a matter of class and therefore compliance with these requirements is also verified by the Society for classification purposes.

In general, only IACS Unified Requirements in force related to fire protection, detection and extinction have been retained as Rule

requirements within the scope of classification and are contained in this Chapter 4.

**1.1.2** Requirements for tankers in this Section apply to tankers carrying oil having a flashpoint not exceeding 60°C (closed cup test).

**1.1.3** Unless otherwise stated, for materials and design criteria of piping and relevant accessories reference is to be made to Ch 1, Sec 8.

## 2 Documentation to be submitted

### 2.1

**2.1.1** The Interested Party is to submit to the Society the documents listed in Tab 1.

**Table 1 : Documentation to be submitted**

No.	I/A (1)	Document (2)
1	A	Ventilation systems in cargo area of tankers, excluding cargo tanks
2	A	Automatic fire detection systems in unattended machinery spaces
3	A	Arrangement of low pressure CO <sub>2</sub> and local application fixed fire-extinguishing systems (2) and inert gas systems
4	A	Gas detection systems
5	A	Fixed fire-extinguishing system in scavenge spaces of two-stroke crosshead type engines, according to the requirements of Ch 1, Sec 2, [2.4.1]
6	A	Electrical diagram of low pressure CO <sub>2</sub> and local application fixed gas fire-extinguishing systems
7	I	General arrangement plan

(1) A : to be submitted for approval, in four copies I : to be submitted for information, in duplicate.  
(2) Plans are to be schematic and functional and to contain all information necessary for their correct interpretation and verification such as:

- service pressures
- capacity and head of pumps and compressors, if any
- materials and dimensions of piping and associated fittings
- volumes of protected spaces
- surface areas of protected zones for pressure water-spraying systems
- type, number and location of nozzles of extinguishing media for gas and pressure water-spraying systems.

All or part of the information may be provided, instead of on the above plans, in suitable operation manuals or in specifications of the systems.

### 3 Definitions

#### 3.1 Accommodation spaces

**3.1.1** Accommodation spaces are those spaces used for public spaces, corridors, stairs, lavatories, cabins, offices, hospitals, cinemas, games and hobby rooms, barber shops, pantries containing no cooking appliances and similar spaces.

#### 3.2 Cargo area

**3.2.1** The cargo area is that part of the ship that contains cargo holds, cargo tanks, slop tanks and cargo pump rooms including pump rooms, cofferdams, ballast and void spaces adjacent to cargo tanks and also deck areas throughout the entire length and breadth of the part of the ship over the above-mentioned spaces.

#### 3.3 Cargo spaces

**3.3.1** Cargo spaces are spaces used for cargo, cargo oil tanks, tanks for other liquid cargo and trunks to such spaces.

#### 3.4 Continuously manned central control stations

**3.4.1** A continuously manned central control station is a central control station which is continuously manned by a responsible member of the crew.

#### 3.5 Control stations

**3.5.1** Control stations are those spaces in which the ship's radio or main navigating equipment or the emergency source of power is located or where the fire recording or fire control equipment is centralized.

#### 3.6 Crude oil

**3.6.1** Crude oil is any oil occurring naturally in the earth whether or not treated to render it suitable for transportation and includes crude oil where certain distillate fractions may have been removed from, or added to.

#### 3.7 Deadweight

**3.7.1** The deadweight is the difference in tonnes between the displacement of a ship in water of a specific gravity of 1,025 t/m<sup>3</sup> at the load waterline corresponding to the assigned summer freeboard and the lightweight of the ship.

#### 3.8 Flashpoint

**3.8.1** Flashpoint is the temperature in degrees Celsius (closed cup test) at which a product will give off enough flammable vapour to be ignited, as determined by an approved flashpoint apparatus.

#### 3.9 Lightweight

**3.9.1** The lightweight is the displacement of a ship in tonnes without cargo, fuel, lubricating oil, ballast water, fresh water and feed water in tanks, consumable stores, and passengers and crew and their effects.

#### 3.10 Machinery spaces

**3.10.1** Machinery spaces are machinery spaces of category A and other spaces containing propulsion machinery, boilers, fuel oil units, steam and internal combustion engines, generators and major electrical machinery, oil filling stations, refrigerating, stabilizing, ventilation and air conditioning machinery, and similar spaces, and trunks to such spaces.

#### 3.11 Machinery spaces of category A

**3.11.1** Machinery spaces of category A are those spaces and trunks to such spaces which contain either:

- internal combustion machinery used for main propulsion,
- internal combustion machinery used for purposes other than main propulsion where such machinery has in the aggregate a total power output of not less than 375 kW, or
- any oil-fired boiler or oil fuel unit, or any oil-fired equipment other than boilers, such as inert gas generators, incinerators, etc.

#### 3.12 Oil fuel unit

**3.12.1** The oil fuel unit is the equipment used for the preparation of oil fuel for delivery to an oil fired boiler or equipment used for the preparation for delivery of heated oil to an internal combustion engine and includes any oil pressure pumps, filters and heaters dealing with oil at a pressure of more than 0,18 MPa.

**3.12.2** "Oil fuel unit" includes any equipment used for the preparation and delivery of oil fuel, whether or not heated, to boilers (including inert gas generators) and engines (including gas turbines) at a pressure of more than 0,18 MPa.

Note 1: For the purpose of these Rules "oil fuel" has the same meaning of "fuel oil".

#### 3.13 Public spaces

**3.13.1** Public spaces are those portions of the accommodation which are used for halls, dining rooms, lounges and similar permanently enclosed spaces.

#### 3.14 Service spaces

**3.14.1** Service spaces are those spaces used for galleys, pantries containing cooking appliances, lockers, mail and specie rooms, storerooms, workshops other than those forming part of the machinery spaces, and similar spaces and trunks to such spaces.

### 3.15 Special category spaces

**3.15.1** Special category spaces are those enclosed vehicle spaces above and below the bulkhead deck, into and from which vehicles can be driven and to which passengers have access. Special category spaces may be accommodated on more than one deck provided that the total overall clear height for vehicles does not exceed 10 m.

### 3.16 Tanker

**3.16.1** A tanker is a cargo ship constructed or adapted for the carriage in bulk of liquid cargoes of an inflammable nature.

Note 1: For the purpose of this Chapter, the term tanker includes the following service notations (see Pt A, Ch 1, Sec 2, Tab 1):

- Flammable liquid substances tanker
- Oil tanker.

### 3.17 Weather decks

**3.17.1** A weather deck is a deck which is completely exposed to the weather from above and from at least two sides.

## 4 Type approved products

### 4.1

**4.1.1** The following materials, equipment, systems or products in general used for fire protection are to be type approved by the Society, except for special cases for which acceptance may be given for individual ships on the basis of suitable documentation or ad hoc tests:

- a) Flexible pipes and expansion bellows of non-conventional material for any type of fluid
- b) Nozzles for fixed pressure water-spraying fire-extinguishing systems for machinery spaces and boiler rooms
- c) Sensing heads for automatic fire alarm and fire detection systems.
- d) Fixed fire detection and fire alarm systems
- e) Explosive mixture detecting systems
- f) Portable explosive mixture detecting apparatus
- g) Fixed instruments for measuring the oxygen content for inert gas systems serving cargo tanks
- h) Portable instruments for measuring the oxygen content for inert gas systems serving cargo tanks.

## 5 Probability of ignition

### 5.1 Arrangements for gaseous fuel for domestic purposes

**5.1.1** In case of use of movable cooking appliances - the so-called "flambé carts" - they are to meet the following requirements:

- a) Constructional requirements:

- 1) In addition to the main gas supply valve, the flambé carts are equipped with an emergency gas shut-off valve which can be activated:
  - manually by the operator, either by pulling on a metallic wire loop or using a rod pull type lever;
  - automatically with a mechanical (in general gravity type) tip over device which will shut off the gas flow from the gas cylinder should the cart accidentally tip over.
- 2) The regulation system ensures a pressure of about 0,0001 MPa downstream from the regulator itself.
- 3) A pressure gauge is fitted between the gas cylinder and the regulation system, to indicate the gas pressure inside the cylinder.
- 4) Special materials are used for the low pressure hose (between the regulation system and the stove) so that, in case of fire, the hose melts and closes on itself acting as an automatic check valve.
- 5) The gas cylinder is safely secured on its cradle inside the cart.
- 6) A safely re-ignition system is provided to automatically relight the burner if the flame goes out when the gas valve is "on".
- 7) At least two of the four swivel castors are equipped with brakes, to block the cart in position.

- b) Operational requirements.

Flambé carts complying with the constructional requirements listed under item a) above may be used in public spaces (restaurant, buffet, etc.) on passenger ships under the following conditions, the implementation of which is the Owner's responsibility:

- 1) The carts are safely secured, specially when they are left unmanned in the space where they are used.
- 2) The number of carts permitted in a public space is such that the free volume at ambient temperature and atmospheric pressure of the natural gas contained in the cylinders of all the carts is less than 2% of the gross volume of the public space.
- 3) No spare full gas cylinders are permitted on board. Empty bottles are replaced only when the ship is in the harbour.

### 5.2 Cargo area of tankers

#### 5.2.1 Restriction on boundary openings

- a) Where driven shafts pass through pump room bulkhead or deck plating, gas-tight glands are to be fitted. The glands are to be efficiently lubricated from outside the pump room. The seal parts of the glands are to be of material that will not initiate sparks. The glands are to be constructed and fitted in accordance with the relevant Rules for fittings attached to watertight bulkheads and, if a bellows piece is incorporated in the design, it is to be pressure tested before fitting.
- b) Where the pump room is illuminated through glazed ports, these are to be effectively protected from mechanical damage and are to have strong covers secured from the side of the same space.

Glazed ports are to be so constructed that glass and sealing will not be impaired by the working of the ship. The glass and the protection of the light fitting are not to impair the integrity of the bulkhead and are to be of equivalent strength.

The fitting is to have the same resistance to fire and smoke as the unpierced bulkhead.

### 5.2.2 Ventilation systems in cargo pump rooms

Discharges and air inlets are to be located at a vertical distance of at least 2,4 m from the open deck. Air discharges are also to be arranged at a horizontal distance of not less than 3 m from any other opening leading to the served spaces.

The ventilation system capable of providing the required air changes per hour is to comply with the following as applicable:

- a) in order to avoid air stagnation zones, air exhaust ports inside the pump room are to be adequately distributed and the various landings are to consist of open gratings or perforated flats;
- b) inlet ducts are generally to end at the top of the room and outlet ducts are to extend below the floor plates, with suction ports at the level of the upper edge of ordinary floors or bottom longitudinals;
- c) in addition, suction ducts are to be provided with an emergency intake at approximately 2 m above the pump room lower grating, with a shutter capable of being opened or closed both at lower grating level and from the weather deck level, so that suction normally occurs through the lower suction ports and, in the event of the pump room flooding, through those at the top branched from the emergency intake;
- d) an arrangement involving a specific ratio of areas of upper emergency and lower main ventilator openings, which can be shown to result in at least the required 20 air changes per hour through the lower inlets, can be adopted without the use of shutters.

When the lower access inlets are closed then at least 15 air changes per hour are to be obtained through the upper inlets.

### 5.2.3 Ventilation systems in spaces other than the cargo pump room

Hose lockers and enclosed or partially enclosed spaces adjacent to cargo tanks are to be independently ventilated, in general by mechanical ventilation (exhaust) where such spaces are normally attended by the crew. In general, the arrangement of inlets and outlets serving these spaces is to comply with the provisions set out in [5.2.2] a).

### 5.2.4 Gas measurements

- a) Portable instruments

Every oil tanker is to be provided with at least two portable gas detectors capable of measuring flammable vapour concentrations in air and at least two portable O<sub>2</sub> analysers. In addition, for tankers fitted with inert gas systems, at least two portable gas detectors are to be capable of measuring concentrations of flammable vapours in inerted atmosphere.

- b) Arrangement for gas measurement in double hull and double bottom spaces.

Gas analysing units with non-explosion proof measuring equipment associated to the fixed gas sampling line system may be located in areas outside cargo areas, e.g. in the cargo control room, navigation bridge or engine room, when mounted on the forward bulkhead facing the cargo area provided the following requirements are observed:

- sampling lines are not to run through gas-safe spaces, except where permitted under the last bullet below;
- the gas sampling pipes are to be equipped with flame arresters. Sample gas is to be led to the atmosphere with outlets arranged in a safe location;
- bulkhead penetrations of sample pipes between safe and dangerous areas are to be approved by the Society and to have the same fire integrity as the division penetrated. A manual isolating valve is to be fitted in each of the sampling lines at the bulkhead on the gas-safe side;
- the gas detection equipment, including sample piping, sample pumps, solenoids, analysing units etc., is to be located in a reasonably gas-tight enclosure (e.g. a fully enclosed steel cabinet with a gasketed door), which is to be monitored by its own sampling point. At gas concentration above 30% of the lower flammable limit (LFL) inside the enclosure, the entire gas analysing unit is to be automatically shut down; and
- where the enclosure cannot be arranged directly on the bulkhead facing the cargo area, sample pipes are to be of steel or other equivalent material and without detachable connections, except for the connection points for isolating valves at the bulkhead and analysing units, and are to be routed along the shortest path.

### 5.2.5 Safety aspects of double hull spaces, double bottoms and duct keels under cargo oil tanks

Pipe ducts in the double bottom are to comply with the following requirements:

- a) In general, they are not to communicate with the engine room. When access is provided from a pump room, a watertight door is to be fitted complying with the requirements of Pt B, Ch 2, Sec 1, [6.2.1] and, in addition, with the following:
  - 1) in addition to operation from the bridge, the watertight door is to be capable of being manually closed from outside the main pump room entrance; and
  - 2) the watertight door is to be kept closed during normal operation of the ship except when access to the pipe tunnel is required.
- b) For double bottoms and ducts keels, provision is to be made for at least two exits to the open deck arranged as far apart from each other as practicable. One of these exits fitted with a watertight closure may lead to the cargo pump room;
- c) In the duct, provision is to be made for adequate mechanical ventilation.

## 5.3 Non-sparking fans

### 5.3.1 General

Where non-sparking fans are required by the Rules, the provisions of [5.3.2] and [5.3.3] are also to be complied with.

### 5.3.2 Design criteria

- a) The air gap between the impeller and the casing is to be not less than 0,1 of the shaft diameter in way of the impeller bearing and in any case not less than 2 mm, but need not exceed 13 mm.
- b) Protective screens with square mesh of not more than 13 mm are to be fitted to the inlet and outlet of ventilation openings on the open deck to prevent objects entering the fan housing.

### 5.3.3 Materials

- a) Except as indicated in the fourth bullet of item c) below, the impeller and the housing in way of the impeller are to be made of spark-proof materials which are recognised as such by means of an appropriate test to the satisfaction of the Society.
- b) Electrostatic charges, both in the rotating body and the casing, are to be prevented by the use of antistatic materials. Furthermore, the installation on board of ventilation units is to be such as to ensure their safe bonding to the hull.
- c) Tests may not be required for fans having the following material combinations:
  - impellers and/or housings of non-metallic material, due regard being paid to the elimination of static electricity
  - impellers and housings of non-ferrous materials
  - impellers of aluminium alloys or magnesium alloys and a ferrous (including austenitic stainless steel) housing on which a ring of suitable thickness of non-ferrous material is fitted in way of the impeller
  - any combination of ferrous (including austenitic stainless steel) impellers and housings with not less than 13 mm design tip clearance.
- d) The following impeller and housing combinations are considered as sparking and therefore are not permitted:
  - impellers of an aluminium alloy or a magnesium alloy and a ferrous housing, regardless of tip clearance
  - housings made of an aluminium alloy or a magnesium alloy and a ferrous impeller, regardless of tip clearance
  - any combination of ferrous impeller and housing with less than 13 mm design tip clearance.
- e) Complete fans are to be tested in accordance either with the Society's requirements or national or international standards accepted by the Society.

## 6 Suppression of fire - detection and alarm

### 6.1 Protection of machinery spaces

#### 6.1.1 Installation

Fire detecting systems to be fitted in unattended machinery spaces are also to comply with the following:

- a) the system is to be designed with self-monitoring properties. Power or system failures are to initiate an audible alarm distinguishable from the fire alarm.
- b) The fire detection indicating panel is to be located on the navigating bridge, fire control station, or other accessible place where a fire in the machinery space will not render it inoperative.
- c) The fire detection indicating panel is to indicate the place of the detected fire in accordance with the arranged fire zones by means of a visual signal. Audible signals clearly distinguishable in character from any other audible signals are to be audible throughout the navigating bridge and the accommodation area of the personnel responsible for the operation of the machinery space.
- d) Fire detectors are to be of types, and so located, that they will rapidly detect the onset of fire in conditions normally present in the machinery space. Consideration is to be given to avoiding false alarms. The type and location of detectors are to be approved by the Society and a combination of detector types is recommended in order to enable the system to react to more than one type of fire symptom.
- e) Fire detector zones are to be arranged in a manner that will enable the operating staff to locate the seat of the fire. The arrangement and the number of loops and the location of detector heads are to be approved in each case. Air currents created by the machinery are not to render the detection system ineffective.
- f) When fire detectors are provided with the means to adjust their sensitivity, necessary arrangements are to be ensured to fix and identify the set point.
- g) When it is intended that a particular loop or detector is to be temporarily switched off, this state is to be clearly indicated. Reactivation of the loop or detector is to be performed automatically after a preset time.
- h) The fire detection indicating panel is to be provided with facilities for functional testing.
- i) The fire detecting system is to be fed automatically from the emergency source of power by a separate feeder if the main source of power fails.

- j) Facilities are to be provided in the fire detecting system to manually release the fire alarm from the following places:
- passageways having entrances to the engine and boiler rooms,
  - the navigating bridge and control station in the engine room.
- k) The testing of the fire detecting system on board is to be carried out to the satisfaction of the Society.

For the fire detecting system for unattended machinery spaces, see also Pt F, Ch 2, Sec 2.

## 7 Suppression of fire: fire - fighting

### 7.1 Fire-extinguishing arrangements in machinery spaces

#### 7.1.1 General

- a) Air pipes from oil fuel tanks are to be led to a safe position on the open deck. Air pipes from lubricating oil storage tanks may terminate in the machinery space, provided that the open ends are so situated that issuing oil cannot come into contact with electrical equipment or heated surfaces.

Any overflow pipe is to have a sectional area of at least 1,25 times that of the filling pipe and is to be led to an overflow tank of adequate capacity or to a storage tank having space reserved for overflow purposes.

An alarm device is to be provided to give warning when the oil reaches a predetermined level in the tank, or alternatively, a sight glass is to be provided in the overflow pipe to indicate when any tank is overflowing. Such sight glasses are to be placed on vertical pipes only and in readily visible positions.

- b) Short sounding pipes may be used for tanks other than double bottom tanks without the additional closed level gauge provided an overflow system is fitted.
- c) Level switches may be used below the tank top provided they are contained in a steel enclosure or other enclosures not capable of being destroyed by fire.
- d) Controls required by this regulation are to be also provided from the compartment itself.
- e) Hose clamps and similar types of attachments for flexible pipes are permitted.
- f) Oil fuel in storage tanks is not to be heated to temperatures within 10°C below the flashpoint of the oil fuel, except that where oil fuel in service tanks, settling tanks and any other tanks in the supply system is heated the following arrangements are to be provided:
- the length of the vent pipes from such tanks and/or a cooling device is sufficient for cooling the vapours

to below 60°C, or the outlet of the vent pipes is located 3 m away from a source of ignition;

- the vent pipes are fitted with flame screens;
- there are no openings from the vapour space of the fuel tanks into machinery spaces (bolted manholes are acceptable);
- enclosed spaces are not located directly over such fuel tanks, except for vented cofferdams;
- electrical equipment is not fitted in the vapour space of the tanks, unless it is certified to be intrinsically safe.

- g) In the proximity of any electrical switchboard or section board having a power of 20 kW and upwards at least one CO<sub>2</sub> or powder extinguisher is to be fitted.

#### 7.1.2 Fixed local application fire-fighting systems

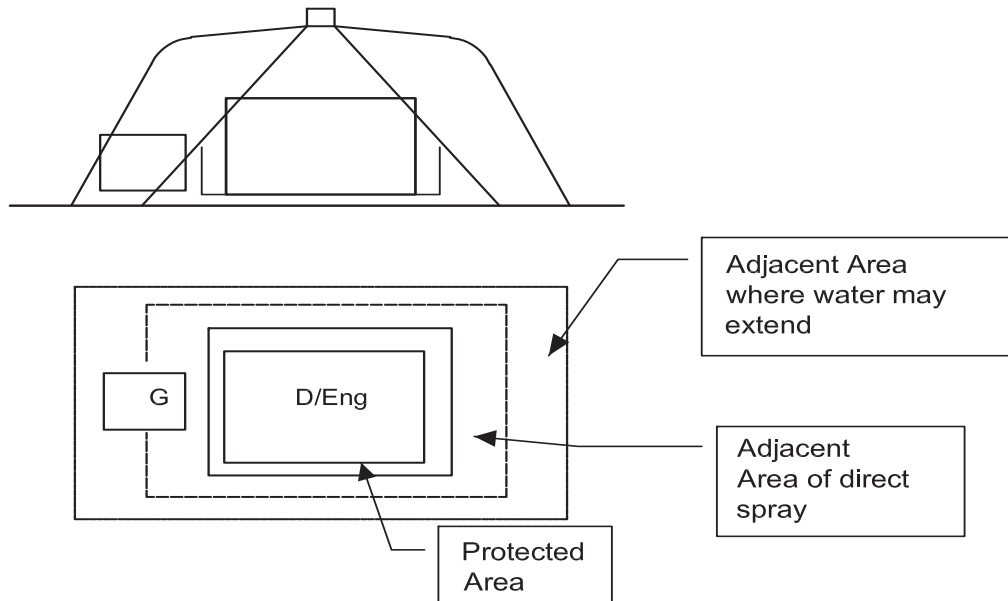
This item applies to the installation of electrical and electronic equipment in engine rooms protected by fixed water-based local application fire-fighting systems (FWBLAFFS).

- a) The following definitions apply (see also Fig 1):
- 1) Protected space: a machinery space where a FWBLAFFS is installed.
  - 2) Protected areas: areas within a protected space which are required to be protected by FWBLAFFS.
  - 3) Adjacent areas:
    - areas, other than protected areas, exposed to direct spray
    - areas, other than those defined above, where water may extend.
- b) The electrical and electronic equipment enclosures located within areas protected by FWBLAFFS and those within adjacent areas exposed to direct spray is to have a degree of protection not less than IP44, except where evidence of suitability is submitted to and approved by the Society.
- c) The electrical and electronic equipment within adjacent areas not exposed to direct spray may have a lower degree of protection provided evidence of suitability for use in these areas is submitted taking into account the design and equipment layout, e.g. position of inlet ventilation openings, and that cooling airflow for the equipment is assured.

Note 1: Additional precautions may be required to be taken in respect of:

- a) tracking as a result of water entering the equipment
- b) potential damage as a result of residual salts from sea water systems
- c) high voltage installations
- d) personnel protection against electric shock.

Figure 1



## 8 Low pressure carbon dioxide systems

### 8.1 Vessels and associated devices

#### 8.1.1

- The rated amount of liquid carbon dioxide is to be stored in vessels under the working pressure in the range of 1,8 MPa to 2,2 MPa. The normal liquid charge in the container is to be limited to provide sufficient vapour space to allow for expansion of the liquid under the maximum storage temperatures that can be obtained corresponding to the setting of the pressure relief valves, but is not to exceed 95% of the volumetric capacity of the container.
- The vessels are to be designed, constructed and tested in accordance with the requirements of Ch 1, Sec 3. For this purpose the design pressure is to be taken not less than the relief valve setting. In addition, for each vessel, provision is to be made for:
  - a pressure gauge
  - a high pressure alarm: not more than the setting of the relief valve
  - a low pressure alarm: not less than 1,8 MPa
  - branch pipes with stop valves for filling the vessel
  - discharge pipes
  - a liquid CO<sub>2</sub> level indicator, fitted on the vessel
  - two safety relief valves arranged so that either valve can be shut off while the other is connected to the vessel. The setting of the relief valves is to be no less than 1,1 times the working pressure. The capacity of each valve is to be such that the vapours generated due to fire can be discharged with a pressure rise not more than 20% above the setting pressure. The dis-

charge from the safety valves is to be led to the open.

- The vessels and outgoing pipes permanently filled with carbon dioxide are to have thermal insulation preventing the operation of the safety valve for 24 hours after de-energising the plant, at ambient temperature of 45°C and an initial pressure equal to the starting pressure of the refrigeration unit. The insulating materials and their liners are to be to the satisfaction of the Society, bearing in mind, in particular, their fire resistance and mechanical properties, as well as protection against penetration of water vapours.

### 8.2 Refrigerating plant

#### 8.2.1

- The vessels are to be serviced by two automated completely independent refrigerating units solely intended for this purpose, each comprising a compressor and the associated prime mover, evaporator and condenser.
- The refrigerating plant is to comply with the relevant requirements of Ch 1, Sec 13. The refrigerating capacity and the automatic control of each unit are to be such as to maintain the required temperature under conditions of continuous operation for 24 hours at a sea temperature up to 32°C and ambient air temperature up to 45°C.
- In the event of failure of either one of the refrigerating units the other is to be actuated automatically. Provision is to be made for local manual control of the refrigerating plant.
- Each electric refrigerating unit is to be supplied from the main switchboard busbars by a separate feeder.
- Cooling water supply to the refrigerating plant (where required) is to be provided from at least two circulating pumps, one of which being used as a standby. The standby pump may be a pump used for other services so long as its use for cooling would not interfere with any



other essential service of the ship. Cooling water is to be taken from not less than two sea connections, preferably one port and one starboard.

### 8.3 Pipes, valves and associated fittings

#### 8.3.1

- a) The pipes, valves and fittings are to be in accordance with the requirements of Ch 1, Sec 10 for a design pressure not less than the design pressure of the CO<sub>2</sub> vessels.
- b) Safety relief devices are to be provided in each section of pipe that may be isolated by block valves and in which there could be a build-up of pressure in excess of the design pressure of any of the components.
- c) The piping system is to be designed in such a way that the CO<sub>2</sub> flows through in liquid phase up to the discharge nozzles. For this purpose, the pressure at the nozzles is to be not less than 1 MPa.

### 8.4 Control of fire-extinguishing system operation

**8.4.1** The machinery alarm system is to be equipped with audible and visual alarms activated when:

- a) the pressure in the vessels reaches the low and the high values according to [8.1.1] b)
- b) any one of the refrigerating units fails to operate
- c) the lowest permissible level of the liquid in the vessels is reached.

### 8.5 Release control

**8.5.1** The release of CO<sub>2</sub> is to be initiated manually.

If a device is provided which automatically regulates the discharge of the rated quantity of carbon dioxide into the protected spaces, it is also to be possible to regulate the discharge manually.

If the system serves more than one space, means for control of discharge quantities of CO<sub>2</sub> are to be provided, e.g. automatic timer or accurate level indicators located at the control positions or positions.

### 8.6 Testing

#### 8.6.1

- a) Tests are to be witnessed by the Society.
- b) The pipes, valves and fittings and assembled system are to be tested to the satisfaction of the Society.
- c) The pipes from the vessels to the release valves on the distribution manifold are to be subjected to a pressure

test to not less than 1,5 times the set pressure of the safety relief valves.

- d) The pipes from the release valves on the distribution manifold to the nozzles are to be tested for tightness and free flow of CO<sub>2</sub>, after having been assembled on board.
- e) After having been fitted on board, the refrigerating plant is to be checked for its proper operation.
- f) If deemed necessary by the Society, a discharge test may be required to check the fulfilment of the requirements of [8.3.1] c).

## 9 Fire safety systems: General requirements and application for inert gas systems

### 9.1 General requirements

**9.1.1** The inert gas system is to be capable of inerting, purging and gas-freeing empty cargo tanks and maintaining the atmosphere in cargo tanks with the required oxygen content.

**9.1.2** The inert gas system referred to in [9.2.1] is to be designed, constructed and tested in accordance with the requirements of [10], [11] and [12]. Unless otherwise stated, for materials and design criteria of piping and relevant accessories reference is to be made to Ch 1, Sec 10.

**9.1.3** Tankers fitted with a fixed inert gas system are to be provided with a closed ullage system.

### 9.2 Application

**9.2.1** For tankers of 20,000 tonnes deadweight and upwards, the protection of the cargo tanks is to be achieved by a fixed inert gas system in accordance with the requirements of [9], [10] and [12], except that, in lieu of the above, the Society, after having given consideration to the ship's arrangement and equipment, may accept other fixed installations if they afford protection equivalent to the above.

The requirements for alternative installations are given in [9.1].

**9.2.2** Tankers operating with a cargo tank cleaning procedure using crude oil washing are to be fitted with an inert gas system complying with the requirements of [10] and with fixed tank washing machines.

**9.2.3** Tankers required to be fitted with inert gas systems are to comply with the following provisions:

- a) double hull spaces are to be fitted with suitable connections for the supply of inert gas
- b) where hull spaces are connected to a permanently fitted inert gas distribution system, means are to be provided to prevent hydrocarbon gases from the cargo tanks entering the double hull space through the system and
- c) where such spaces are not permanently connected to an inert gas distribution system, appropriate means are to be provided to allow connection to the inert gas main.

**9.2.4** The requirements for inert gas systems given in [10] and [11] need not be applied to:

- a) gas carriers when carrying crude oil and petroleum products having a flashpoint not exceeding 60°C (closed cup test), provided that they comply with the requirements for inert gas systems on chemical tankers in [11], or
- b) gas carriers when carrying flammable cargoes other than crude oil or petroleum products such as cargoes listed in Chapter 17 and 18 of the International Code for the Construction and Equipment of Ships Carrying Dangerous Chemicals in Bulk, provided that the capacity of tanks used for their carriage does not exceed 3000 m<sup>3</sup>, the individual nozzle capacities of tank washing machines do not exceed 17,5 m<sup>3</sup>/h and the total combined throughput from the number of machines in use in a cargo tank at any one time does not exceed 110 m<sup>3</sup>/h.

### 9.3 Requirements for equivalent systems

#### 9.3.1

When an installation equivalent to a fixed inert gas system is installed, it is to:

- a) be capable of preventing dangerous accumulations of explosive mixtures in intact cargo tanks during normal service throughout the ballast voyage and necessary in-tank operations, and
- b) be so designed as to minimise the risk of ignition from the generation of static electricity by the system itself.

## 10 Fire safety systems: Inert gas systems on oil tankers

### 10.1 Contents

**10.1.1** This item [10] gives the specification of inert gas systems in cargo oil tanks and double hull spaces as required by this Chapter.

### 10.2 Engineering specifications

#### 10.2.1 General

- a) Throughout this item [10] the term "cargo tank" includes also "slop tanks".
- b) The inert gas system referred to in this Chapter is to be designed, constructed and tested to the satisfaction of the Society. It is to be so designed and operated as to render and maintain the atmosphere of the cargo tanks non-flammable at all times, except when such tanks are required to be gas-free. In the event that the inert gas system is unable to meet the operational requirement set out above and it has been assessed that it is impractical to effect a repair, then cargo discharge, deballasting and necessary tank cleaning are only to be resumed

when the "emergency conditions" laid down in the Society Rules for Inert Gas Systems are complied with.

- c) The system is to be capable of:
  - 1) inerting empty cargo tanks by reducing the oxygen content of the atmosphere in each tank to a level at which combustion cannot be supported
  - 2) maintaining the atmosphere in any part of any cargo tank with an oxygen content not exceeding 8 per cent by volume and at a positive pressure at all times in port and at sea except when it is necessary for such a tank to be gas-free
  - 3) eliminating the need for air to enter a tank during normal operations except when it is necessary for such a tank to be gas-free
  - 4) purging empty cargo tanks of hydrocarbon gas, so that subsequent gas-freeing operations will at no time create a flammable atmosphere within the tank.

#### 10.2.2 Component requirements

- a) Supply of inert gas
  - 1) The inert gas supply may be treated flue gas from main or auxiliary boilers. The Society may accept systems using flue gases from one or more separate gas generators or other sources or any combination thereof, provided that an equivalent standard of safety is achieved. Such systems are, as far as practicable, to comply with the requirements of this Article. Systems using stored carbon dioxide are not permitted unless the Society is satisfied that the risk of ignition from generation of static electricity by the system itself is minimised.
  - 2) The system is to be capable of delivering inert gas to the cargo tanks at a rate of at least 125 per cent of the maximum rate of discharge capacity of the ship expressed as a volume.
  - 3) The system is to be capable of delivering inert gas with an oxygen content of not more than 5 per cent by volume in the inert gas supply main to the cargo tanks at any required rate of flow.
  - 4) Two fuel oil pumps are to be fitted to the inert gas generator. The Society may permit only one fuel oil pump on condition that sufficient spares for the fuel oil pump and its prime mover are carried on board to enable any failure of the fuel oil pump and its prime mover to be rectified by the ship's crew.
- b) Scrubbers
  - 1) A flue gas scrubber is to be fitted which will effectively cool the volume of gas specified in 2) and 3) of item a) above and remove solids and sulphur combustion products. The cooling water arrangements are to be such that an adequate supply of water will always be available without interfering with any essential services of the ship. Provision is

also to be made for an alternative supply of cooling water.

- 2) Filters or equivalent devices are to be fitted to minimise the amount of water carried over to the inert gas blowers.
- 3) The scrubber is to be located aft of all cargo tanks, cargo pump rooms and cofferdams separating these spaces from machinery spaces of category A.

c) Blowers

- 1) At least two blowers are to be fitted which together are to be capable of delivering to the cargo tanks at least the volume of gas required by 2) and 3 of item b) above. In the system with gas generator the Society may permit only one blower if that system is capable of delivering the total volume of gas required by 2) and 3 of item b) above to the protected cargo tanks, provided that sufficient spares for the blower and its prime mover are carried on board to enable any failure of the blower and its prime mover to be rectified by the ship's crew.
- 2) The inert gas system is to be so designed that the maximum pressure which it can exert on any cargo tank will not exceed the test pressure of any cargo tank. Suitable shut-off arrangements are to be provided on the suction and discharge connections of each blower. Arrangements are to be provided to enable the functioning of the inert gas plant to be stabilised before commencing cargo discharge. If the blowers are to be used for gas-freeing, their air inlets are to be provided with blanking arrangements.
- 3) The blowers are to be located aft of all cargo tanks, cargo pump rooms and cofferdams separating these spaces from machinery spaces of category A.

d) Water seal

- 1) The water seal referred to in the first bullet of item 4 of [10.2.3] is to be capable of being supplied by two separate pumps, each of which is to be capable of maintaining an adequate supply at all times.
- 2) The arrangements of the seal and its associated fittings are to be such that they will prevent backflow of hydrocarbon vapours and will ensure the proper functioning of the seal under operating conditions.
- 3) Provision is to be made to ensure that the water seal is protected against freezing, in such a way that the integrity of seal is not impaired by overheating.
- 4) A water loop or other approved arrangement is also to be fitted to each associated water supply and drain pipe and each venting or pressure sensing pipe leading to gas safe spaces. Means are to be provided to prevent such loops from being emptied by vacuum.
- 5) The deck water seal and loop arrangements are to be capable of preventing return of hydrocarbon vapours at a pressure equal to the test pressure of the cargo tanks.
- 6) In respect of the low water level in the water seal as per item c)1) of [10.2.4], the Society is to be satisfied

as to the maintenance of an adequate reserve of water at all times and the integrity of the arrangements to permit the automatic formation of the water seal when the gas flow ceases. The audible and visual alarm on the low level of water in the water seal is to operate when the inert gas is not being supplied.

**10.2.3 Installation requirements**

a) Safety measures in the system

1) Flue gas isolating valves

Flue gas isolating valves are to be fitted in the inert gas supply mains between the boiler uptakes and the flue gas scrubber. These valves are to be provided with indicators to show whether they are open or shut, and precautions are to be taken to maintain them gas-tight and keep the seatings clear of soot. Arrangements are to be made to ensure that boiler soot blowers cannot be operated when the corresponding flue gas valve is open.

2) Prevention of flue gas leakage

Special consideration is to be given to the design and location of the scrubber and blowers with relevant piping and fittings in order to prevent flue gas leakages into enclosed spaces.

To permit safe maintenance, an additional water seal or other effective means of preventing flue gas leakage is to be fitted between the flue gas isolating valves and scrubber, or incorporated in the gas entry to the scrubber.

3) Gas regulation valves

A gas regulating valve is to be fitted in the inert gas supply main. This valve is to be automatically controlled to close as required in the next item 5. It is also to be capable of automatically regulating the flow of inert gas to the cargo tanks unless means are provided to automatically control the speed of the inert gas blowers required in item c) of [10.2.2].

The valve referred to in the preceding item is to be located at the forward bulkhead of the forward most gas-safe space through which the inert gas supply main passes.

Note 1: A gas-safe space is a space in which the entry of hydrocarbon gases would produce hazards with regard to flammability or toxicity.

4) Non-return devices of flue gas

At least two non-return devices, one of which is to be a water seal, are to be fitted in the inert gas supply main, in order to prevent the return of hydrocarbon vapour to the machinery space uptakes or to any gas-safe spaces under all normal conditions of trim, list and motion of the ship. They are to be located between the automatic valve required by item 3 above and the aftermost connection to any cargo tank or cargo pipeline.

The devices referred to in the preceding item are to be located in the cargo area on deck.

The second device is to be a non-return valve or equivalent capable of preventing the return of vapours or liquids and fitted forward of the deck

water seal required in the first bullet of this item 4. It is to be provided with positive means of closure. As an alternative to positive means of closure, an additional valve having such means of closure may be provided forward of the non-return valve to isolate the deck water seal from the inert gas main to the cargo tanks.

As an additional safeguard against the possible leakage of hydrocarbon liquids or vapours back from the deck main, means are to be provided to permit this section of the line between the valve having positive means of closure referred to in the previous item and the valve referred to in item 3 to be vented in a safe manner when the first of these valves is closed.

5) Automatic shutdown

Automatic shutdown of the inert gas blowers and gas regulating valve is to be arranged on predetermined limits being reached in respect of the first three items of c) 1) of [10.2.4].

Automatic shutdown of the gas regulating valve is to be arranged in respect of the fourth item of c) 1) of [10.2.4].

6) Oxygen rich gas

In respect of the fifth item of c) 1) of [10.2.4], when the oxygen content of the inert gas exceeds 8 per cent by volume, immediate action is to be taken to improve the gas quality. Unless the quality of the gas improves, all cargo tank operations are to be suspended so as to avoid air being drawn into the tanks and the isolation valve referred to in the third item of 4 above is to be closed.

b) Inert gas lines

- 1) The inert gas main may be divided into two or more branches forward of the non-return devices required by item d) of [10.2.2].
- 2) The inert gas supply mains are to be fitted with branch piping leading to each cargo tank. Branch piping for inert gas is to be fitted with either stop valves or equivalent means of control for isolating each tank. Where stop valves are fitted, they are to be provided with locking arrangements which are to be under the control of a responsible ship's officer. The control system operated is to provide positive indication of the operational status of such valves.
- 3) Means are to be provided to protect cargo tanks against the effect of overpressure or vacuum caused by thermal variations when the cargo tanks are isolated from the inert gas mains.
- 4) Piping systems are to be so designed as to prevent the accumulation of cargo or water in the pipelines under all normal conditions.
- 5) Arrangements are to be provided to enable the inert gas main to be connected to an external supply of inert gas. The arrangements are to consist of a 250 mm nominal pipe size bolted flange, isolated from the inert gas main by a valve and located forward of the non-return valve referred to in the third bullet of previous item a) 4). The design of the flange is to conform to the appropriate class in the standards

adopted for the design of other external connections in the ship's cargo piping system.

- 6) If a connection is fitted between the inert gas supply main and the cargo piping system, arrangements are to be made to ensure effective isolation having regard to the large pressure difference which may exist between the systems. This is to consist of two shut-off valves with an arrangement to vent the space between the valves in a safe manner, or an arrangement consisting of a spool-piece with associated blanks.
- 7) The valve separating the inert gas supply main from the cargo main and which is on the cargo main side is to be a non-return valve with a positive means of closure.

#### 10.2.4 Operation and control requirements

a) Indication devices

Means are to be provided for continuously indicating the temperature and pressure of the inert gas at the discharge side of the gas blowers whenever the latter are operating.

b) Indicating and recording devices

- 1) Instrumentation is to be fitted for continuously indicating and permanently recording, when the inert gas is being supplied:
  - the pressure of the inert gas supply mains forward of the non-return devices required by the first bullet of item a) 4) of [10.2.3], and
  - the oxygen content of the inert gas in the inert gas supply mains on the discharge side of the gas blowers.
- 2) The devices referred to in 1) above are to be placed in the cargo control room where provided. But where no cargo control room is provided, they are to be placed in a position easily accessible to the officer in charge of cargo operations.
- 3) In addition, meters are to be fitted:
  - on the navigating bridge to indicate at all times the pressure referred to in the first item of b) 1) above and the pressure in the slop tanks of combination carriers, whenever those tanks are isolated from the inert gas supply main, and
  - in the machinery control room or in the machinery space to indicate the oxygen content referred to in the second item of b) 1) above.
- 4) Portable instruments for measuring oxygen and flammable vapour concentration are to be provided. In addition, suitable arrangement is to be made on each cargo tank such that the condition of the tank atmosphere can be determined using these portable instruments.
- 5) Suitable means are to be provided for the zero and span calibration of both fixed and portable gas concentration measurement instruments, referred to in the preceding items 1) to 4).

c) Audible and visual alarms

1) For inert gas systems of both the flue gas type and the inert gas generator type, audible and visual alarms are to be provided to indicate:

- low water pressure or low water flow rate to the flue gas scrubber as referred to in item b) 1) of [10.2.2]
- 1 high water level in the flue gas scrubber as referred to in item b) 1) of [10.2.2]
- 2 high gas temperature as referred to in item a) of [10.2.4]
- 3 failure of the inert gas blowers referred to in item c) of [10.2.2]
- oxygen content in excess of 8 per cent by volume as referred to in the second item of b)1) of [10.2.4]
- failure of the power supply to the automatic control system for the gas regulating valve and to the indicating devices as referred to in item a)3) of [10.2.3] and in item b)1) of [10.2.4]
- low water level in the water seal as referred to in the first item of a)4) of [10.2.3]
- gas pressure less than 981 Pa (100 mm water gauge) as referred to in the first item of b)1) of [10.2.4].
- high gas pressure as referred to in the first item of b)1) of this [10.2.4].

2) For inert gas systems of the inert gas generator type, additional audible and visual alarms are to be provided to indicate:

- insufficient fuel oil supply
- failure of the power supply to the generator
- failure of the power supply to the automatic control systems for the generator.

3) The alarms required in the fifth, sixth and eighth items of c)1) above are to be fitted in the machinery space and cargo control room, where provided, but in each case in such a position that they are immediately received by responsible members of the crew.

4) An audible alarm system independent of that required in the eighth item of c)1) above or automatic shutdown of cargo pumps is to be provided to operate on predetermined limits of low pressure in the inert gas mains being reached.

d) Instruction manual

Detailed instruction manuals are to be provided on board, covering the operations, safety and maintenance requirements and occupational health hazards relevant to the inert gas system and its application to the cargo tank system (see Note 1). The manuals are to include guidance on procedures to be followed in the event of a fault or failure of the inert gas system.

Note 1: Refer to the Revised guidelines for inert gas systems (IMO MSC/Circ.353), as amended by IMO MSC/Circ.387.

## 10.3 Additional requirements

### 10.3.1 General

In addition to the preceding provisions of this item [10], the following requirements apply:

- a) When two blowers are provided, the total required capacity of the inert gas system is preferably to be divided equally between them, and in no case is one blower to have a capacity less than 1/3 of the total capacity required.
- b) In particular those parts of scrubbers, blowers, non-return devices, scrubber effluent and other drain pipes which may be subjected to corrosive action of the gases and/or liquids are to be either constructed of corrosion-resistant material or lined with rubber, glass fibre epoxy resin or other equivalent coating material.
- c) A compartment in which any oil fired inert gas generator is situated is to be treated as a machinery space of category A with respect to fire protection.
- d) Arrangements are to be made to vent the inert gas from oil fired inert gas generators to the atmosphere when the inert gas produced is off-specification, e.g. during start-up or in the event of equipment failure.
- e) Automatic shutdown of the fuel oil supply to inert gas generators is to be arranged on predetermined limits being reached in respect of low water pressure or low water flow rate to the cooling and scrubbing arrangement and in respect of high gas temperature.
- f) Automatic shutdown of the gas regulating valve, referred to [10.2.3] a)3), is to be arranged in respect of failure of the power supply to the oil fired inert gas generators.

### 10.3.2 Nitrogen generator systems

- a) The requirements of this item are specific only to the gas generator system and apply where inert gas is produced by separating air into its component gases by passing compressed air through a bundle of hollow fibres, semi-permeable membranes or adsorber materials.
- b) Where such systems are provided in place of the boiler flue gas or oil fired inert gas generators, the previous requirements for inert gas systems applicable to piping arrangements, alarms and instrumentation downstream of the generator are to be complied with, as far as applicable.
- c) A nitrogen generator consists of a feed air treatment system and any number of membrane or adsorber modules in parallel necessary to meet the required capacity, which is to be at least 125% of the maximum discharge capacity of the ship expressed as a volume.
- d) The air compressor and the nitrogen generator may be installed in the engine room or in a separate compartment. A separate compartment is to be treated as one of the "Other machinery spaces" with respect to fire protection.
- e) Where a separate compartment is provided, it is to be positioned outside the cargo area and is to be fitted with an independent mechanical extraction ventilation system providing 6 air changes per hour. A low oxygen

alarm is also to be fitted. The compartment is to have no direct access to accommodation spaces, service spaces and control stations.

- f) The nitrogen generator is to be capable of delivering high purity nitrogen with O<sup>2</sup> content not exceeding 5% by volume. The system is to be fitted with automatic means to discharge off-specification gas to the atmosphere during start-up and abnormal operation.
- g) The system is to be provided with two air compressors. The total required capacity of the system is preferably to be divided equally between the two compressors, and in no case is one compressor to have a capacity less than 1/3 of the total capacity required. Only one air compressor may be accepted provided that sufficient spares for the air compressor and its prime mover are carried on board to enable their failure to be rectified by the ship's crew.
- h) A feed air treatment system is to be fitted to remove free water, particles and traces of oil from the compressed air, and to preserve the specification temperature.
- i) Where fitted, a nitrogen receiver/buffer tank may be installed in a dedicated compartment or in the separate compartment containing the air compressor and the generator or may be located in the cargo area. Where the nitrogen receiver/buffer tank is installed in an enclosed space, the access is to be arranged only from the open deck and the access door is to open outwards. Permanent ventilation and alarm are to be fitted as required by e) above.
- j) The oxygen-enriched air from the nitrogen generator and the nitrogen-product enriched gas from the protective devices of the nitrogen receiver are to be discharged to a safe location on the open deck.
- k) In order to permit maintenance, means of isolation are to be fitted between the generator and the receiver.
- l) At least two non-return devices are to be fitted in the inert gas supply main, one of which is to be of the double block and bleed arrangement (refer to item a) of [11.2.3]). The second non-return device is to be equipped with positive means of closure.
- m) Instrumentation is to be provided for continuously indicating the temperature and pressure of air:
  - 1) at the discharge side of the compressor,
  - 2) at the entrance side of the nitrogen generator.
- n) Instrumentation is to be fitted for continuously indicating and permanently recording the oxygen content of

the inert gas downstream of the nitrogen generator when inert gas is being supplied.

- o) The instrumentation referred to in the preceding item n) is to be placed in the cargo control room, where provided. But where no cargo control room is provided, it is to be placed in a position easily accessible to the officer in charge of cargo operations.
- p) Audible and visual alarms are to be provided to indicate:
  - 1) low feed-air pressure from compressor as referred to in m)1) above
  - 2) high air temperature as referred to in m)1) above
  - 3) high condensate level at automatic drain of water separator as referred to in item h) above
  - 4) failure of electric heater, if fitted
  - 5) oxygen content in excess of that required in item f) above
  - 6) failure of power supply to the instrumentation as referred to in item n) above.
- q) Automatic shutdown of the system is to be arranged upon alarm conditions as required by items p) 1) to 5) above.
- r) The alarms required by items p) 1) to 6) above are to be fitted in the machinery space and cargo control room, where provided, but in each case in such a position that they are immediately received by responsible members of the crew.

### 10.3.3 Nitrogen/inert gas systems fitted for purposes other than inerting required by [9.2.1]

For nitrogen/inert gas systems fitted on oil tankers of less than 20,000 tonnes deadweight for purposes other than inerting required by [9.2.1], the following items a) and b) apply:

- a) The requirements of items d) to r) of [10.3.2] apply, except item g).
- b) Where the connections to the cargo tanks, to the hold spaces or to cargo piping are not permanent, the non-return devices required by item l) of [10.3.2] may be replaced by two non-return valves.

## SECTION 2

## EMERGENCY SHUTDOWN SYSTEMS

### 1 General requirements and definitions

#### 1.1

**1.1.1** The safest conditions for the systems on board are to be defined.

**1.1.2** All equipment and systems are to be equipped with indicating or monitoring instruments and devices necessary for safe operation.

**1.1.3** Emergency shutdown systems are to be provided against hazardous events.

Production systems are to be equipped with shutdown systems.

Systems that could endanger the safety if they fail or operate outside pre-set conditions are to be provided with automatic shutdown.

**1.1.4** An emergency shutdown system (ESD) includes.:

- a) manual input devices (push buttons)
- b) interfaces towards other safety systems, e.g.:
  - fire detection system
  - gas detection system
  - alarm and communication systems
  - process shutdown system
  - fire-fighting systems
  - ventilation systems
- c) a central control unit receiving and evaluating signals from the manual input devices and the interfaced systems, and creating output signals to devices that are to be shut down or activated. The ESD central control unit is to include a device providing visual indication of initiated inputs and activated outputs and a local audible alarm
- d) output actuators, e.g. relays, valves and dampers, including status indicators
- e) signal transfer lines between the ESD central control unit and all input devices, interfaced systems and output actuators
- f) power supply.

**1.1.5** In the context of these requirements under [4], 'circuit' is defined as any signal transfer facility, e.g. electrical, pneumatic, hydraulic, optical or acoustic.

**1.1.6** A normally energised circuit is a circuit where energy is present, e.g. an electrical current or pneumatic or hydraulic pressure, when the circuit is not activated by the shutdown system.

**1.1.7** A normally de-energised circuit is a circuit where energy is not present when the circuit is not activated by the shutdown system.

### 2 Basic design principles

#### 2.1

**2.1.1** All shutdowns are to be executed in a predetermined logical manner. The shutdown system is normally to be designed in a hierarchical manner where higher level shutdowns automatically initiate lower level shutdowns.

**2.1.2** Definition of the shutdown logic and required response times are to be based on consideration of dynamic effects and interactions between systems.

**2.1.3** Shutdown is not to result in adverse cascade effects, which depends on activation of other protection devices to maintain a plant in a safe condition.

**2.1.4** The shutdown system is to be designed to ensure that any ongoing operations can be terminated safely when a shutdown is activated.

**2.1.5** Inter-trips between process systems are to be initiated as a result of any initial event which could cause undesirable cascade effects in other parts of the plant before operator intervention can be realistically expected.

**2.1.6** Emergency shutdown is to initiate a process shutdown.

**2.1.7** The shutdown system is to be completely independent of control systems used for normal operation. See also Pt. C Ch. 3 Sec.2 [1.1.4].

**2.1.8** The shutdown system is to be capable to monitor critical parameters and bring the system to a safe condition if specified conditions are exceeded. See also Pt. C Ch. 3 Sec.2 [7].

**2.1.9** The system is to be designed so that the risk of unintentional shutdown caused by malfunction or inadvertent operation is minimised.

**2.1.10** The system is to be designed to allow testing without interrupting other systems on board.

**2.1.11** The central control unit is to be located in a non-hazardous and continuously manned area.

**2.1.12** The system is to be powered from a monitored Uninterruptible Power Supply (UPS) capable of at least 30 minutes continuous operation on loss of its electrical power supply systems. The UPS is to be powered from both the main and the emergency power system.

### 3 Design and functional requirements

#### 3.1

**3.1.1** Upon failure of the shutdown system, all connected systems are to default to the safest condition [4.1.1] for the unit or installation.

**3.1.2** Failures to be considered for the shutdown system are to include broken connections and short-circuits on input and output circuits, loss of power supply and, if relevant, loss of communication with other systems.

**3.1.3** For a shutdown system with only normally energized outputs, all inputs are to be normally energized.

**3.1.4** For a shutdown system with one or more normally de-energized outputs, all inputs able to activate a normally de-energized output are to be normally de-energized. All normally de-energized input and output circuits are to be monitored for broken connection and short-circuit.

**3.1.5** Shutdown is not to require unrealistically quick or complex intervention by the operator.

**3.1.6** Shutdowns on a hierarchical level are automatically to include shutdowns on lower levels.

**3.1.7** Shutdown is to initiate alarm at the control station. The initiating device and operating status of devices affected by the shutdown action are to be indicated at the control station (e.g. valve position, unit tripped, etc.).

**3.1.8** Personnel lifts, work platforms and other man-riding equipment are to be designed to enable safe escape after an emergency shutdown, e.g. by controlled descent to an access point on a lower level.

**3.1.9** Systems which are not permanently attended during operation, and which could endanger safety if they fail, are to be provided with automatic safety control, alert and alarm systems.

**3.1.10** Plants that are protected by automatic safety systems are to have pre-alarms to alert when operating parameters are exceeding normal levels.

**3.1.11** The shutdown commands are not to be automatically reset. Significant shutdown devices are to be reset locally following recognition and reset at the main control room, provided that shut down causes have been resolved.

### 4 Automatic and manual shutdown

#### 4.1

**4.1.1** Shutdowns are normally to be automatically initiated, however solely manually initiated actions may be pro-

vided where automatic action could be detrimental to safety.

**4.1.2** Systems designed for automatic shutdown are also to be designed to enable manual shutdown.

**4.1.3** Alarms for manual initiation are to be clear and are to be readily identifiable at a permanently manned control station.

**4.1.4** In all shutdown systems, it is to be possible to manually activate all levels of shutdown at the control station.

**4.1.5** Other manual shutdown buttons are to be located at strategic locations on the unit or installation.

### 5 Electrical equipment for use in an emergency

#### 5.1

**5.1.1** The following systems are to be operable after abandon unit shutdown:

- a) emergency lighting, for half an hour at:
  - every embarkation station on deck and over sides
  - in all service and accommodation alleyways, stairways and exits, personnel lift cars, and personnel lift trunks
  - in machinery spaces and main generating stations including their control positions
  - in all control stations and machinery control rooms
- b) general alarm
- c) public address
- d) battery supplied radio-communication.

**5.1.2** Electrical equipment left operational after abandon unit shutdown is to be suitable for operation in zone 2 areas with the exceptions given in [4.3.7].

**5.1.3** Electrical equipment located in non-hazardous areas affected by a gas release, which is left operational after gas detection is to be suitable for zone 2, with the exceptions given in [4.3.7].

**5.1.4** Safety critical, uncertified electrical equipment may be left operational after ESD or gas detection affecting its area of location, provided that:

- the ventilation to the room where the equipment is located is isolated
- gas detectors are installed in the room where the equipment is located
- facilities for manual shutdown of the equipment are available.



## SECTION 3

## GAS ALARM AND DETECTION SYSTEMS

### 1 General

#### 1.1

**1.1.1** In case the ship is expected to navigate in area where the presence of H<sub>2</sub>S or explosive gas may be possible, a H<sub>2</sub>S alarm and suitable gas detection system are to be provided.

#### 1.2 H<sub>2</sub>S alarm system

**1.2.1** A H<sub>2</sub>S detection and alarm system is to be fitted so as to adequately alert about the presence of H<sub>2</sub>S within the vessel.

Sensors are to be provided in all areas where persons may be present, typically:

- wheelhouse
- accommodations
- engine rooms
- airlocks
- cargo areas
- exposed decks.

Different or additional arrangements, based on risk analysis, may be envisaged.

The H<sub>2</sub>S detection system is to be submitted to the Society for approval.

#### 1.3 H<sub>2</sub>S survival kits

**1.3.1** Breathing apparatus sets are to be available for all crewmembers that may be present onboard.

Gas masks with active carbon filters are to be provided for the maximum number of persons that may be present onboard.

#### 1.4 Gas detection and alarm

**1.4.1** A fixed automatic gas detection and alarm system is to be provided to the satisfaction of the Society so arranged as to monitor continuously all enclosed areas of the unit in which an accumulation of flammable gas may be expected

to occur and capable of indicating at the main control stations and at the required emergency control stations, by acoustic and visual means, the presence and location of an accumulation. The system is to be so designed to allow testing without interrupting other systems on board.

The flammable gas detectors are to actuate the alarm at not more than 25% and at 60% of the lower explosive limit (LEL). At least two portable combustible gas detectors are to be provided for operating personnel to locate small.

#### 1.4.2 Gas analysing units of the sampling type

When the gas detection is performed by means of gas analysing units of the sampling type, the analysing units with non-explosion proof measuring equipment may be located in areas outside hazardous cargo areas, e.g. in cargo control room, navigation bridge or engine room when mounted on the forward bulkhead provided the following requirements are observed:

- a) Sampling lines shall not run through gas safe spaces, except where permitted under e).
- b) The gas sampling pipes shall be equipped with flame arresters. Sample gas is to be led to the atmosphere with outlets arranged in a safe location.
- c) Bulkhead penetrations of sample pipes between safe and dangerous areas shall be of approved type and have same fire integrity as the division penetrated. A manual isolating valve shall be fitted in each of the sampling lines at the bulkhead on the gas safe side.
- d) The gas detection equipment including sample piping, sample pumps, solenoids, analysing units etc. shall be located in a reasonably gas tight enclosure (e.g. a fully enclosed steel cabinet with a gasketed door) which is to be monitored by its own sampling point. At gas concentrations above 30% LFL inside the enclosure the entire gas analysing unit is to be automatically shut down
- e) Where the enclosure cannot be arranged directly on the bulkhead, sample pipes shall be of steel or other equivalent material and without detachable connections, except for the connection points for isolating valves at the bulkhead and analysing units, and are to be routed on their shortest ways.